

Robust Neural Networks: Explainability, Uncertainty, and Intervenability



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IEEE BigData 2023 Tutorial



Presented by: *Ghassan AlRegib, and Mohit Prabhushankar*
Georgia Institute of Technology

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Title: Robust Neural Networks: Explainability, Uncertainty, and Intervenability

Deep Learning

Expectation vs Reality

Expectation vs Reality of Deep Learning



Deep Learning

Expectation vs Reality

LATEST TRICKS

Rotating objects in an image confuses DNNs, probably because they are too different from the types of image used to train the network.

Stop



Dumb-bell

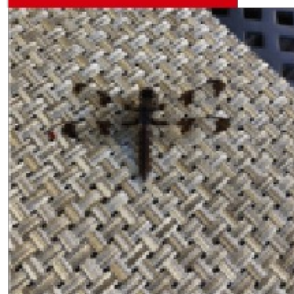


Racket

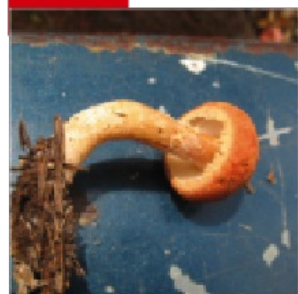


Even natural images can fool a DNN, because it might focus on the picture's colour, texture or background rather than picking out the salient features a human would recognize.

Manhole cover



Pretzel



©nature



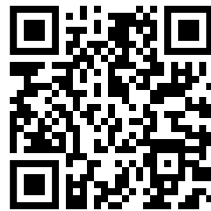
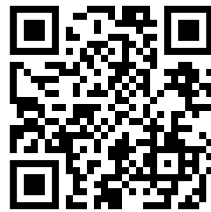
Deep Learning

Requirements and Challenges

Requirements: Deep Learning-enabled systems must predict correctly on novel data

Novel data sources:

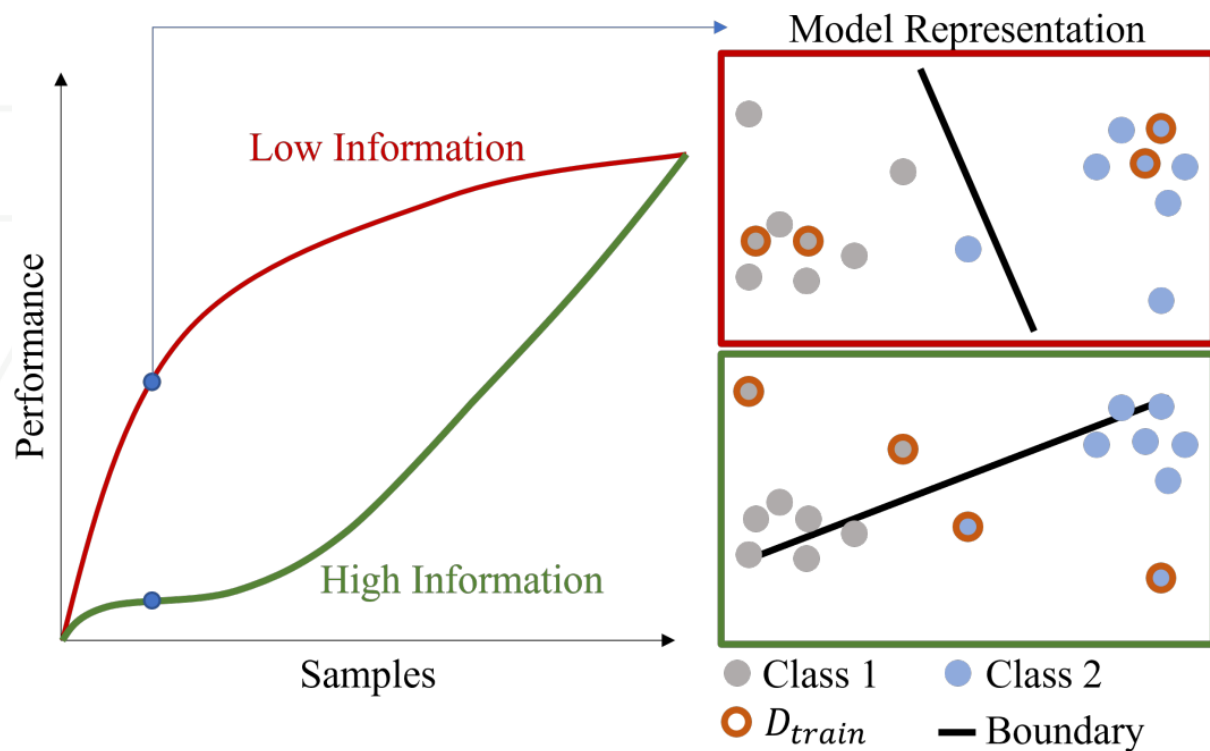
- Test distributions
- Anomalous data
- Out-Of-Distribution data
- Adversarial data
- Corrupted data
- Noisy data
- New classes
- ...



Deep Learning at Training

Overcoming Challenges at Training: Part 1

The most novel/aberrant samples should not be used in early training



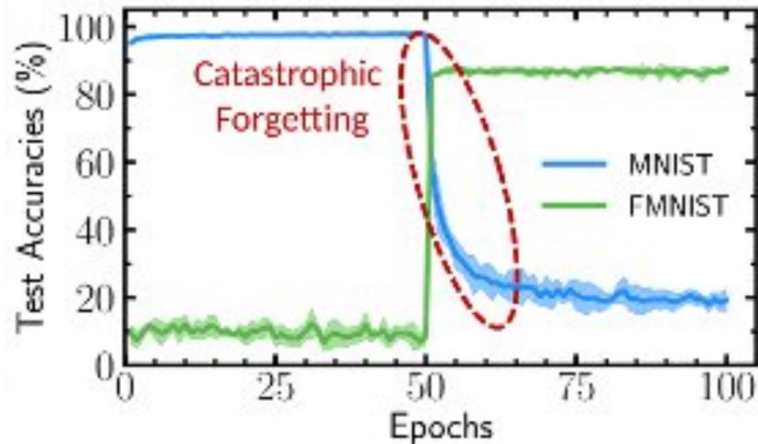
- The first instance of training must occur with less informative samples
- Ex: For autonomous vehicles, less informative means
 - Highway scenarios
 - Parking
 - No accidents
 - No aberrant events

Novel samples = Most Informative

Deep Learning at Training

Overcoming Challenges at Training: Part 2

Subsequent training must not focus only on novel data



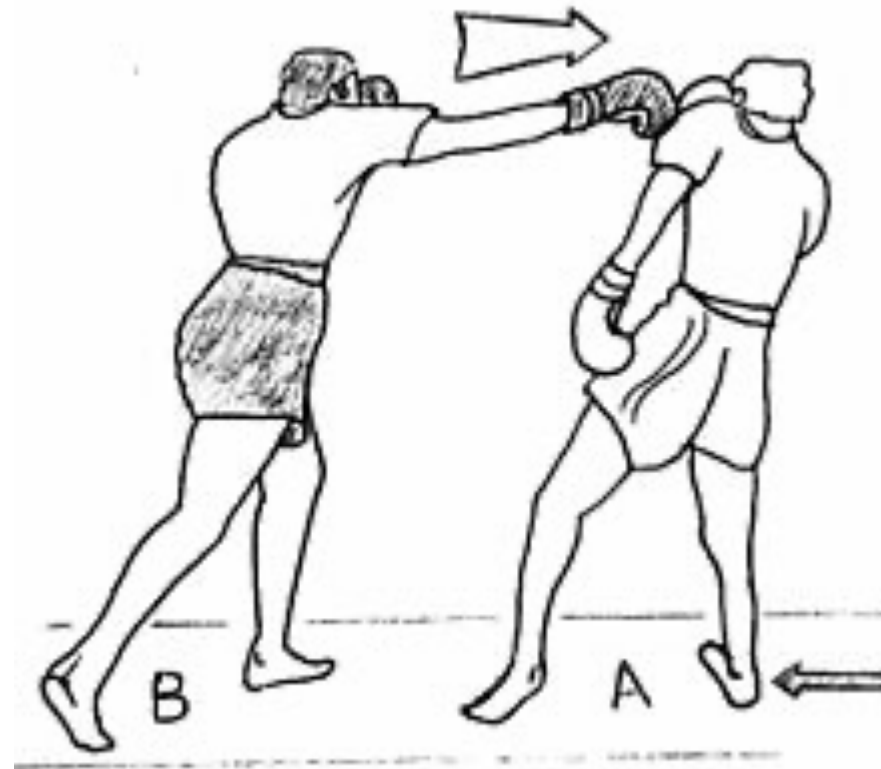
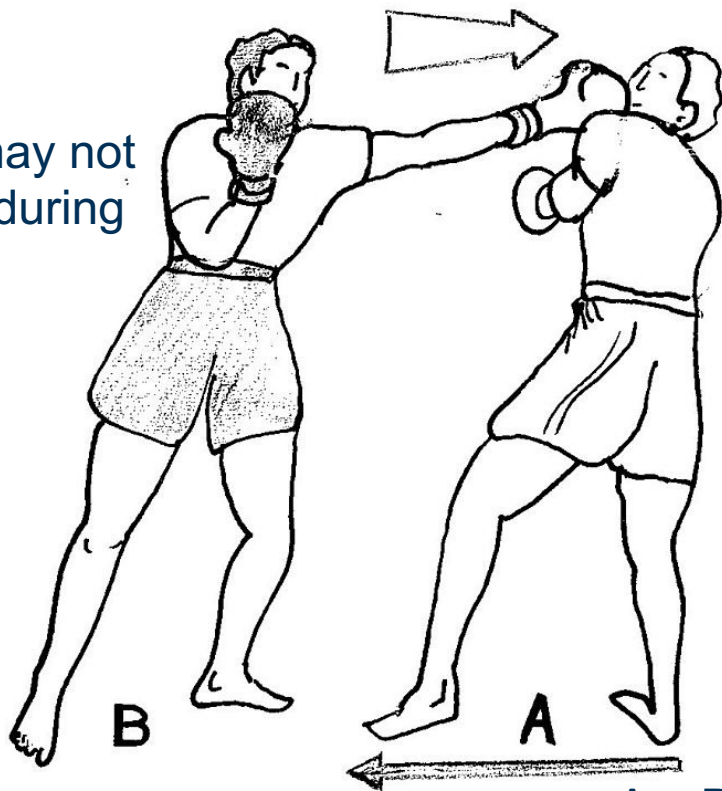
- The model performs well on the new scenarios, while forgetting the old scenarios
- A number of techniques exist to overcome this trend
- However, they affect the overall performance in large-scale settings
- It is not always clear **if and when** to incorporate novel scenarios in training

Deep Learning at Training

Overcoming Challenges at Training

Novel data packs a 1-2 punch!

Novel data may not be available during training



Even if available, novel data does not easily fit into either the earlier or later stages of training

A = Deep Neural Networks
B = Novel data

Deep Learning at Inference

Overcoming Challenges at Inference

We must handle novel data at Inference!!

Novel data sources:

- Test distributions
- Anomalous data
- Out-Of-Distribution data
- Adversarial data
- Corrupted data
- Noisy data
- New classes
- ...

Model Train



At Inference



Objective

Objective of the Tutorial

To discuss methodologies that promote robustness in neural networks at inference

- Part 1: Inference in Neural Networks
- Part 2: Explainability at Inference
- Part 3: Uncertainty at Inference
- Part 4: Intervenability at Inference
- Part 5: Conclusions and Future Directions

Robust Neural Networks

Part I: Inference in Neural Networks

Objective

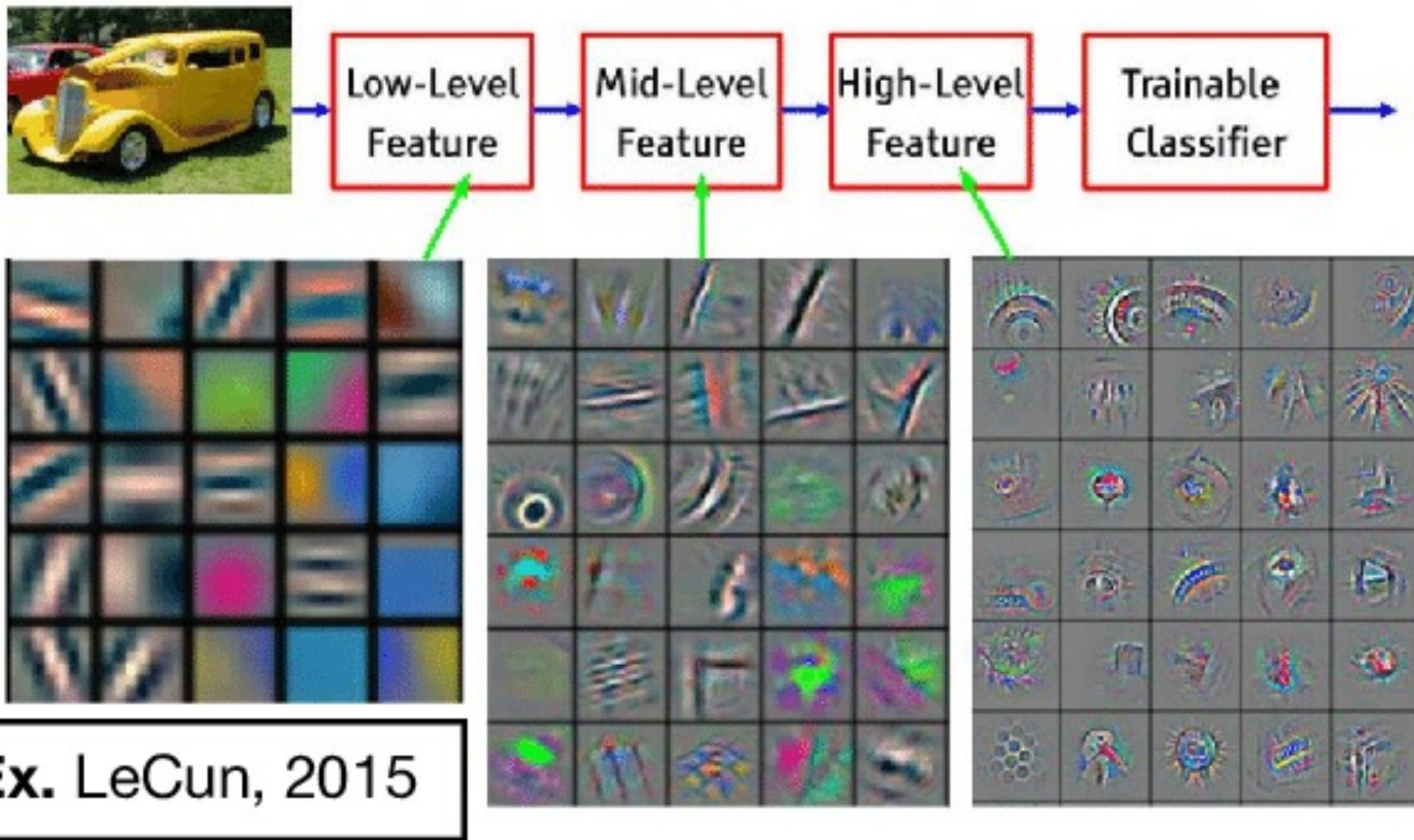
Objective of the Tutorial

To discuss methodologies that promote robustness in neural networks at inference

- **Part 1: Inference in Neural Networks**
 - Neural Network Basics
 - Robustness in Deep Learning
 - Information at Inference
 - Challenges at Inference
 - Gradients at Inference
- Part 2: Explainability at Inference
- Part 3: Uncertainty at Inference
- Part 4: Intervenability at Inference
- Part 5: Conclusions and Future Directions

Deep Learning

Overview



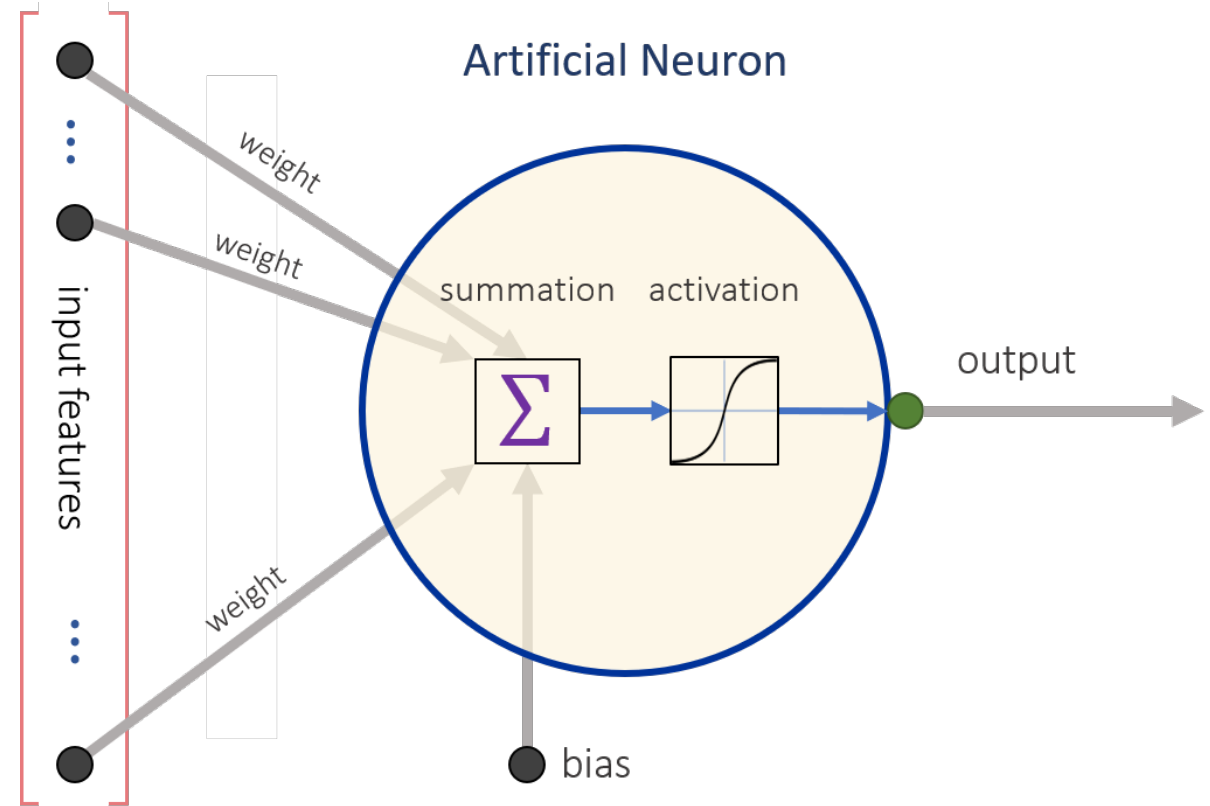
Deep Learning

Neurons

The underlying computation unit is the Neuron

Artificial neurons consist of:

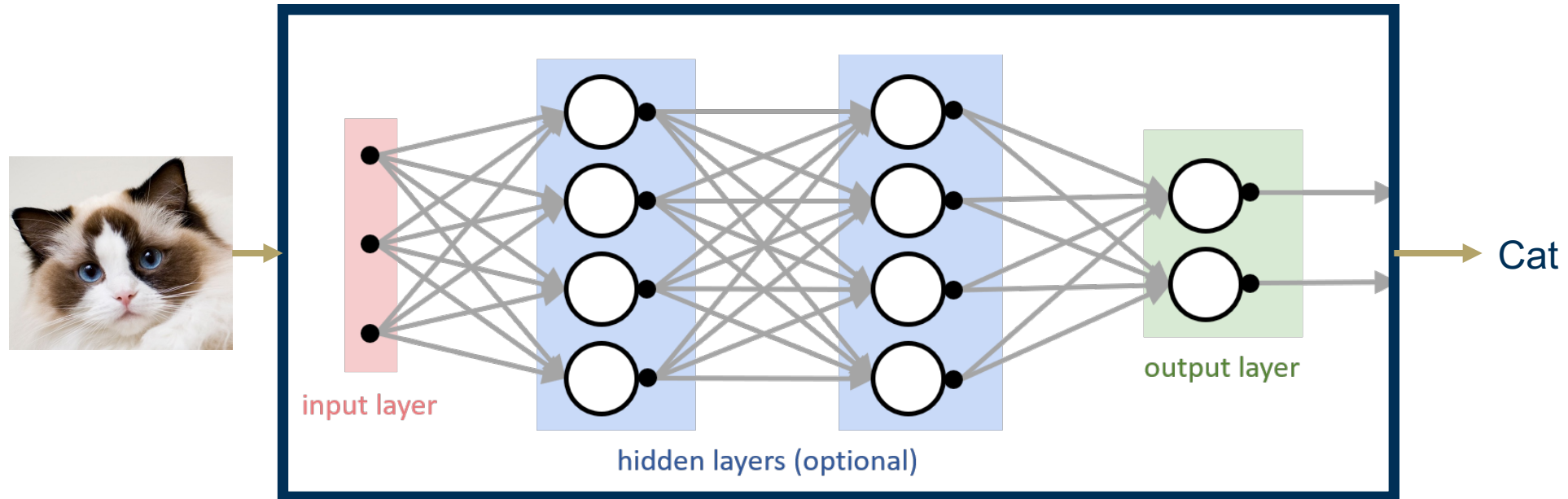
- A single output
- Multiple inputs
- Input weights
- A bias input
- An activation function



Deep Learning

Artificial Neural Networks

Neurons are stacked and densely connected to construct ANNs



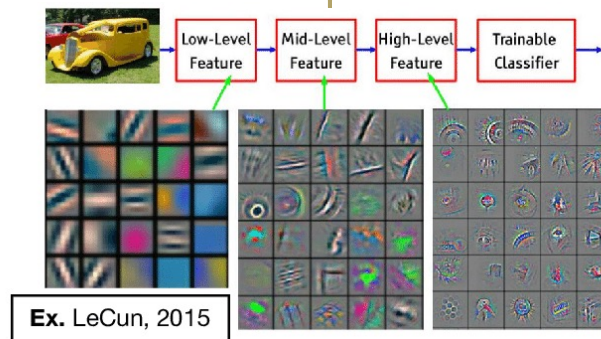
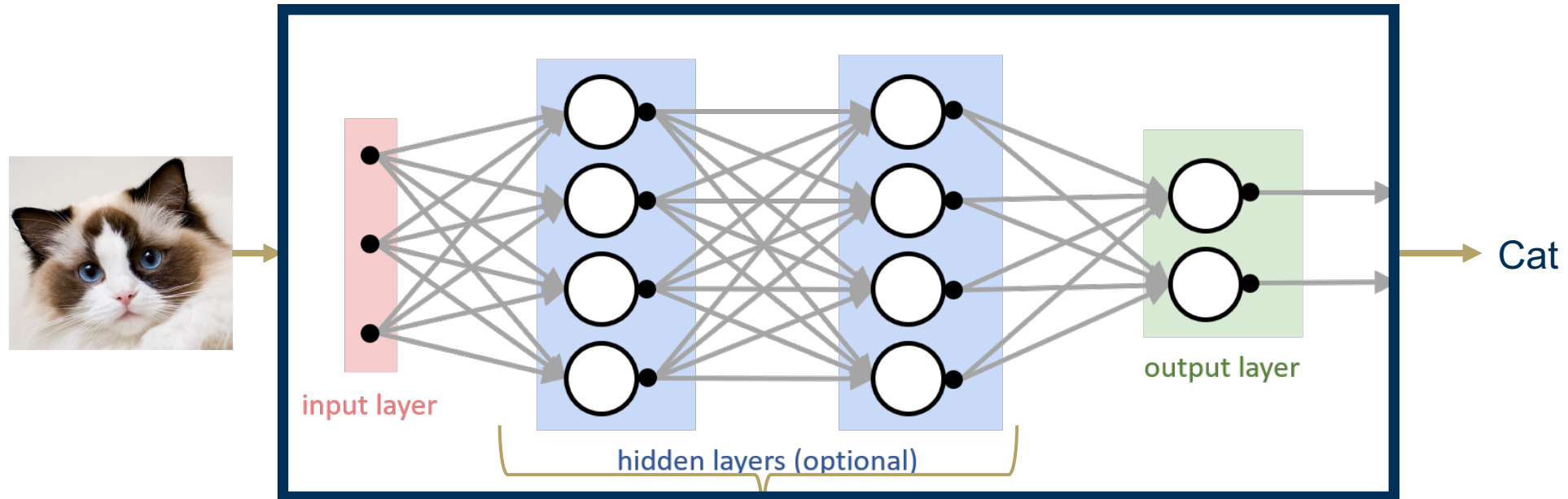
Typically, a neuron is part of a network organized in layers:

- An input layer (Layer 0)
- An output layer (Layer K)
- Zero or more hidden (middle) layers (Layers $1 \dots K - 1$)

Deep Learning

Convolutional Neural Networks

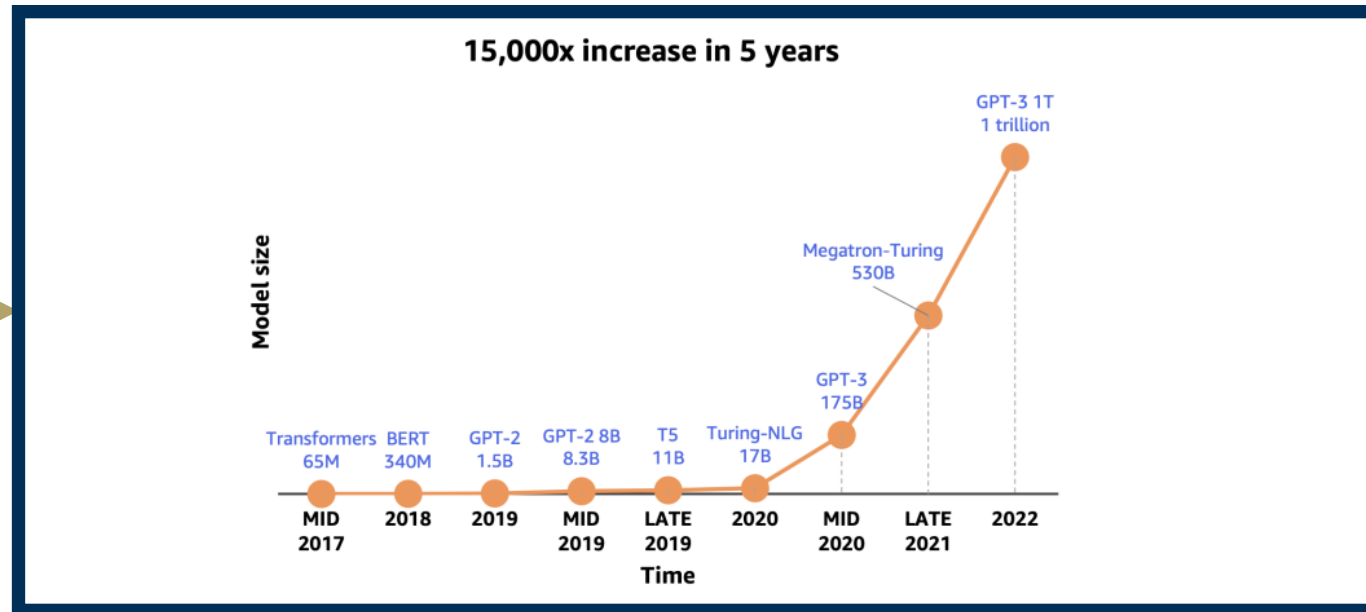
Stationary property of images allow for a small number of convolution kernels



Deep Deep Deep Deep Deep ... Learning

Recent Advancements

Transformers, Large Language Models and Foundation Models



Cat

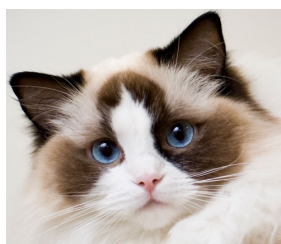
Primary reasons for advancements:

1. Expanded interests from the research community
2. Computational resources availability
3. **Big data availability**

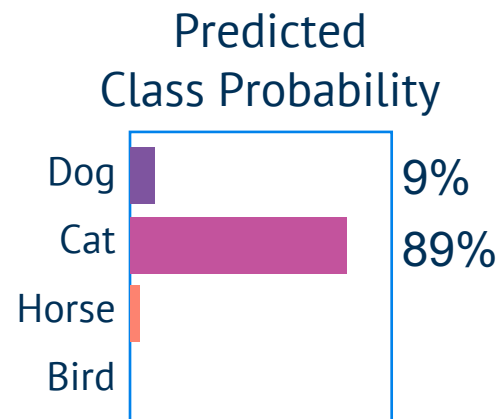
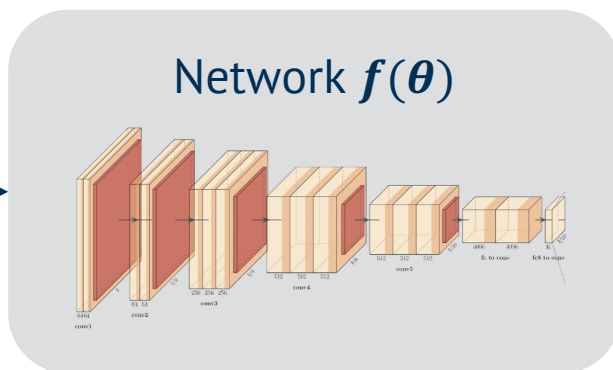
Deep Learning at Inference

Classification

Given : One network, One image. Required: Class Prediction



x



$$\hat{y} = f(x)$$
$$y = \operatorname{argmax}_i \hat{y}_i$$
$$p(\hat{y}) = T(f(x))$$

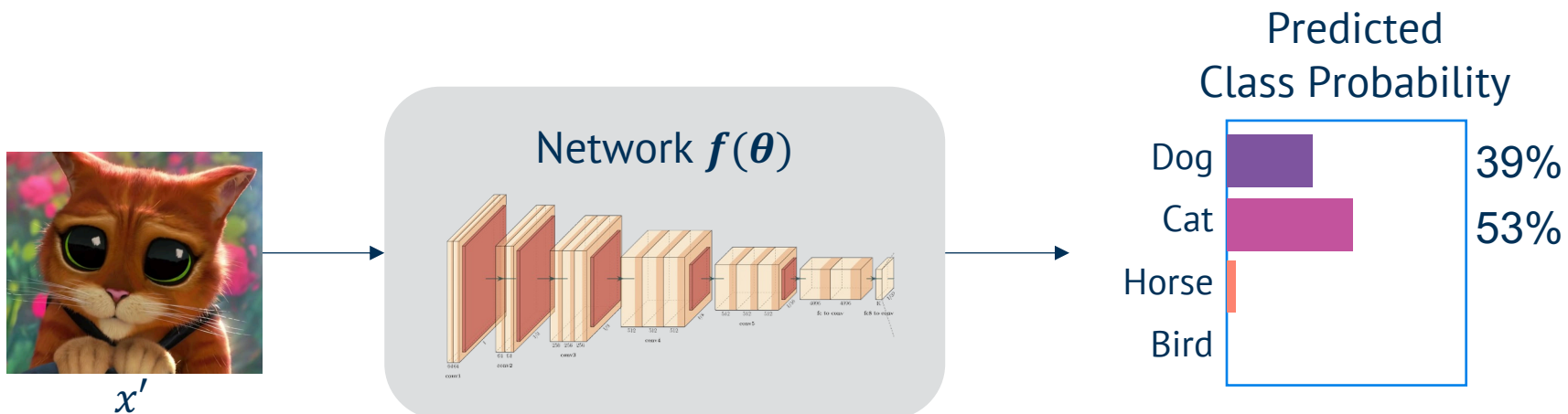
\hat{y} = Logits
 y = Predicted Class
 $p(\hat{y})$ = Probabilities
 $f(\cdot)$ = Trained Network
 χ = Training data

If $x \in \chi$, the data is **not novel**

Deep Learning at Inference

Robust Classification in Deep Networks

Deep learning robustness: Correctly predict class even when data is novel



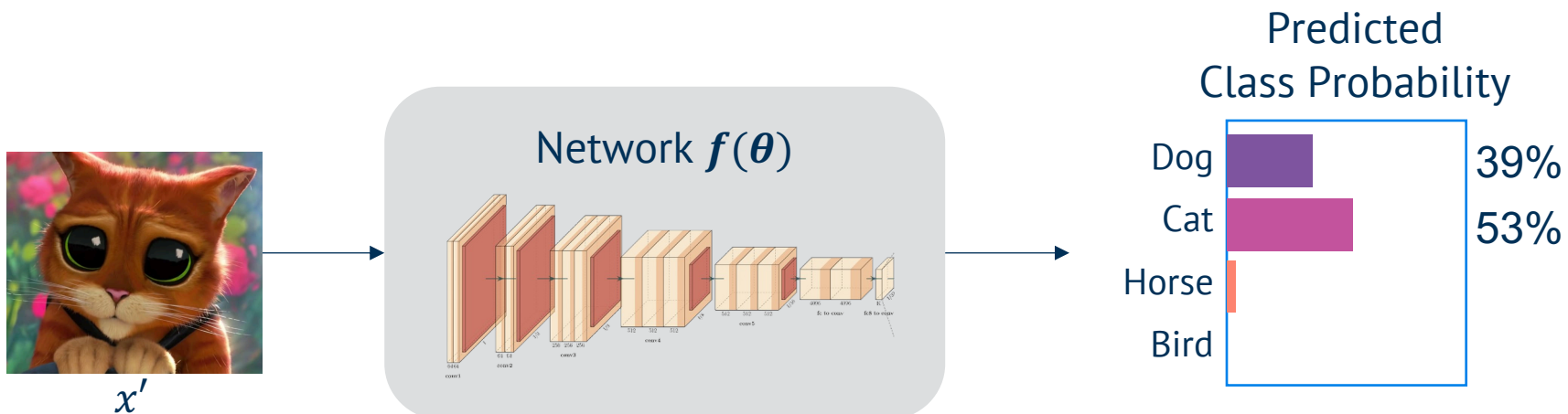
If $x \in \chi$, the data is **novel**

$$\begin{aligned} \hat{y} &= f(x' + \epsilon) & \hat{y} &= \text{Logits} \\ y &= \operatorname{argmax}_i \hat{y} & y &= \text{Predicted Class} \\ p(\hat{y}) &= T(f(x' + \epsilon)) & p(\hat{y}) &= \text{Probabilities} \\ & & f(\cdot) &= \text{Trained Network} \\ & & \chi &= \text{Training data} \\ & & \epsilon &= \text{Noise} \end{aligned}$$

Deep Learning at Inference

Robust Classification in Deep Networks

Deep learning robustness: Correctly predict class even when data is novel



To achieve robustness at Inference, we need the following:

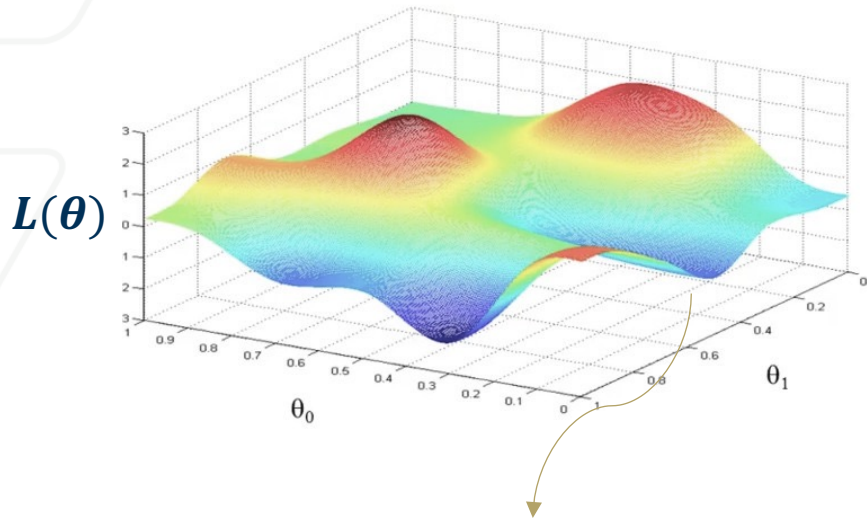
- **Information** provided by the novel data as a **function of training distribution**
- Methodology to **extract information** from novel data
- **Techniques** that utilize the information from novel data

Why is this Challenging?

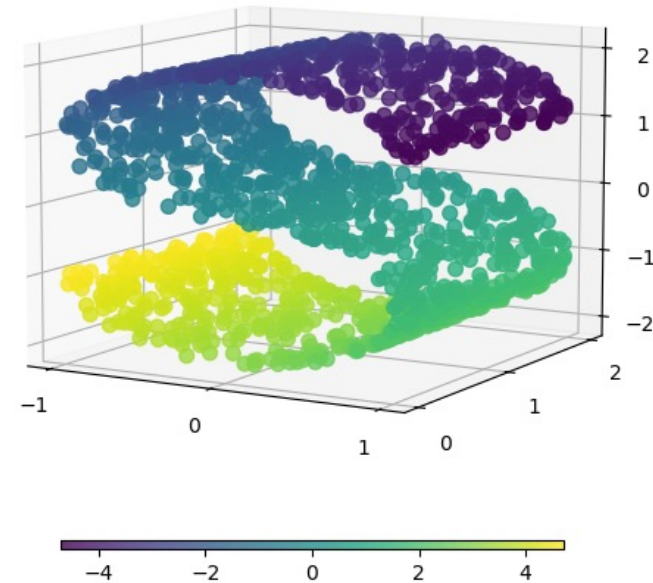
Challenges at Inference

A Quick note on Manifolds..

Manifolds are compact topological spaces that allow exact mathematical functions



Toy visualizations generated using functions
(and thousands of generated data points)

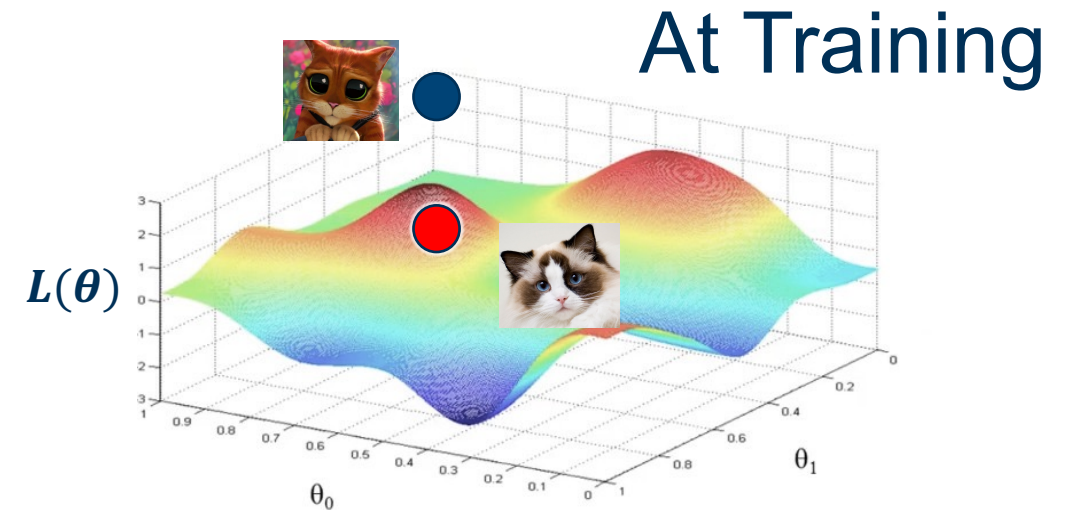
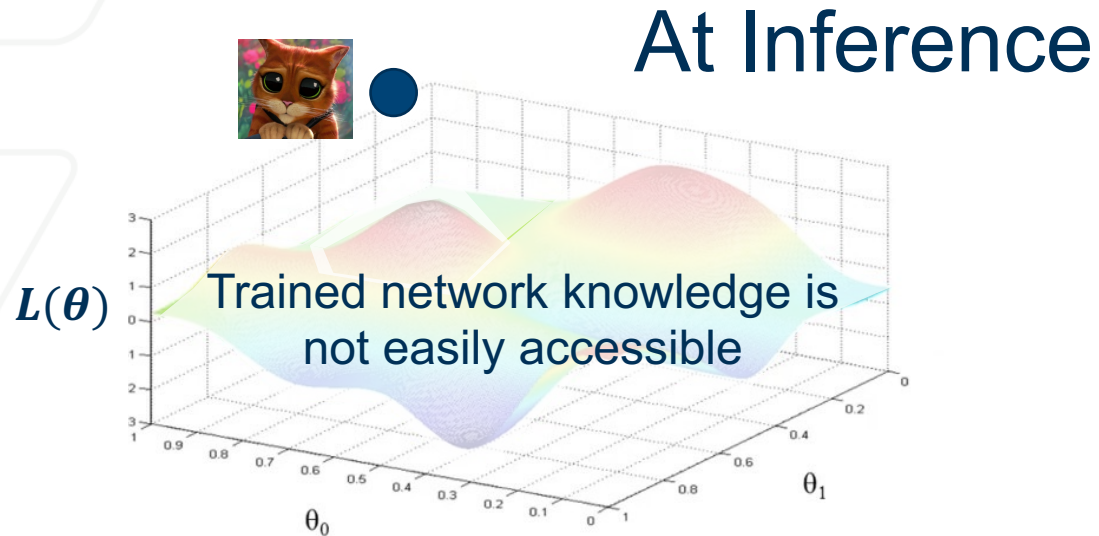


Real data visualizations generated using
dimensionality reduction algorithms (Isomap)

Challenges at Inference

Inference

However, at inference only the test data point is available and the underlying structure of the manifold is unknown

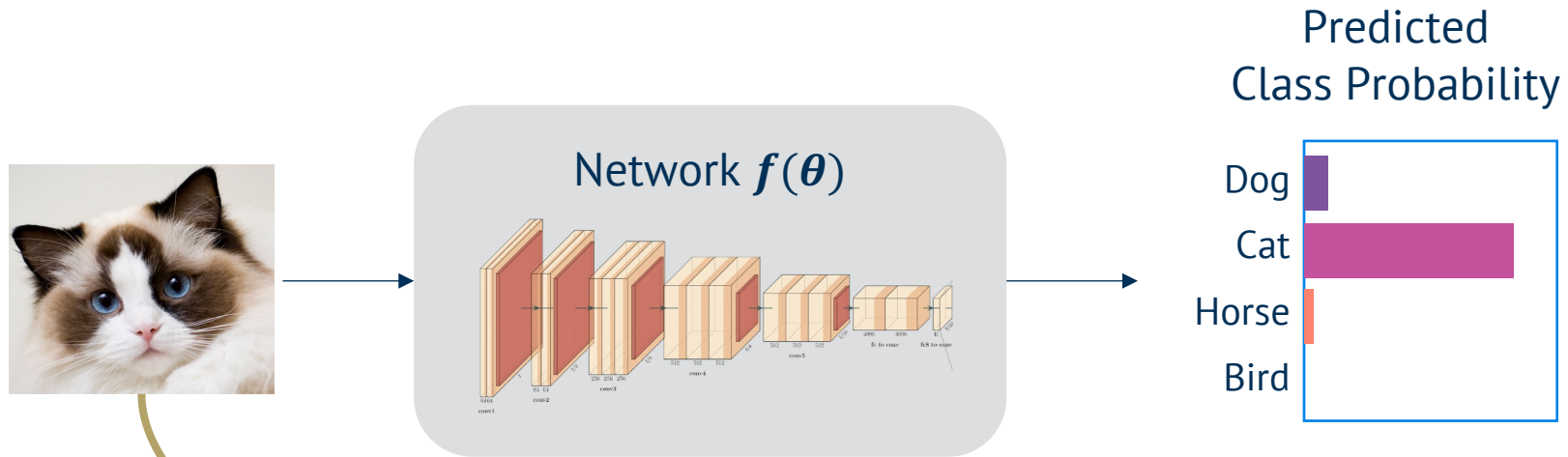


At training, we have access to all training data.

Information at Inference

Fisher Information

Colloquially, Fisher Information is the “surprise” in a system that observes an event

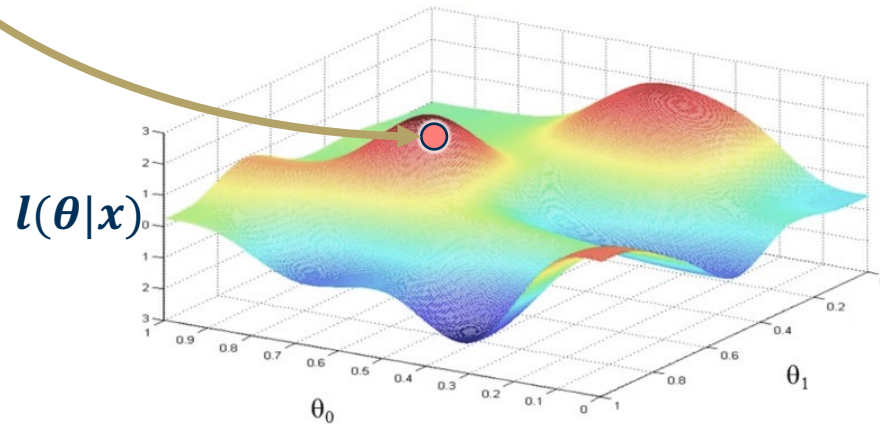


Fisher Information

$$I(\theta) = \text{Var}\left(\frac{\partial}{\partial \theta} l(\theta|x)\right)$$

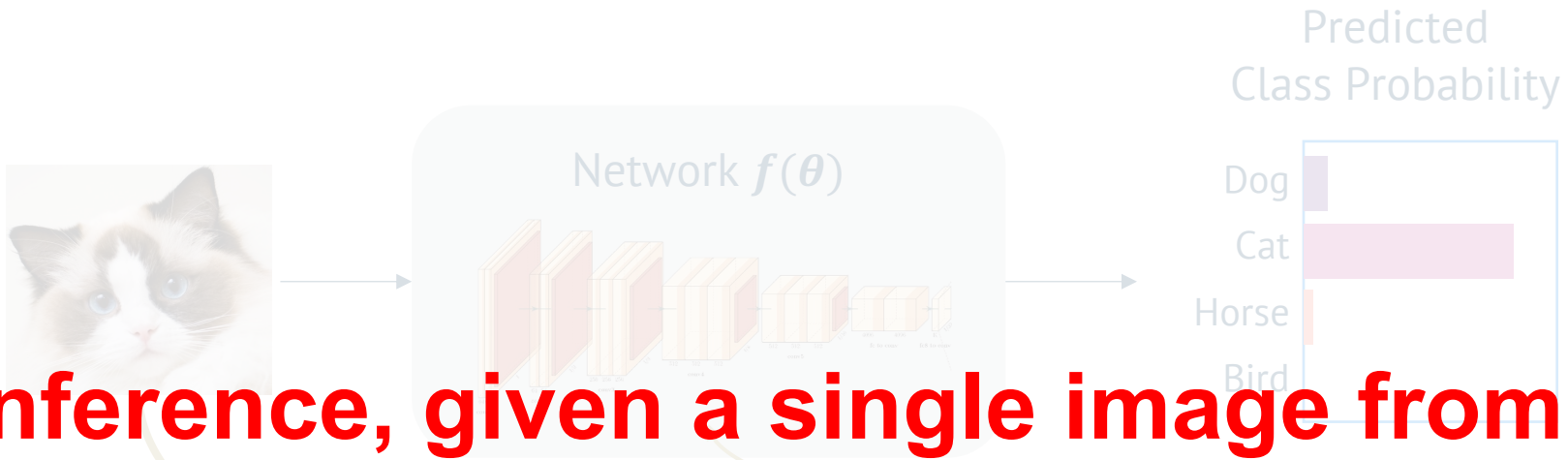
θ = Statistic of distribution
 $l(\theta | x)$ = Likelihood function

Likelihood function

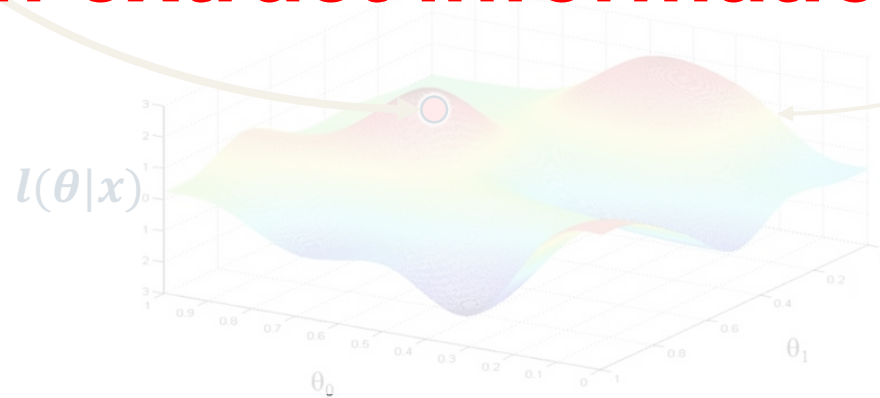


Information at Inference

Information at Inference



At inference, given a single image from a single class, we can extract information about other classes



Likelihood function

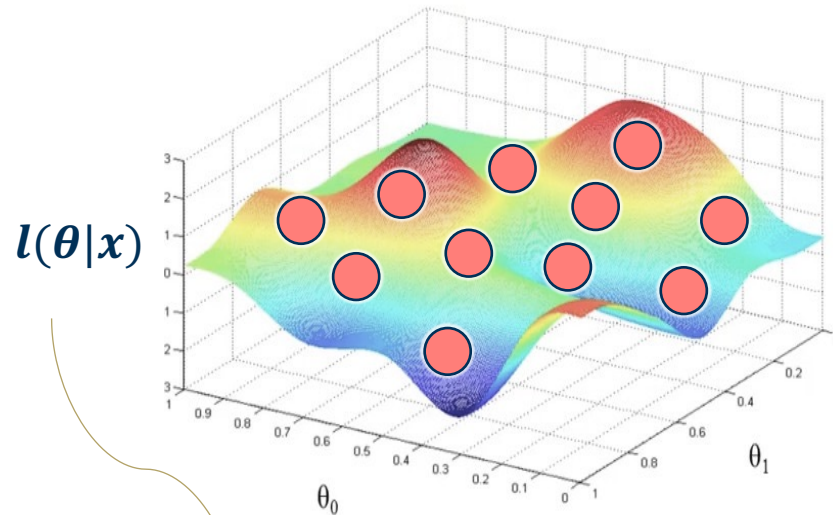
$$I(\theta) = \text{Var}\left(\frac{\partial}{\partial \theta} l(\theta|x)\right)$$

θ = Statistic of distribution
 $l(\theta | x)$ = Likelihood function

Information at Inference

Gradients as Fisher Information

Gradients infer information about the statistics of underlying manifolds



From before, $I(\theta) = \text{Var}\left(\frac{\partial}{\partial \theta} l(\theta|x)\right)$

Using variance decomposition, $I(\theta)$ reduces to:

$I(\theta) = E[U_\theta U_\theta^T]$ where

$E[\cdot]$ = Expectation

$U_\theta = \nabla_\theta l(\theta|x)$, Gradients w.r.t. the sample

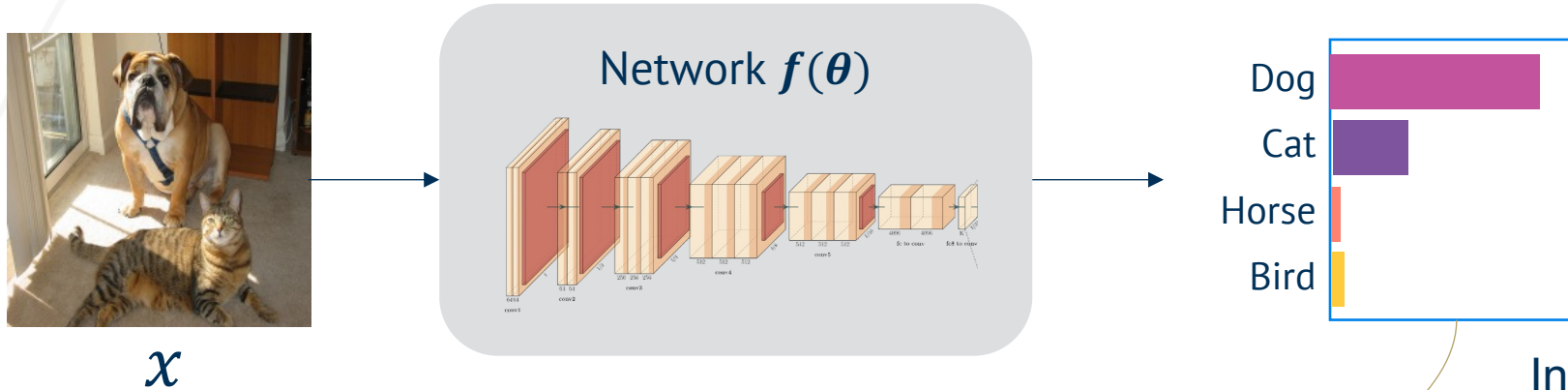
Likelihood function instead of loss manifold

Hence, gradients draw information from the underlying distribution as learned by the network weights!

Information at Inference

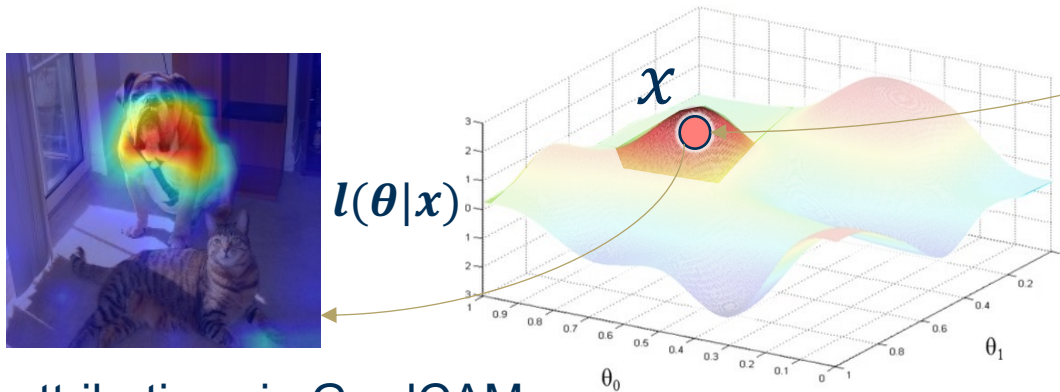
Case Study: Gradients as Fisher Information in Explainability

Gradients infer information about the statistics of underlying manifolds



Local information (specific to x) is sufficient!

In this case, the image and its prediction extracts nose, mouth and jowl features.



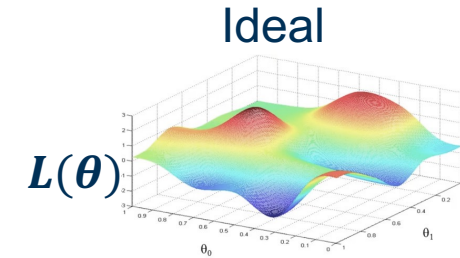
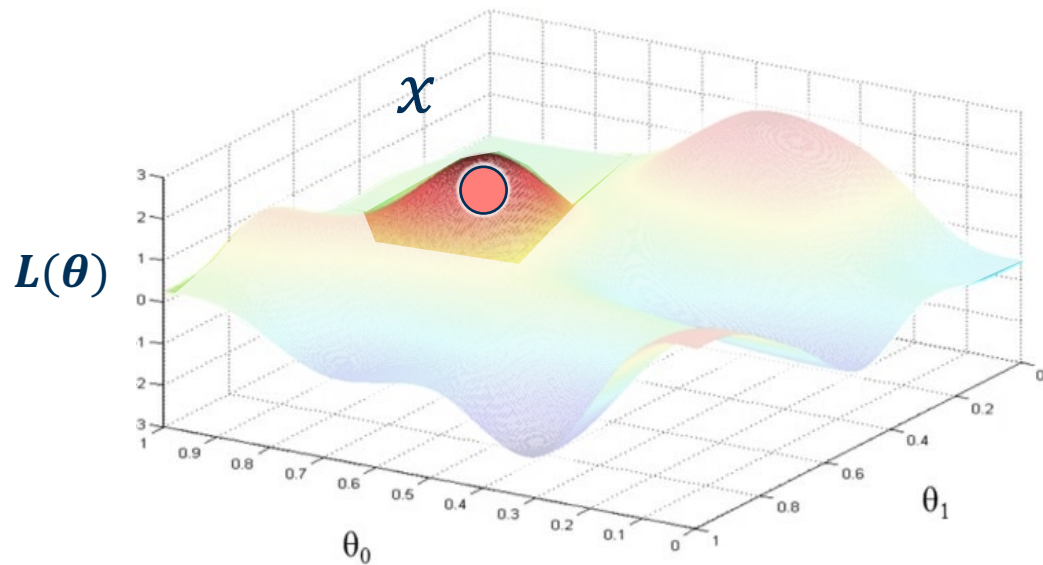
Hence, gradients draw information from the underlying distribution as learned by the network weights!

Feature attribution via GradCAM

Gradients at Inference

Local Information

Gradients provide local information around the vicinity of x , even if x is novel. This is because x projects on the learned knowledge

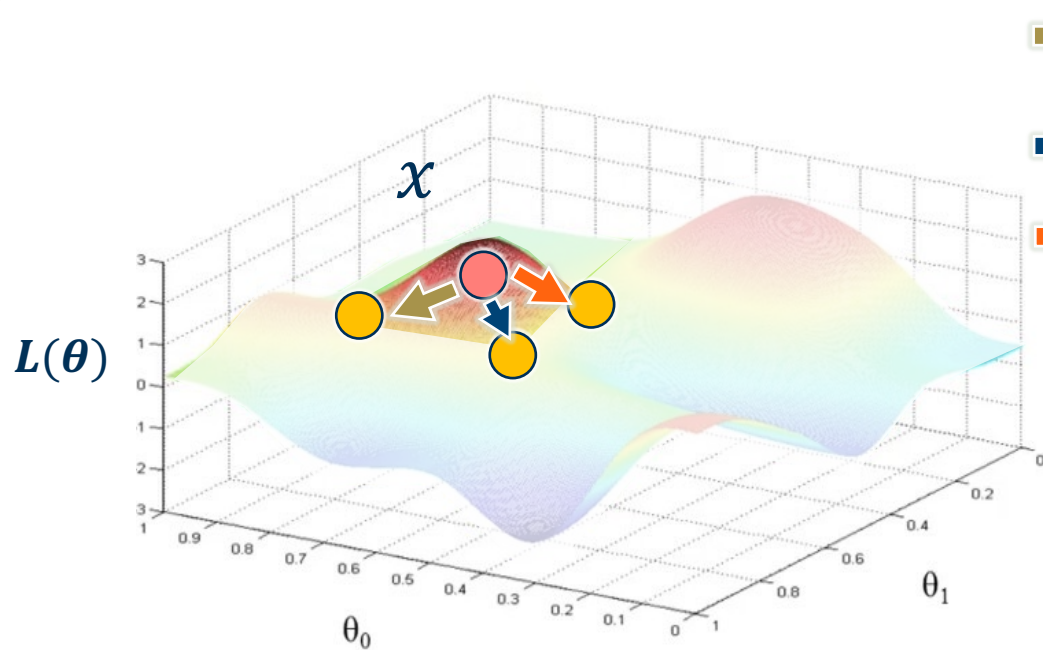


$\alpha \nabla_{\theta} L(\theta)$ provides local information up to a small distance α away from x

Gradients at Inference

Direction of Steepest Descent

Gradients allow choosing the fastest direction of descent given a loss function $L(\theta)$



Path 1?



Path 2?



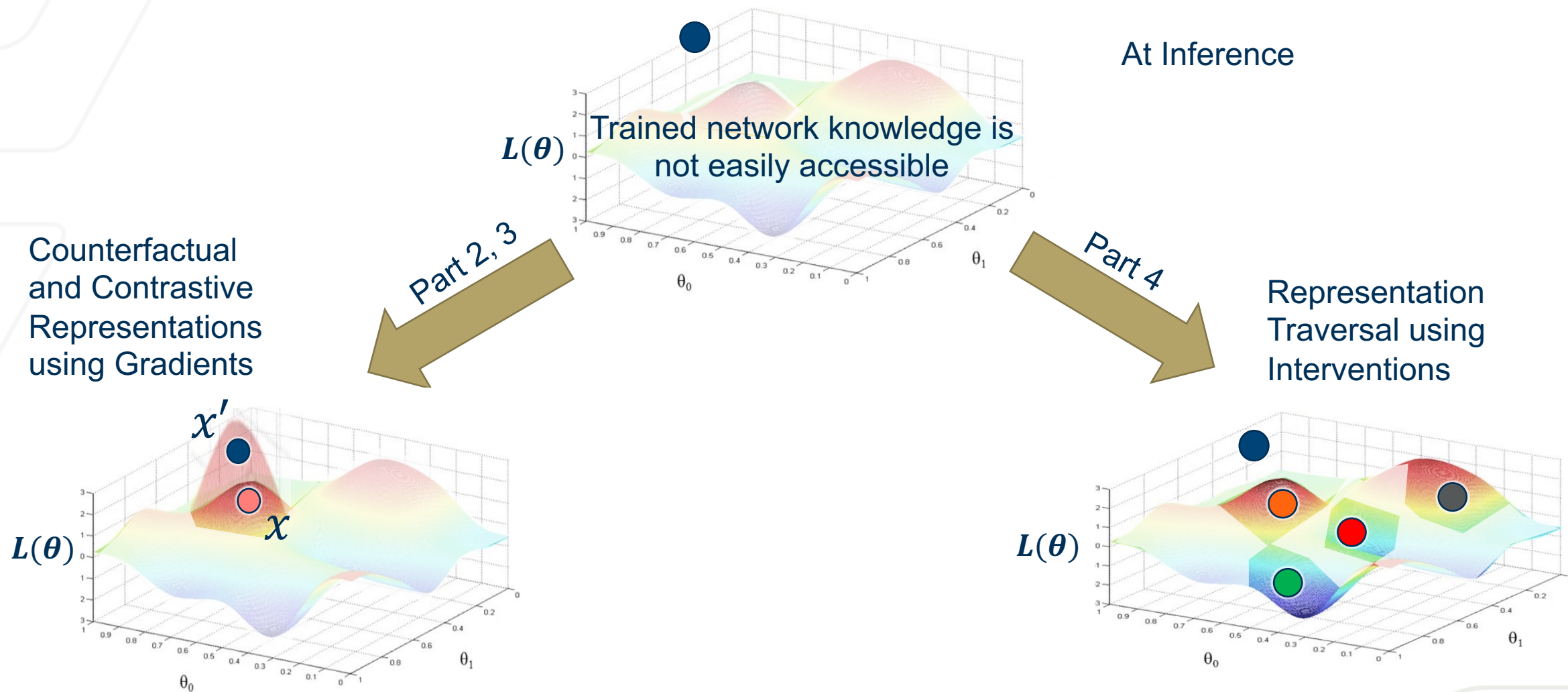
Path 3?

Which direction should we optimize towards (knowing only the local information)?

Negative of the gradient provides the **descent direction** towards the local minima, as measured by $L(\theta)$

Gradients at Inference

To Characterize the Novel Data at Inference



Robust Neural Networks

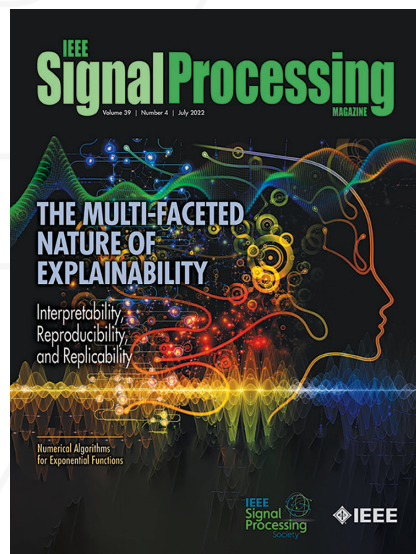
Part 2: Explainability at Inference

Objective

Objective of the Tutorial

To discuss methodologies that promote robustness in neural networks at inference

- Part 1: Inference in Neural Networks
- **Part 2: Explainability at Inference**
 - Visual Explanations
 - Gradient-based Explanations
 - GradCAM
 - CounterfactualCAM
 - ContrastCAM
- Part 3: Uncertainty at Inference
- Part 4: Intervenability at Inference
- Part 5: Conclusions and Future Directions



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations



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Postdoc



Ghassan AlRegib, PhD
Professor



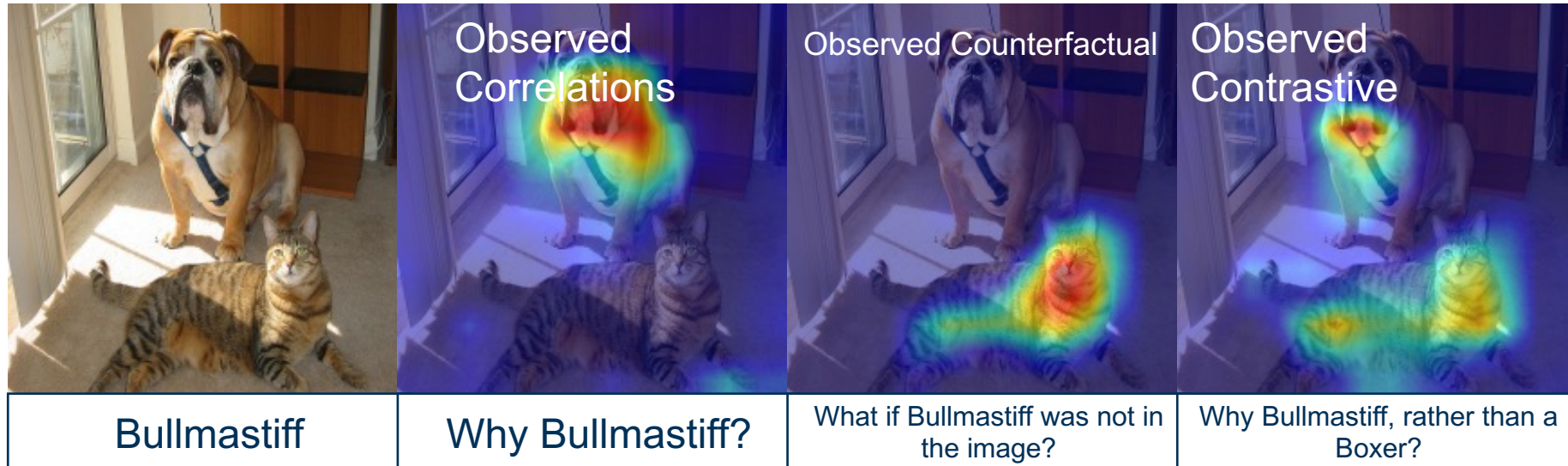
Explanations

Visual Explanations



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

- Explanations are defined as a set of rationales used to understand the reasons behind a decision
- If the decision is based on visual characteristics within the data, the decision-making reasons are visual explanations

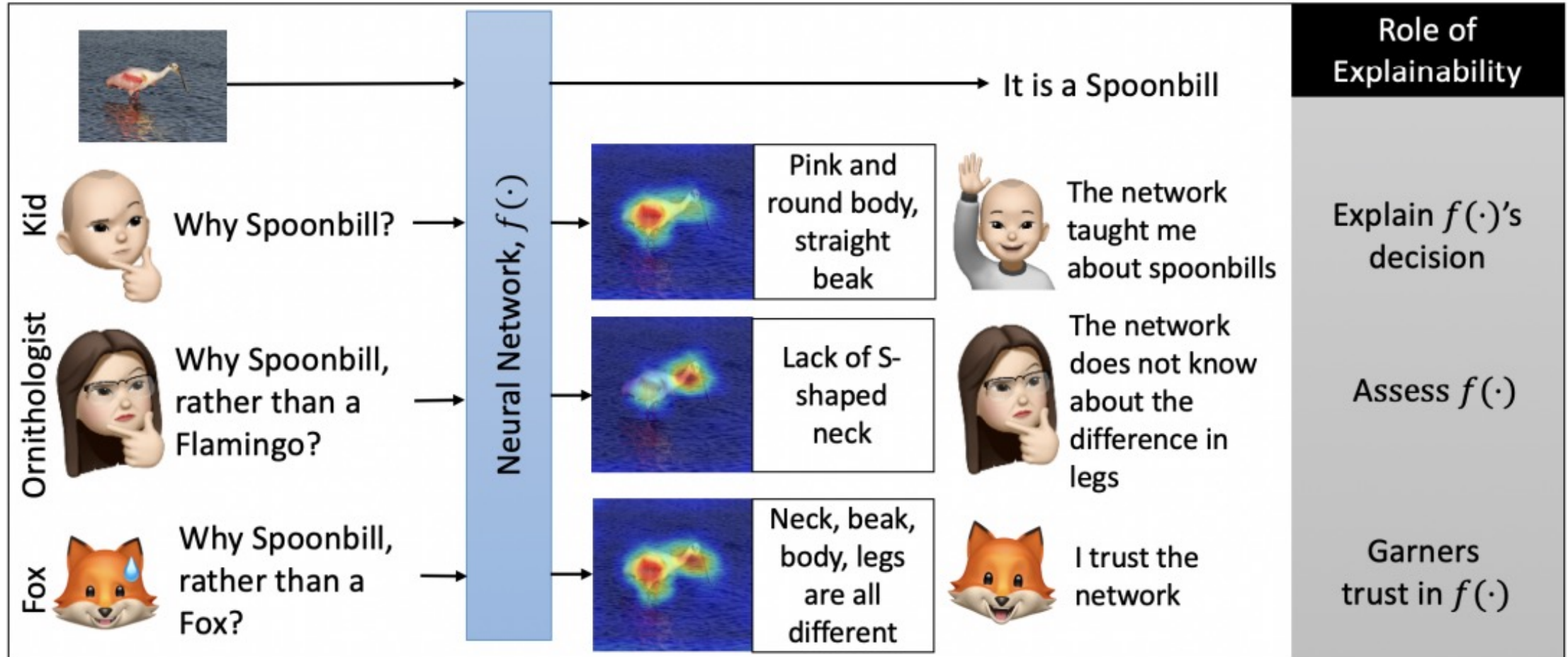


Explanations

Role of Explanations – context and relevance



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations



Explanations

Gradient-based Explanations



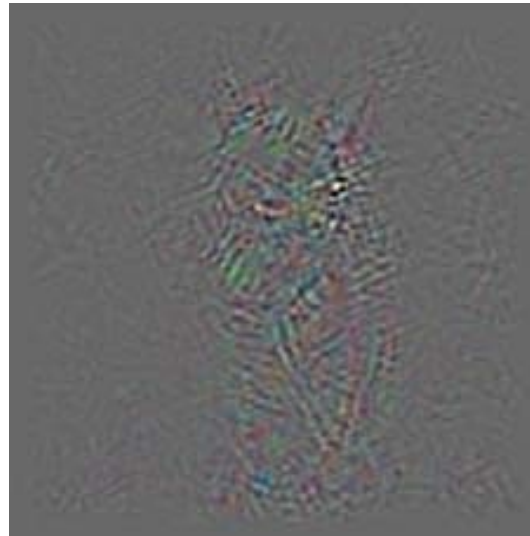
Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

Gradients provide a one-shot means of perturbing the input that changes the output; They provide pixel-level importance scores

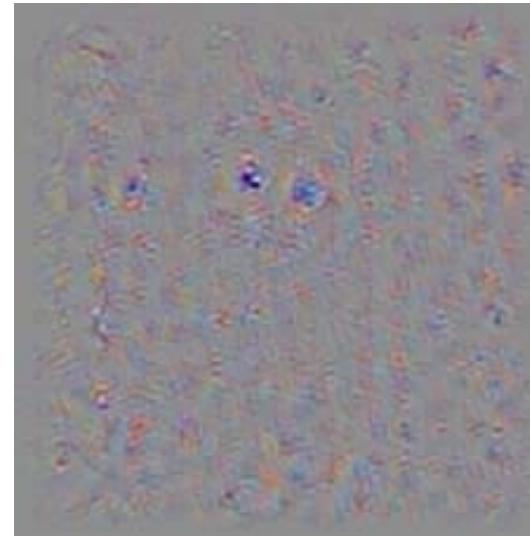
Input



Vanilla Gradients



Deconvolution Gradients



Guided Backpropagation



However, localization remains an issue

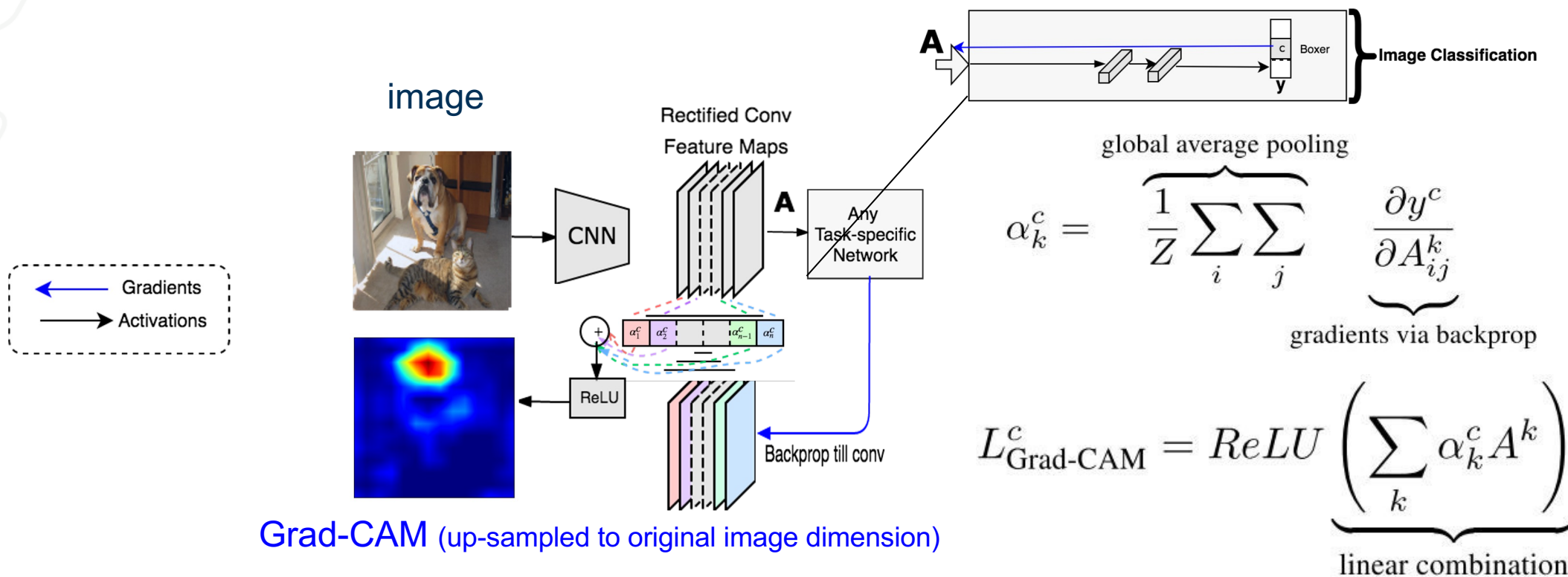
Gradient and Activation-based Explanations

GradCAM



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

Grad-CAM uses the gradient information flowing into the last convolutional layer of the CNN to assign importance values to each activation for a particular decision of interest.



Gradient and Activation-based Explanations

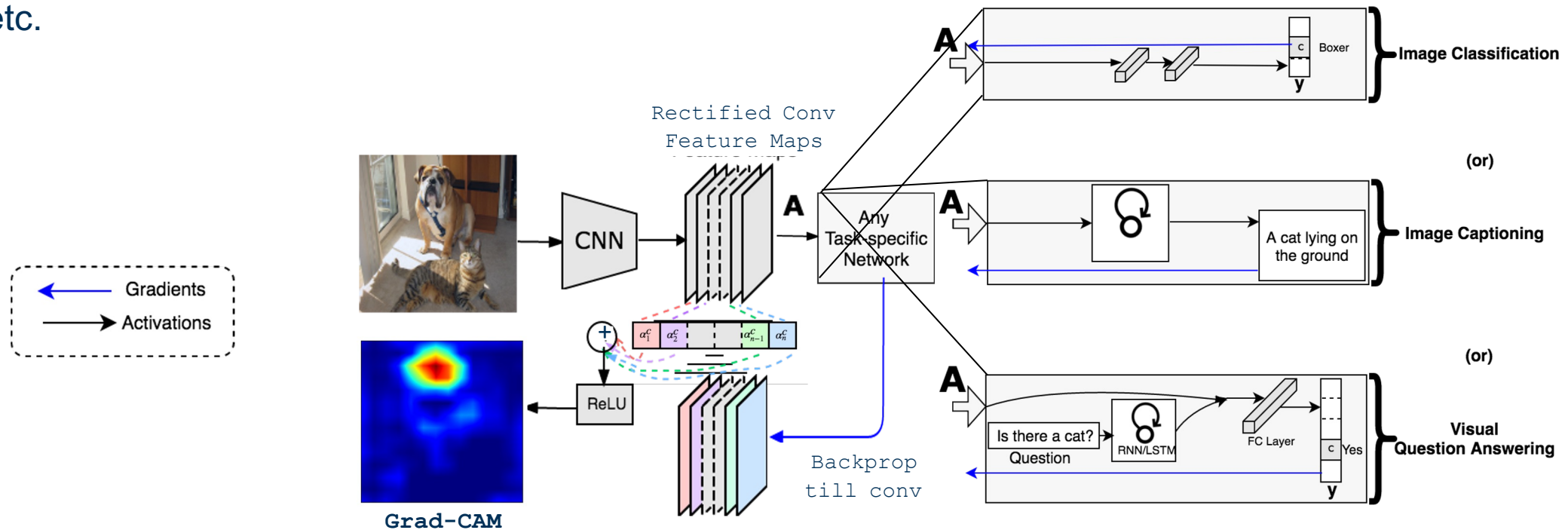
GradCAM

Grad-CAM generalizes to any task:

- Image classification
- Image captioning
- Visual question answering
- etc.



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations



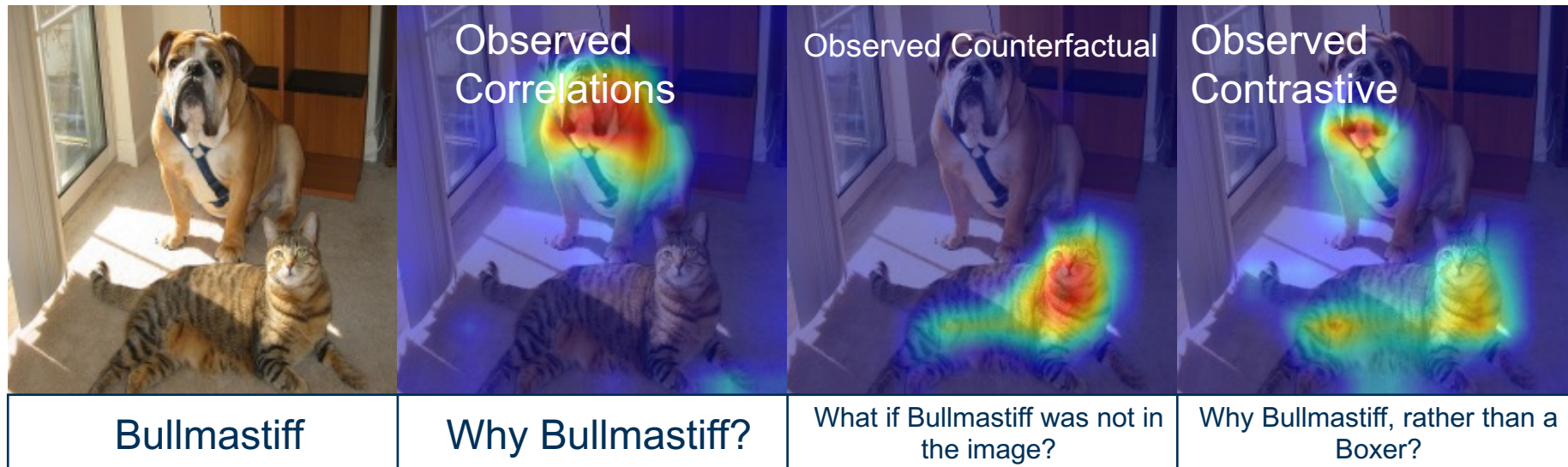
Gradient and Activation-based Explanations

Explanatory Paradigms



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

GradCAM provides answers to ‘Why P?’ questions. But different stakeholders require relevant and contextual explanations



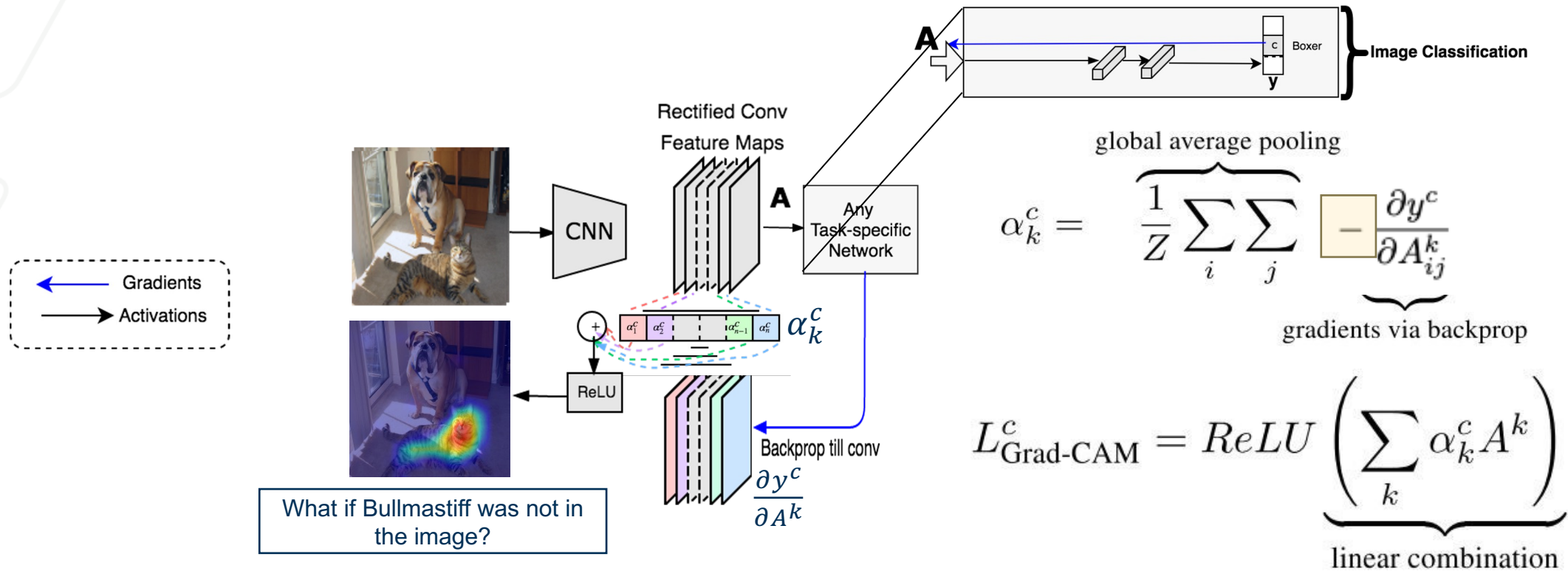
Gradient and Activation-based Explanations

CounterfactualCAM: What if this region were absent in the image?



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

In GradCAM, global average pool the **negative of** gradients to obtain α^c for each kernel k



Negating the gradients effectively removes these regions from analysis

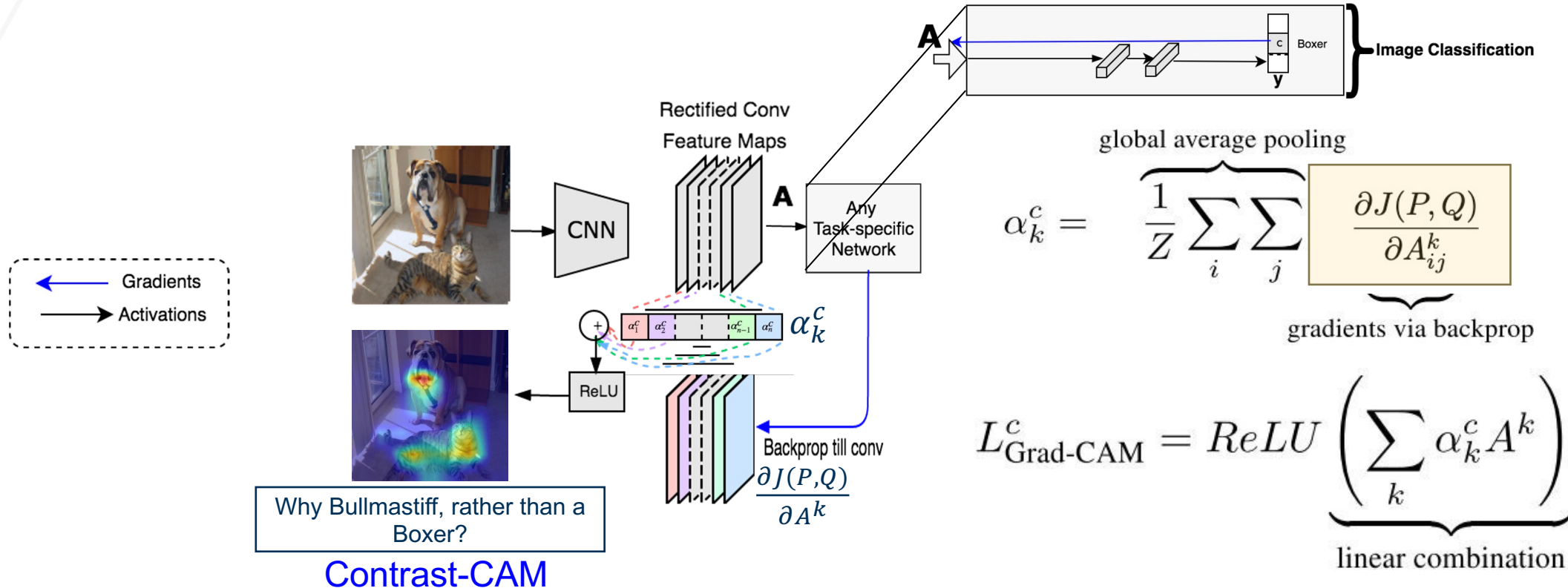
Gradient and Activation-based Explanations

ContrastCAM: Why P, rather than Q?



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

In GradCAM, backward pass the **loss between predicted class P and some contrast class Q** to last conv layer



Backpropagating the loss highlights the differences between classes P and Q.

Gradient and Activation-based Explanations

Results from GradCAM, CounterfactualCAM, and ContrastCAM



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

Input Image	Grad-CAM	Contrast 1	Contrastive Explanation 1	Contrast 2	Contrastive Explanation 2
ImageNet dataset : Spoonbill	Grad-CAM : Why Spoonbill?	Representative Flamingo image	Why Spoonbill, rather than Flamingo?	Representative Pig image	Why Spoonbill, rather than Pig? Why not Spoonbill, with 100% confidence?
ImageNet dataset : Bull Mastiff	Grad-CAM : Why Bull Mastiff?	Representative Boxer image	Why Bull Mastiff, rather than Boxer?	Representative Blue jay image	Why Bull Mastiff, rather than Blue jay? Why not Bull Mastiff, with 100% confidence?
CURE-TSR dataset : No-Left Image	Grad-CAM : Why No-Left?	Representative No-Right image	Why No-Left, rather than No-Right?	Representative Stop Sign	Why No-Left, rather than Stop? Why not No-Left with 100% confidence?
Stanford Cars Dataset: Bugatti Convertible	Grad-CAM: Why Bugatti Convertible?	Representative Bugatti Coupe image	Why Convertible, rather than Coupe?	Representative Audi A6 image	Why Bugatti, rather than Audi A6? Why not Bugatti with 100% confidence?

Gradient and Activation-based Explanations

Results from GradCAM, CounterfactualCAM, and ContrastCAM



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Human Interpretable

Gradient and Activation-based Explanations

Results from GradCAM, CounterfactualCAM, and ContrastCAM



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Human Interpretable

Same as Grad-CAM

Gradient and Activation-based Explanations

Results from GradCAM, CounterfactualCAM, and ContrastCAM



Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

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ImageNet dataset : Bull Mastiff	Grad-CAM : Why : Bull Mastiff?	Representative Boxer image	Why Bull Mastiff, rather than Boxer	Representative Blue jay image	Why Bull Mastiff, rather than Blue jay? Why not Bull Mastiff, with 100% confidence?
CURE-TSR dataset : No-Left Image	Grad-CAM : Why No-Left?	Representative No-Right image	Why No-Left, rather than No-Right?	Representative Stop Sign	Why No-Left, rather than Stop? Why not No-Left with 100% confidence?
Stanford Cars Dataset: Bugatti Convertible	Grad-CAM: Why Bugatti Convertible?	Representative Bugatti Coupe image	Why Convertible, rather than Coupe?	Representative Audi A6 image	Why Bugatti, rather than Audi A6? Why not Bugatti with 100% confidence?

Human Interpretable

Same as Grad-CAM

Not Human Interpretable

Gradient and Activation-based Explanations

Results from GradCAM, CounterfactualCAM, and ContrastCAM

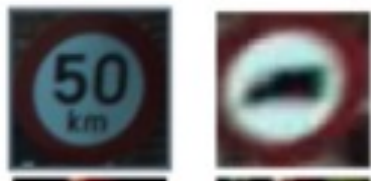


Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

Input Image	Grad-CAM	Contrast 1	Contrastive Explanation 1	Contrast 2	Contrastive Explanation 2
ImageNet dataset : Spoonbill	Grad-CAM : Why Spoonbill?	Representative Flamingo image	Why Spoonbill, rather than Flamingo?	Representative Pig image	Why Spoonbill, rather than Pig? Why not Spoonbill, with 100% confidence?

Human Interpretable

Same as Grad-CAM



CURE-TSR dataset : No-Left Image	Grad-CAM : Why No-Left?	Representative No-Right image	Why No-Left, rather than No-Right?	Representative Stop Sign	Why No-Left, rather than Stop?	Why not No-Left with 100% confidence?
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Gradient and Activation-based Explanations

Results from GradCAM, CounterfactualCAM, and ContrastCAM

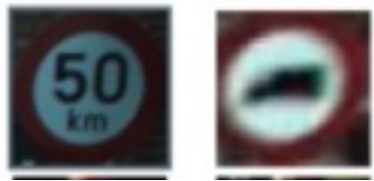


Explanatory Paradigms in Neural Networks: Towards Relevant and Contextual Explanations

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Only traffic sign with a straight bottom-left edge – enough to say 'Not STOP Sign'

Human
e...all
Same as Grad-CAM



CURE-TSR dataset : No-Left Image	Grad-CAM : Why No-Left?	Representative No-Right image	Why No-Left, rather than No-Right?	Representative Stop Sign	Why No-Left, rather than Stop?	Why not No-Left with 100% confidence?	
Stanford Cars Dataset: Bugatti Convertible	Grad-CAM: Why Bugatti Convertible?	Representative Bugatti Coupe image	Why Convertible, rather than Coupe?	Representative Audi A6 image	Why Bugatti, rather than Audi A6?	Why not Bugatti with 100% confidence?	

Robust Neural Networks

Part 3: Uncertainty at Inference

Objective

Objective of the Tutorial

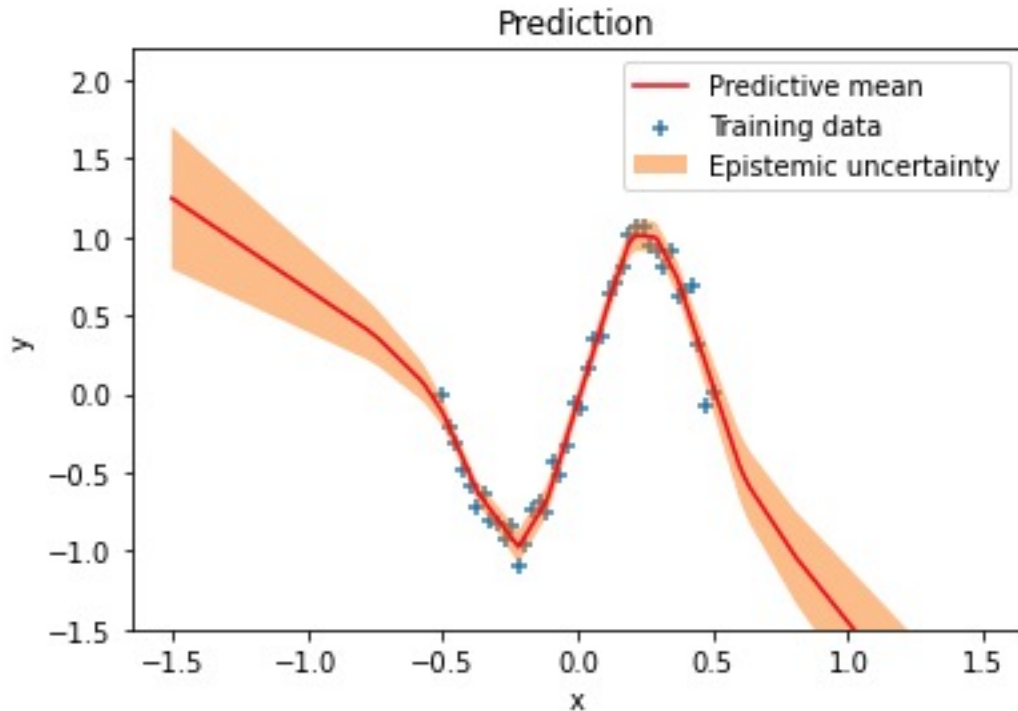
To discuss methodologies that promote robustness in neural networks at inference

- Part 1: Inference in Neural Networks
- Part 2: Explainability at Inference
- **Part 3: Uncertainty at Inference**
 - Uncertainty Definition
 - Uncertainty Quantification
 - Gradient-based Uncertainty
 - Adversarial and Corruption Detection
- Part 4: Intervenability at Inference
- Part 5: Conclusions and Future Directions

Uncertainty

What is Uncertainty?

Uncertainty is a model knowing that it does not know



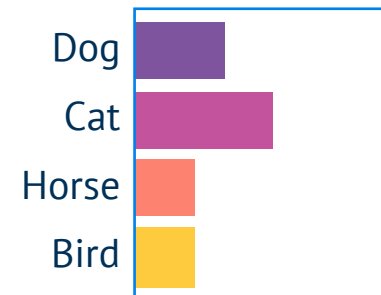
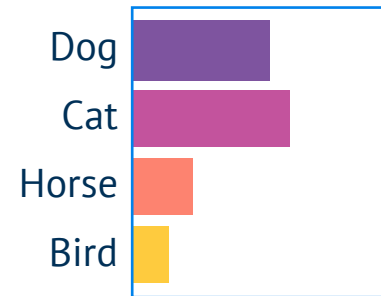
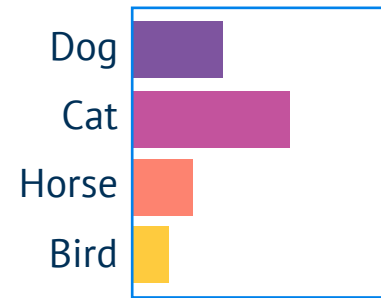
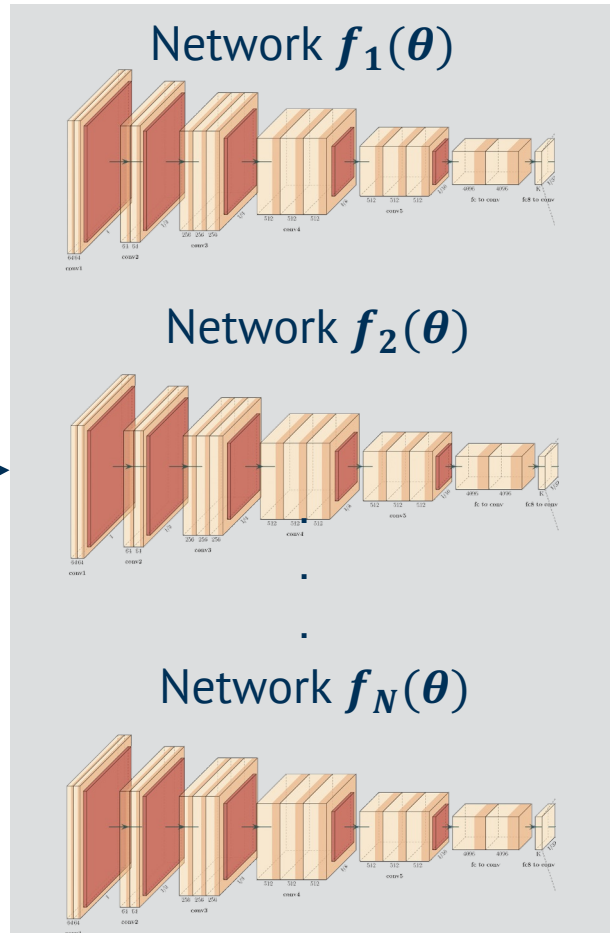
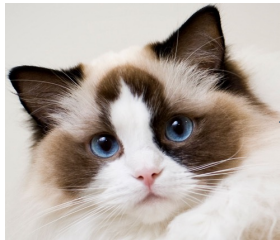
A simple example:

- When training data is **available**: **Less uncertainty**
- When training data is **unavailable**: **More uncertainty**

Uncertainty

Uncertainty Quantification in Neural Networks

Via Ensembles¹

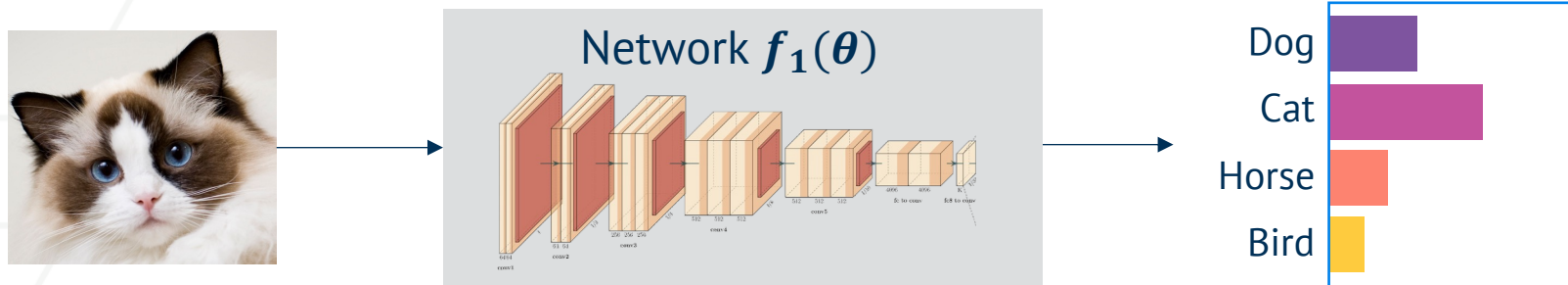


Variation within outputs $Var(y)$ is the uncertainty. Commonly referred to as **Prediction Uncertainty.**

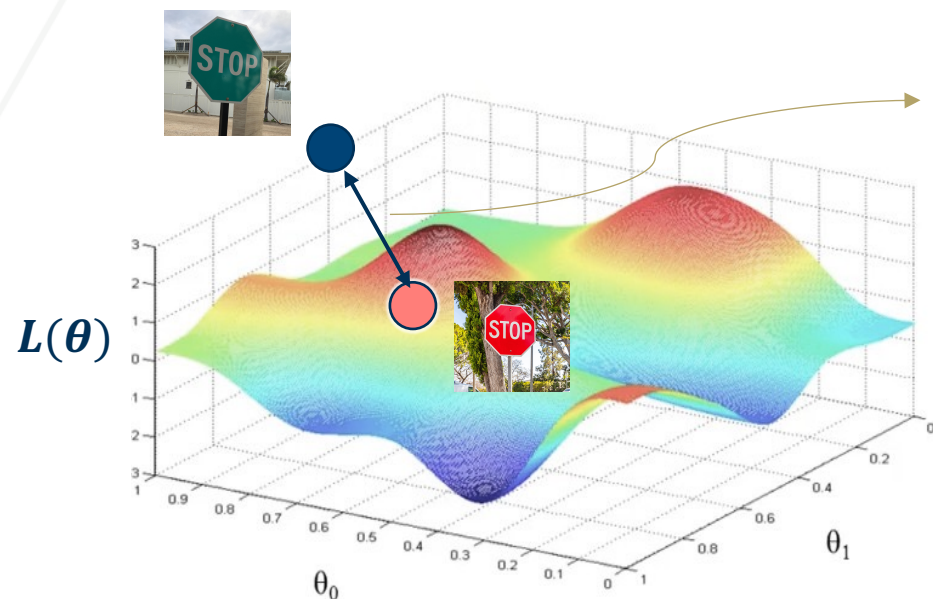
Uncertainty

Uncertainty Quantification in Neural Networks

Via Single pass methods¹



Uncertainty quantification using a single network and a single pass



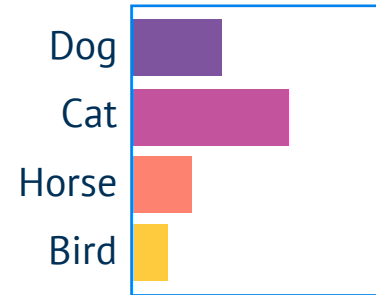
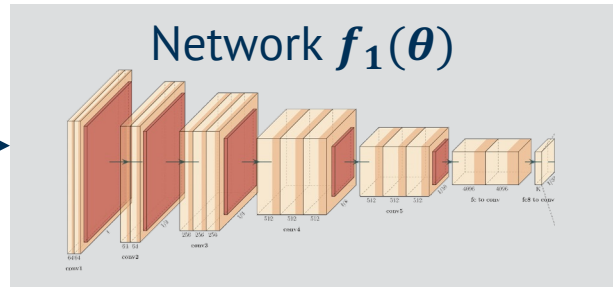
Calculate distance from some trained clusters

Does not require multiple networks!

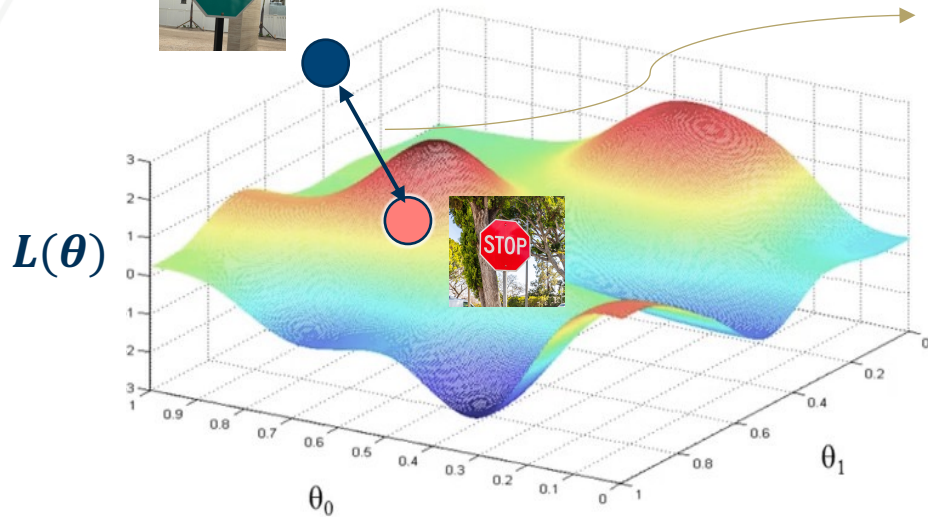
Uncertainty

Gradients as Single pass Features

Our Goal: Use gradients to characterize the novel data at Inference



Uncertainty quantification using a single network and a single pass



Calculate distance from some trained clusters

Does not require multiple networks!

Challenge: Class and prediction cannot be trusted!

Uncertainty

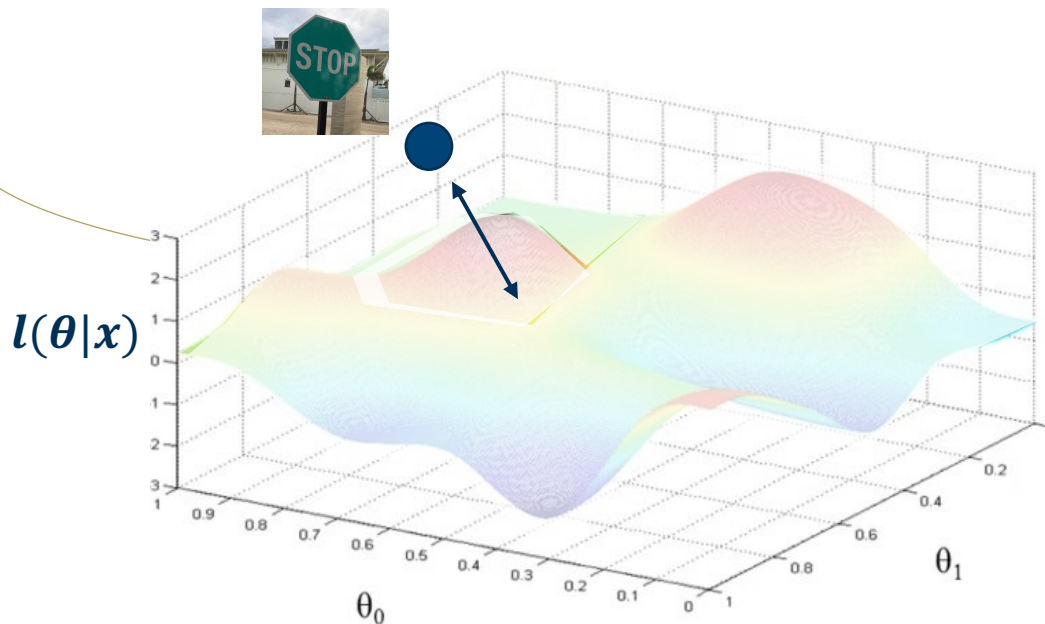
Gradients as Single pass Features

Our Goal: Use gradients to characterize the novel data at Inference, without global information

Distance from unknown cluster

Two techniques:

1. **Backpropagating Confounding labels for Adversarial Detection**
2. Backpropagating Confounding labels for Robust Prediction





Probing the Purview of Neural Networks via Gradient Analysis



Jinsol Lee,
PhD Candidate



Mohit Prabhushankar, PhD
Postdoc



Ghassan AlRegib, PhD
Professor



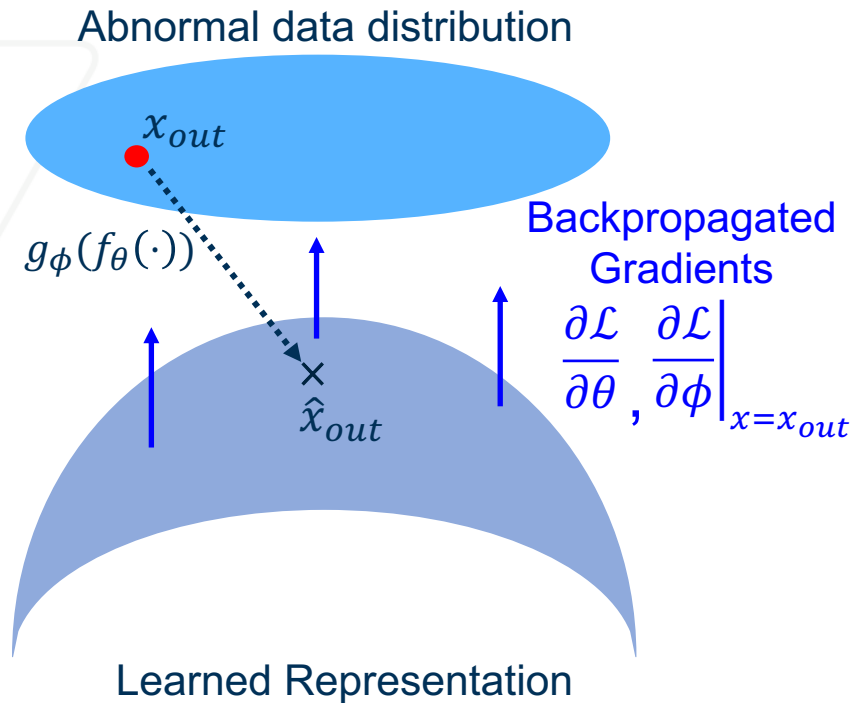
Uncertainty in Neural Networks

Principle



Probing the Purview of Neural Networks via Gradient Analysis

Principle: Gradients provide a distance measure between the learned representations space and novel data



However, what is \mathcal{L} ?

- In anomaly detection, the loss was between the input and its reconstruction
- In prediction tasks, there is neither the reconstructed input nor ground truth

Uncertainty in Neural Networks

Principle



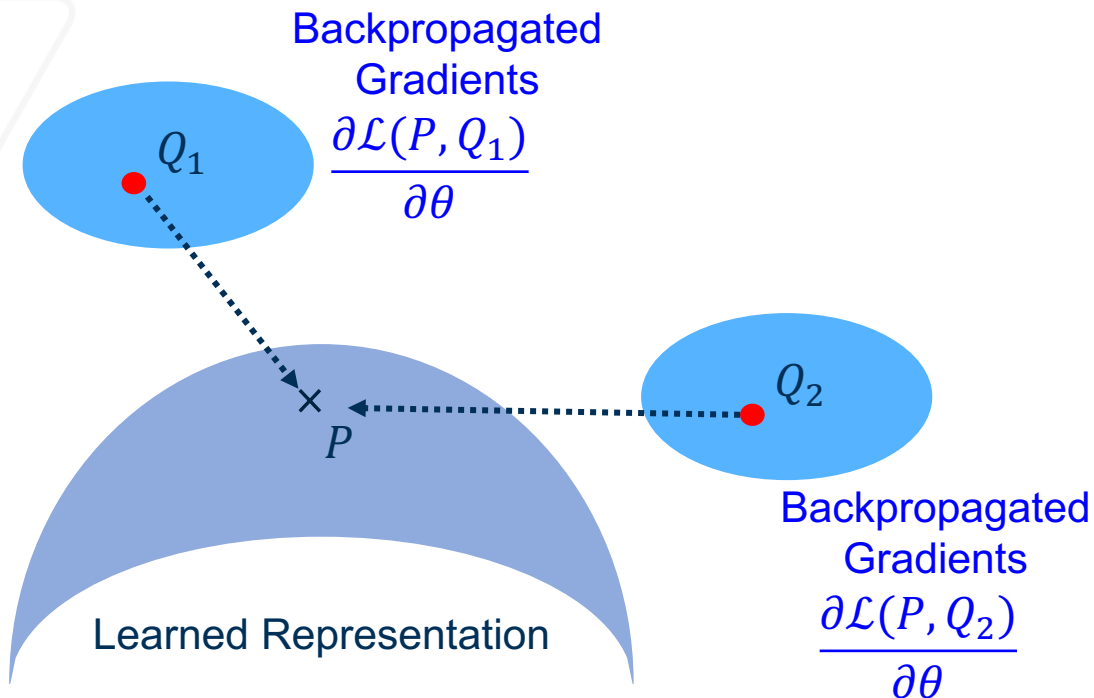
Probing the Purview of Neural Networks via Gradient Analysis

Principle: Gradients provide a distance measure between the learned representations space and novel data

P = Predicted class

Q_1 = Contrast class 1

Q_2 = Contrast class 2



However, what is \mathcal{L} ?

- In anomaly detection, the loss was between the input and its reconstruction
- In prediction tasks, there is neither the reconstructed input nor ground truth
- **We backpropagate all contrast classes - $Q_1, Q_2 \dots Q_N$ by backpropagating N one-hot vectors**
- Higher the distance, higher the uncertainty score

Toy Manifold Example

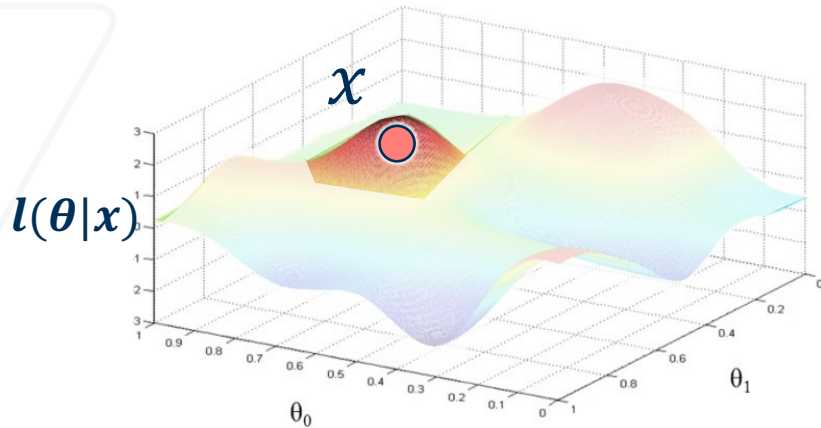
What is uncertainty?



Probing the Purview of Neural Networks via Gradient Analysis

Gradients represent the local required change in manifold

Similar to introspective learning!



Contrast class 1



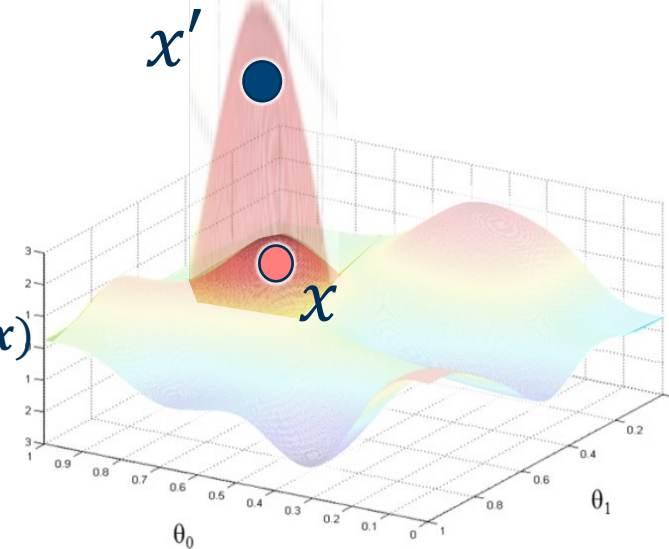
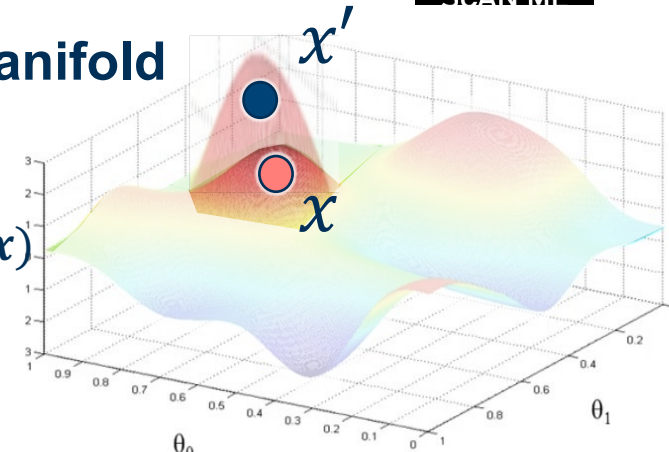
$l(\theta|x)$

⋮

Contrast class N



$l(\theta|x)$



- Gradients provide the necessary change in manifold that would predict the novel data 'correctly'.
- Correctly means contrastively (or incorrectly)!

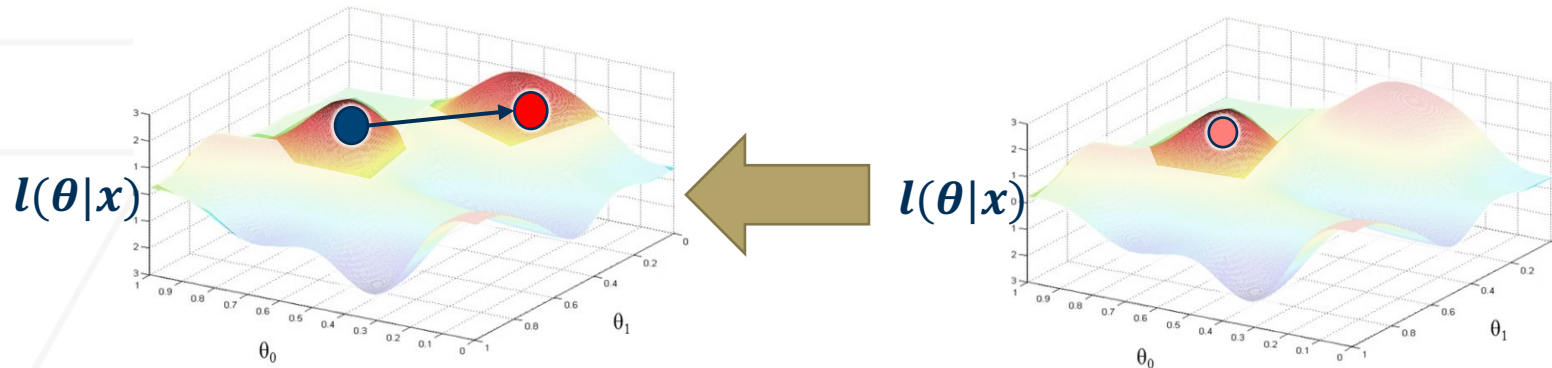
Toy Manifold Example

How is this different from Explainability?



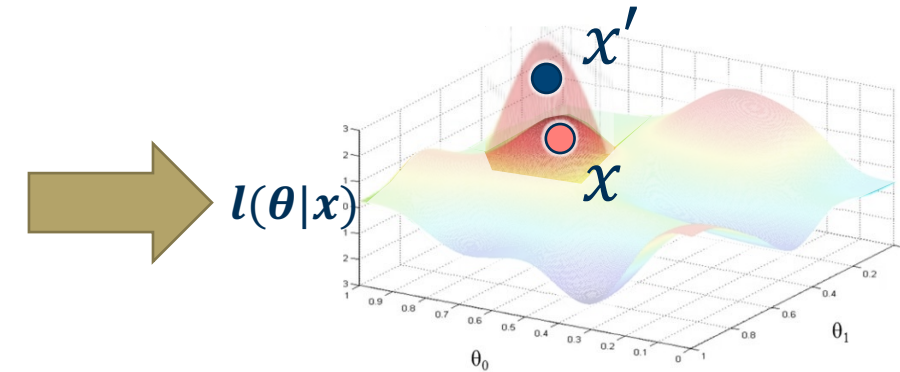
Probing the Purview of Neural Networks via Gradient Analysis

Part 3: Explainability



- In Part 3: Activations of learned manifold are weighted by gradients w.r.t. activations to extract information and provide explanations

Part 4: Uncertainty



- In Part 4: Statistics of gradients w.r.t. the weights (energy) will be directly used as features

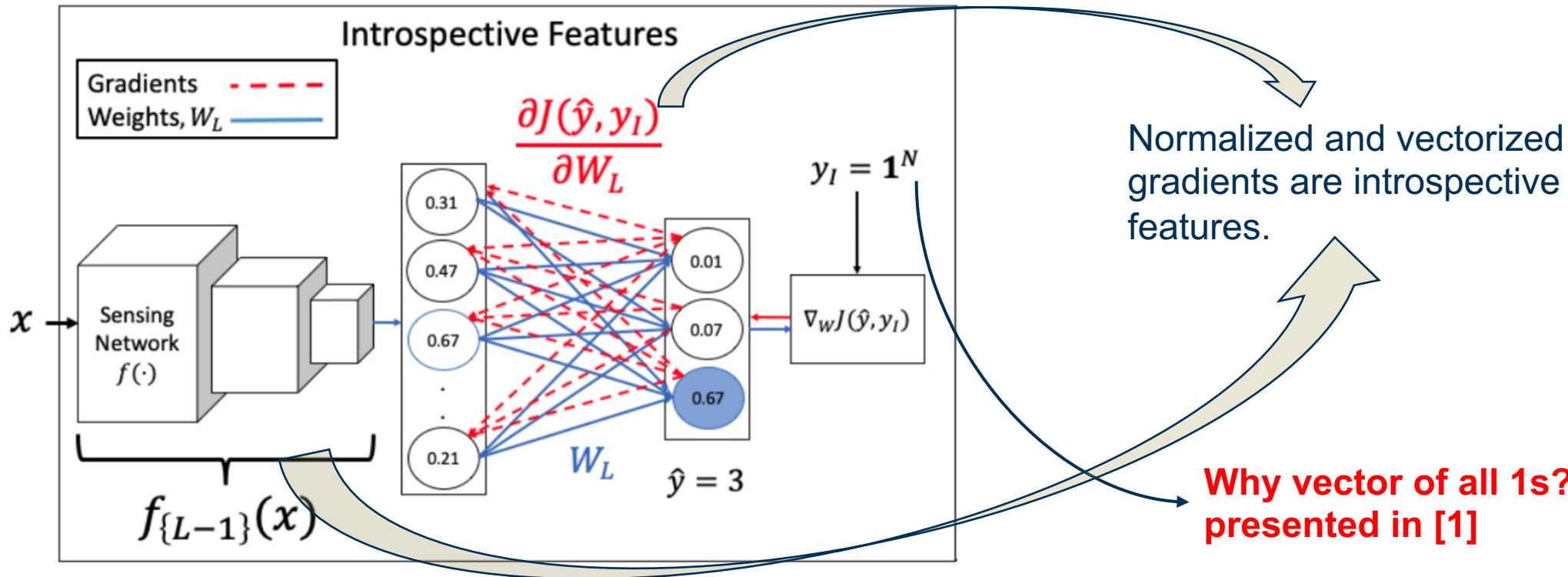
Uncertainty in Neural Networks

Deriving Gradient Features



Probing the Purview of Neural Networks via Gradient Analysis

Step 1: Measure the loss between the prediction P and a vector of all ones and backpropagate to obtain the introspective features



Why vector of all 1s? The theory is presented in [1]

Uncertainty in Neural Networks

Utilizing Gradient Features



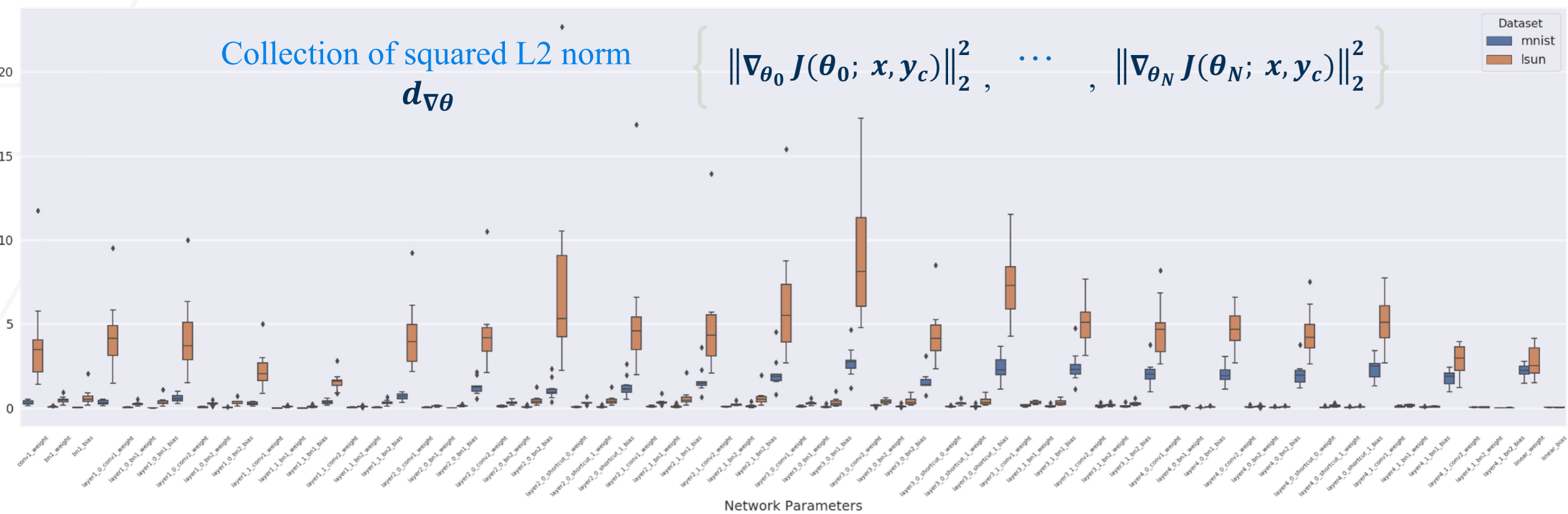
Probing the Purview of Neural Networks via Gradient Analysis

Step 2: Take L2 norm of all generated gradients

Collection of squared L2 norm
 $d_{\nabla\theta}$

$$\left\{ \|\nabla_{\theta_0} J(\theta_0; x, y_c)\|_2^2, \dots, \|\nabla_{\theta_N} J(\theta_N; x, y_c)\|_2^2 \right\}$$

Dataset
mnist
lsun



MNIST: In-distribution, SUN: Out-of-Distribution

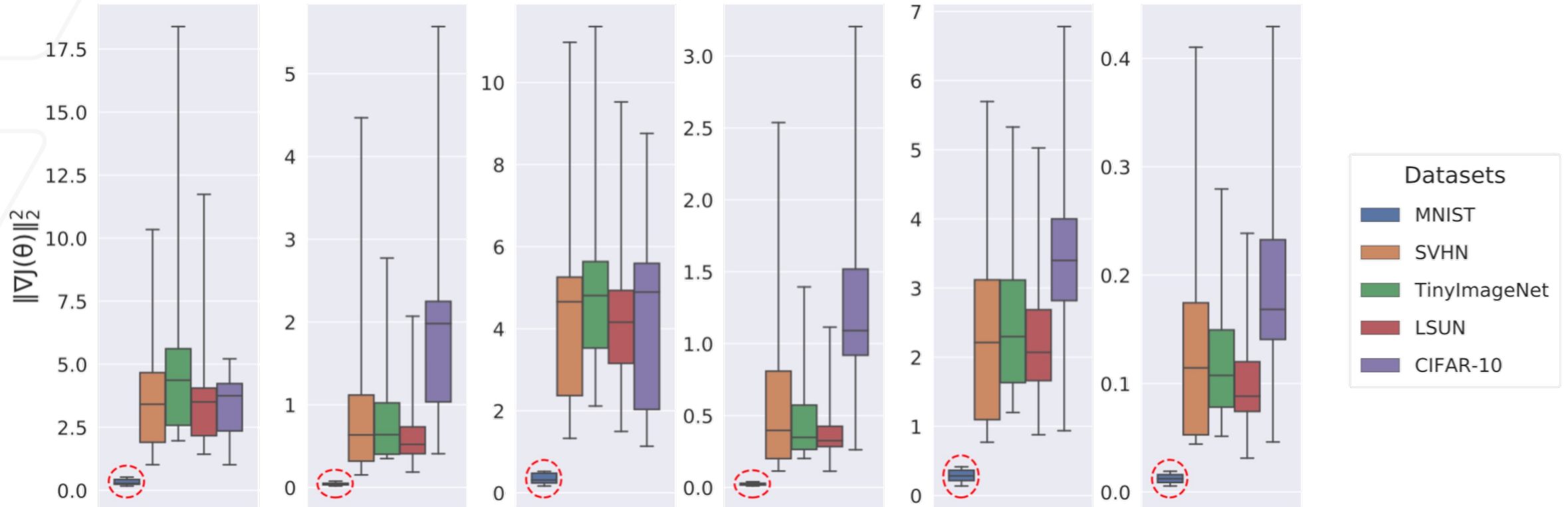
Gradient-based Uncertainty

Uncertainty in OOD Setting



Probing the Purview of Neural Networks via Gradient Analysis

Squared L2 distances for different parameter sets



MNIST: Circled in red. Significantly lower uncertainty compared to OOD datasets

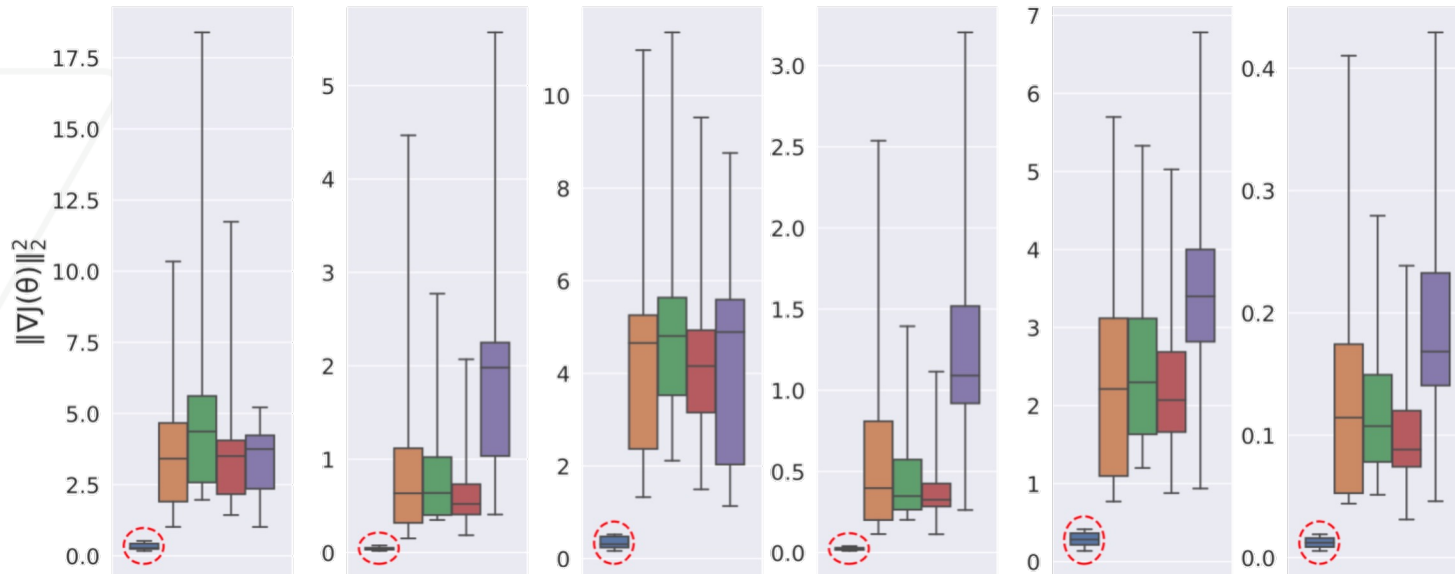
Gradient-based Uncertainty

Experimental Setup



Probing the Purview of Neural Networks
via Gradient Analysis

Utilize this discrepancy in trained vs untrained data gradient L2 distance to detect adversarial, noisy, and OOD data



- Step 1:** Train a deep network $f(\cdot)$ on some **training distribution**
- Step 2:** Introduce challenging (adversarial, noisy, OOD) data
- Step 3:** Derive **gradient uncertainty** on both trained and challenge data
- Step 4:** Train a classifier $H(\cdot)$ to **detect** challenging from trained data
- Step 5:** At test time, data is passed through $f(\cdot)$ and then $H(\cdot)$ to obtain a **Reliability classification**

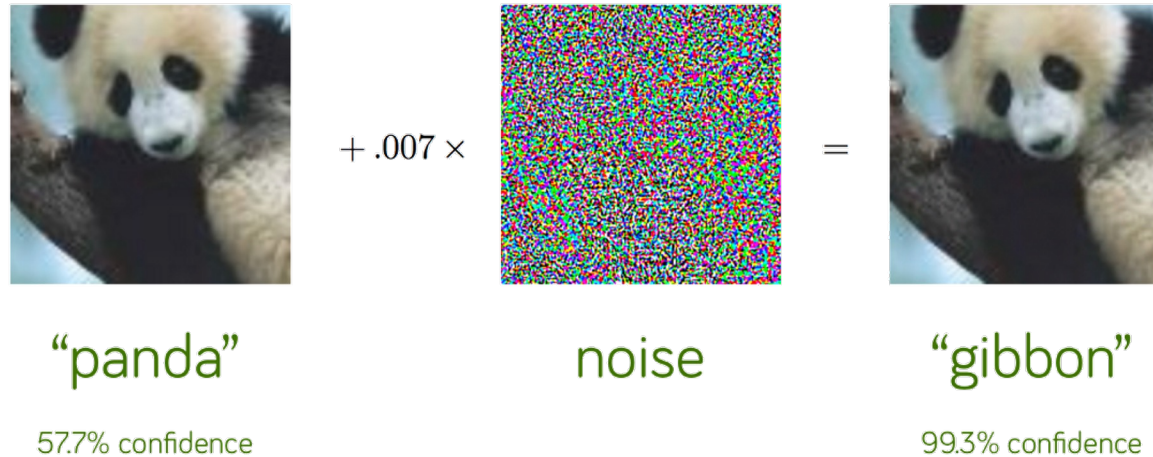
Gradient-based Uncertainty

Uncertainty in Adversarial Setting



Probing the Purview of Neural Networks via Gradient Analysis

Vulnerable DNNs in the real world



Goal: to examine the ability of trained DNNs to handle adversarial inputs during inference

Gradient-based Uncertainty

Uncertainty in Adversarial Setting



SCAN ME

Probing the Purview of Neural Networks via Gradient Analysis

MODEL	ATTACKS	BASELINE	LID	M(V)	M(P)	M(FE)	M(P+FE)	OURS
RESNET	FGSM	51.20	90.06	81.69	84.25	99.95	99.95	93.45
	BIM	49.94	99.21	87.09	89.20	100.0	100.0	96.19
	C&W	53.40	76.47	74.51	75.71	92.78	92.79	97.07
	PGD	50.03	67.48	56.27	57.57	65.23	75.98	95.82
	ITERLL	60.40	85.17	62.32	64.10	85.10	92.10	98.17
	SEMANTIC	52.29	86.25	64.18	65.79	83.95	84.38	90.15
DENSENET	FGSM	52.76	98.23	86.88	87.24	99.98	99.97	96.83
	BIM	49.67	100.0	89.19	89.17	100.0	100.0	96.85
	C&W	54.53	80.58	75.77	76.16	90.83	90.76	97.05
	PGD	49.87	83.01	70.39	66.52	86.94	83.61	96.77
	ITERLL	55.43	83.16	70.17	66.61	83.20	77.84	98.53
	SEMANTIC	53.54	81.41	62.16	62.15	67.98	67.29	89.55

Uncertainty

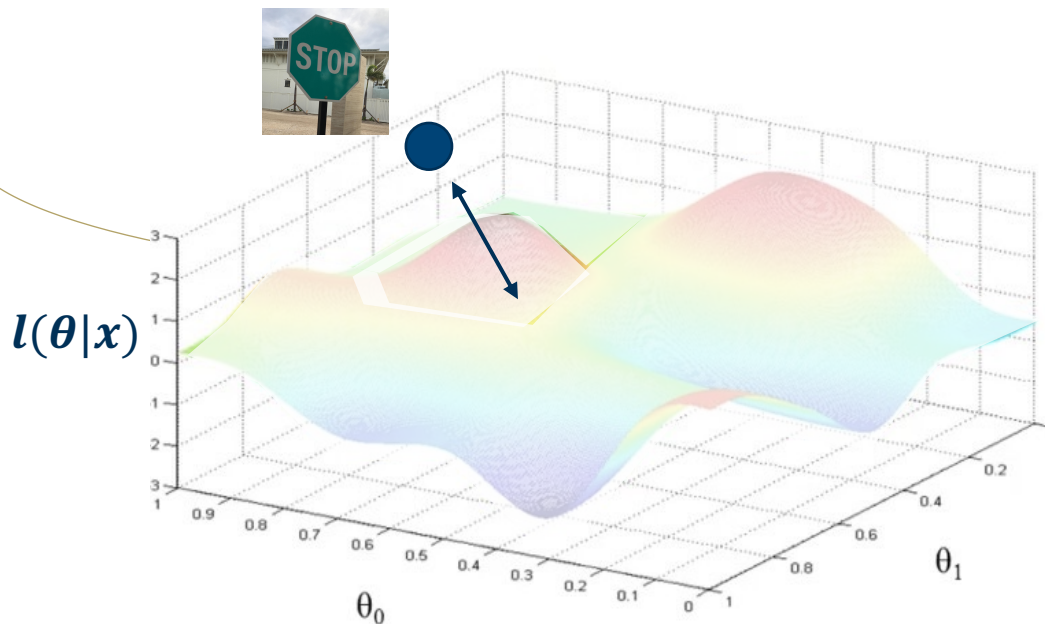
Gradients as Single pass Features

Our Goal: Use gradients to characterize the novel data at Inference, without global information

Distance from unknown cluster

Two techniques:

1. Backpropagating Confounding labels for Adversarial Detection
2. **Backpropagating Confounding labels for Robust Prediction**





Introspective Learning: A Two-Stage Approach for Inference in Neural Networks



Mohit Prabhushankar, PhD
Postdoc



Ghassan AlRegib, PhD
Professor



Robustness in Neural Networks

Why Robustness?



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

How would humans resolve this challenge?

We Introspect!

- Why am I being shown this slide?
- Why images of muffins rather than pastries?
- What if the dog was a bull mastiff?



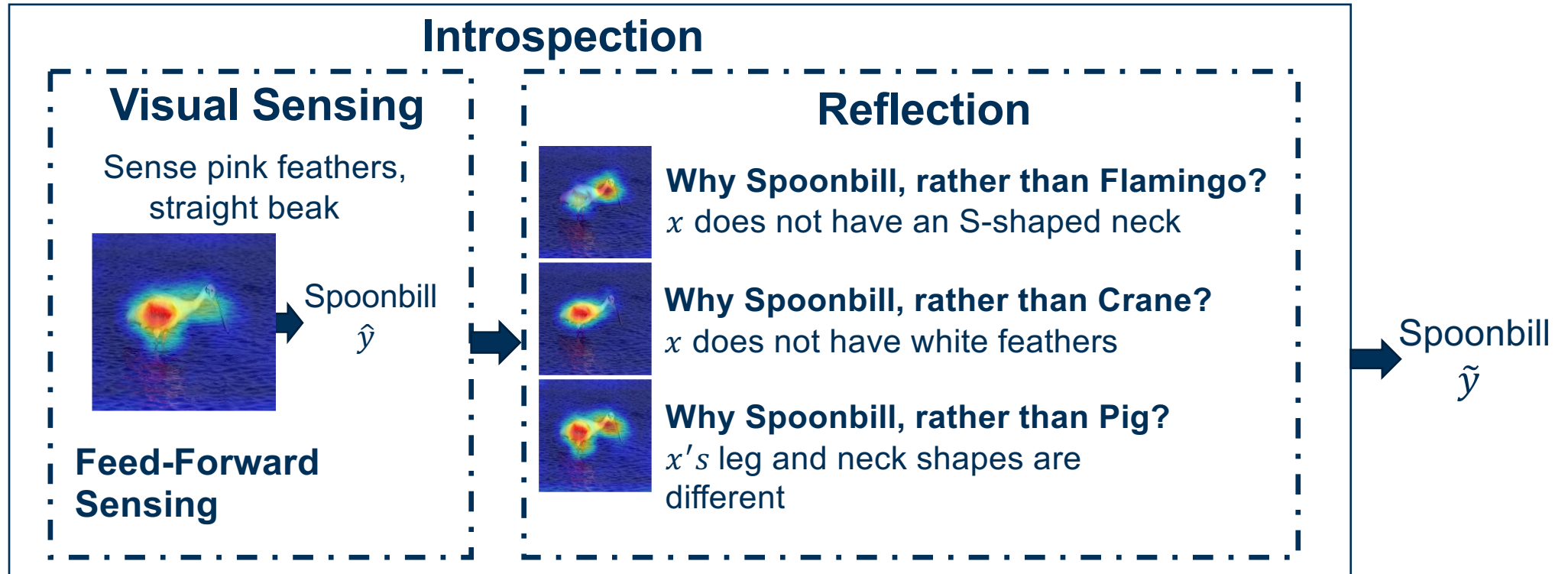
Introspection

What is Introspection?



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Introspection Learning is a two-stage approach for Inference that combines visual sensing and reflection



Introspection

Introspection in Neural Networks



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Introspection Learning is a two-stage approach for Inference that combines visual sensing and reflection

Goal : To simulate Introspection in Neural Networks

Definition : We define introspections as answers to logical and targeted questions.

What are the possible targeted questions?

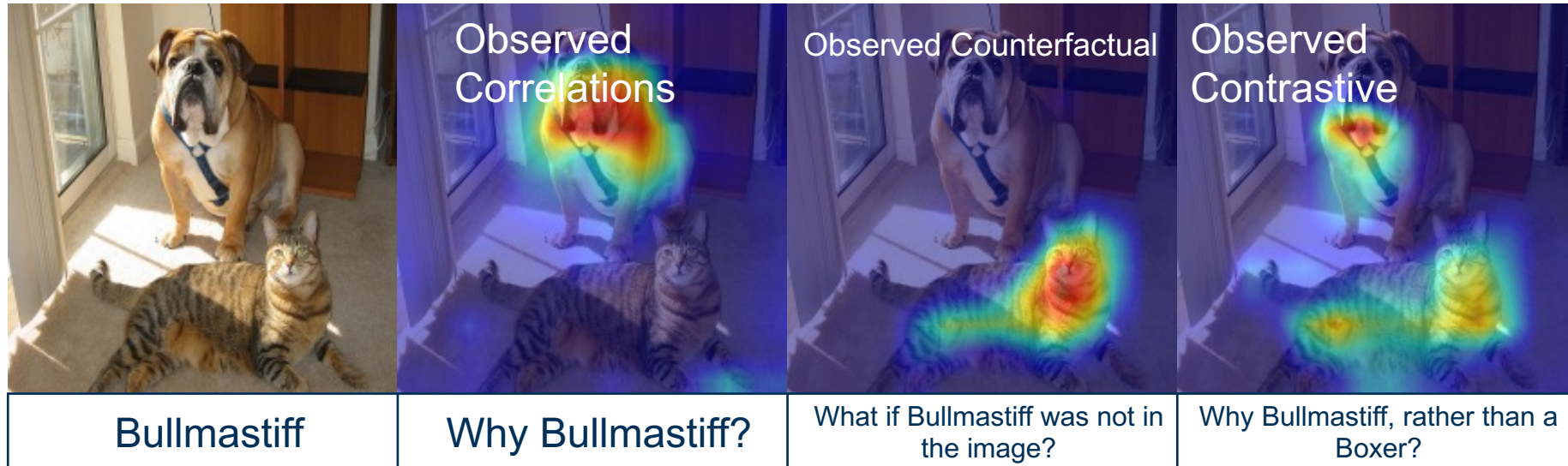
Introspection

Introspection in Neural Networks



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Introspection Learning is a two-stage approach for Inference that combines visual sensing and reflection



What are the possible targeted questions?

Introspection

Introspection in Neural Networks



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Introspection Learning is a two-stage approach for Inference that combines visual sensing and reflection

Goal : To simulate Introspection in Neural Networks

***Contrastive Definition :** Introspection answers questions of the form 'Why P , rather than Q ?' where P is a network prediction and Q is the introspective class.*

***Technical Definition :** Given a network $f(x)$, a datum x , and the network's prediction $f(x) = \hat{y}$, introspection in $f(\cdot)$ is the measurement of change induced in the network parameters when a label Q is introduced as the label for x .*

Introspection

Gradients as Features

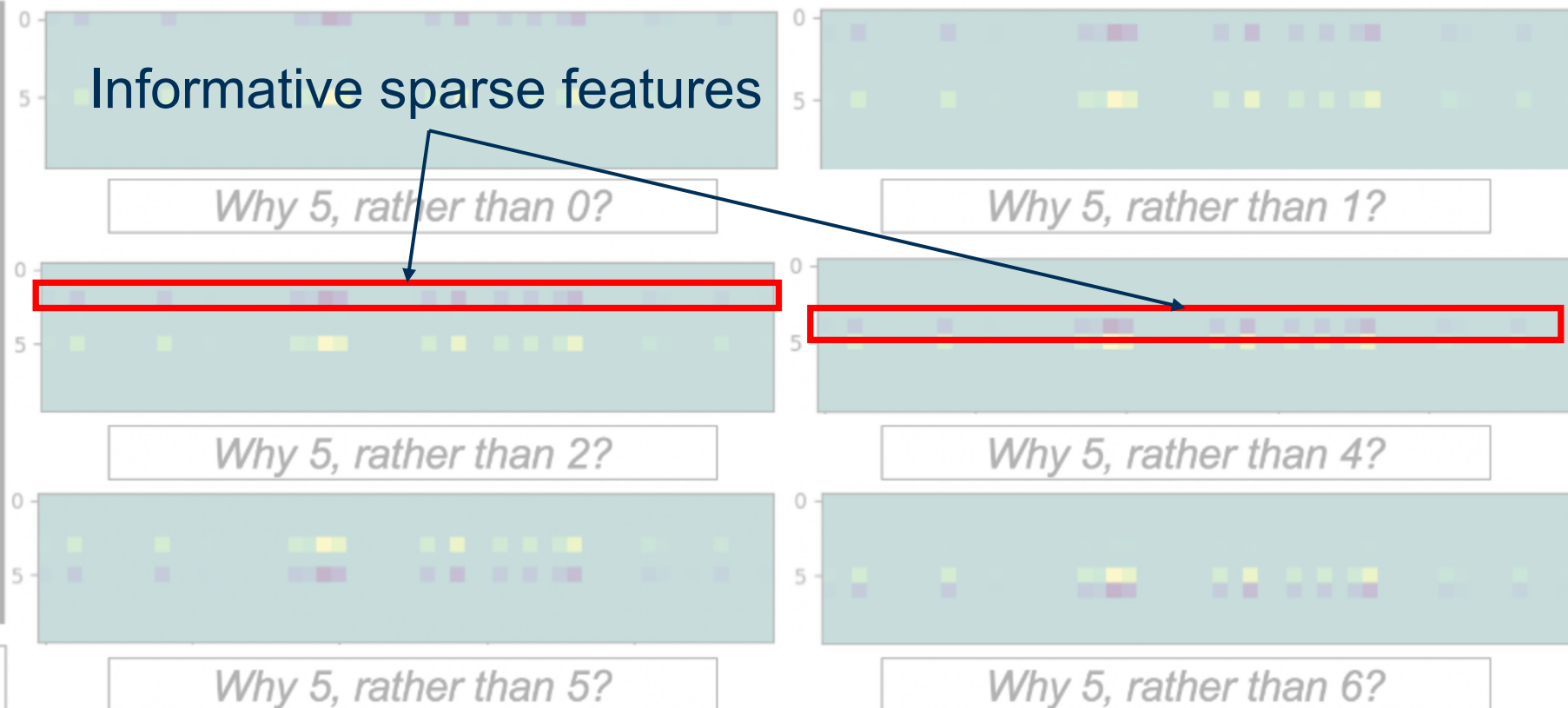


Introspective Learning: A Two-stage Approach for Inference in Neural Networks

For a well-trained network, the gradients are sparse and informative



Input Image x



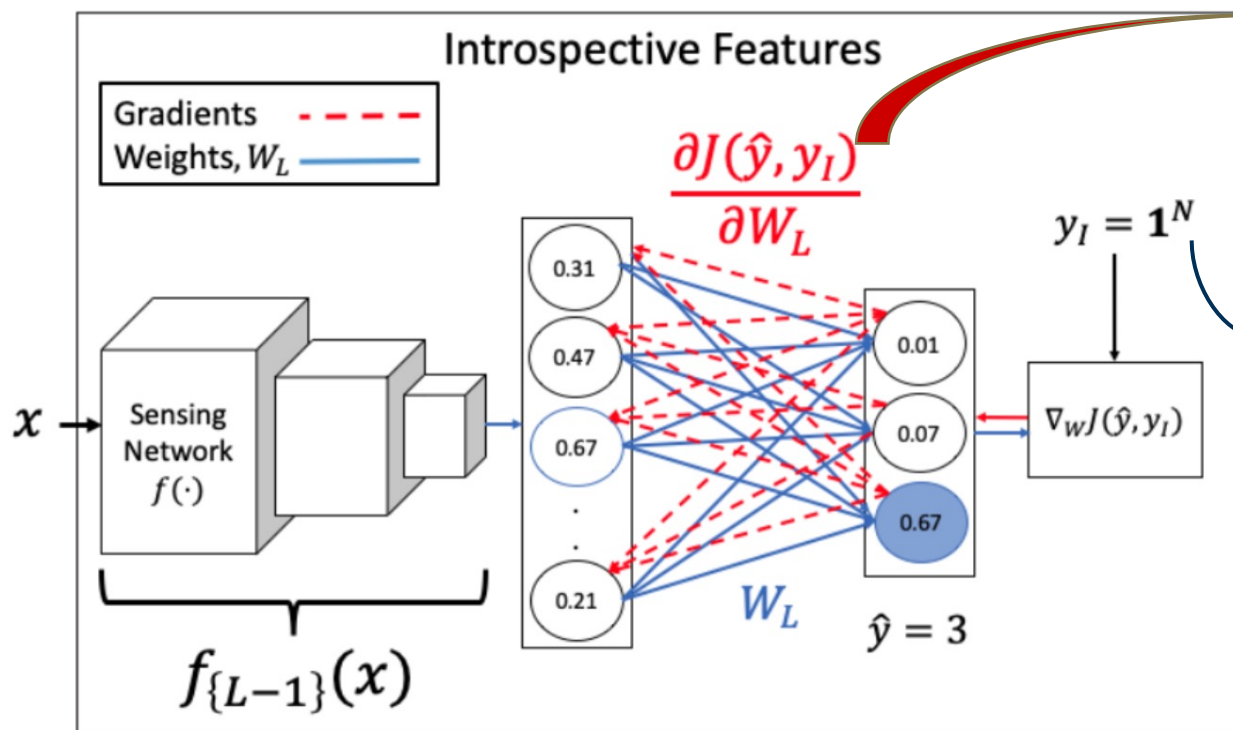
Introspection

Deriving Gradient Features



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Measure the loss between the prediction \hat{y} and a vector of all ones and backpropagate to obtain the introspective features



Normalized and vectorized gradients are introspective features

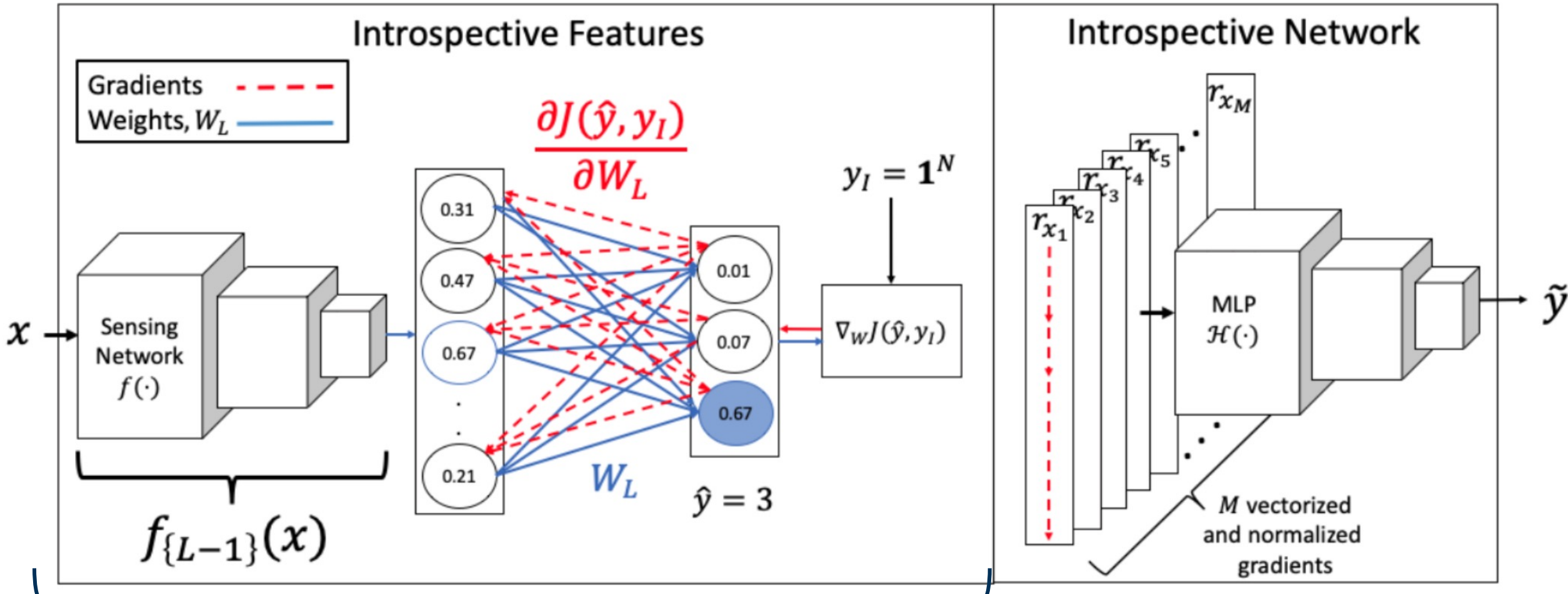
Vector of all ones: A confounding label!

Introspection

Utilizing Gradient Features



Introspective Learning: A Two-stage Approach for Inference in Neural Networks



Introspective Features

Introspection

When is Introspection Useful?



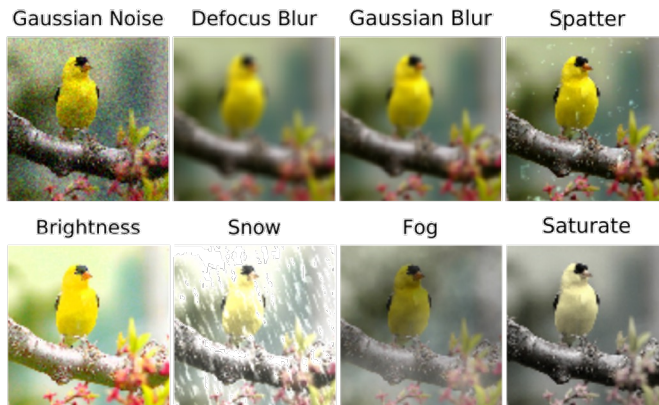
Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Introspection provides robustness when the train and test distributions are different

We define robustness as being generalizable and calibrated to new testing data

Generalizable: Increased accuracy on OOD data

Calibrated: Reduces the difference between prediction accuracy and confidence



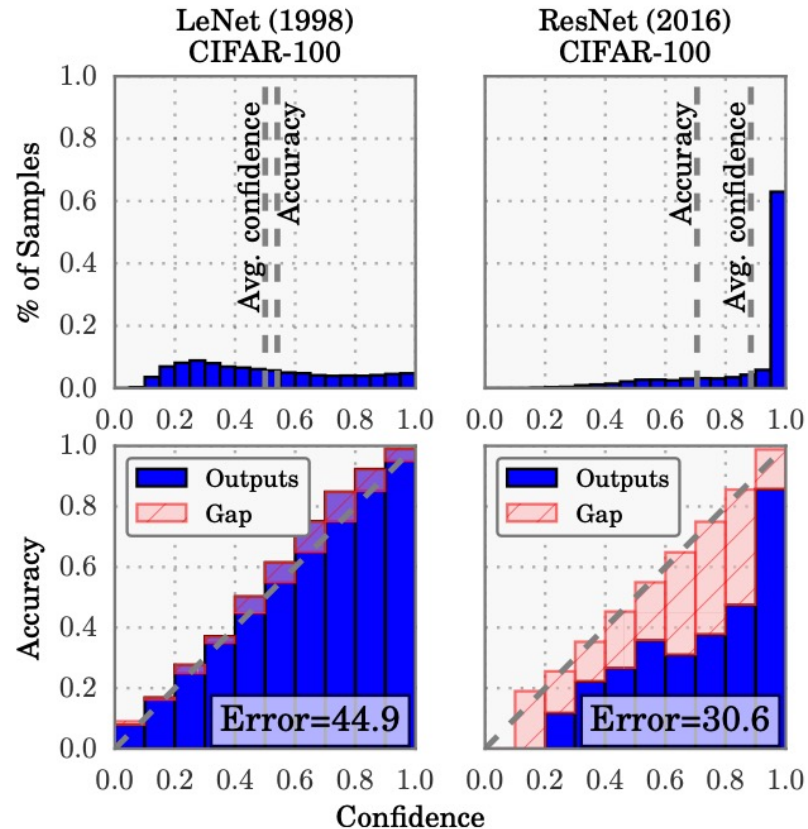
Calibration

A note on Calibration..



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Calibration occurs when there is mismatch between a network's confidence and its accuracy



- Larger the model, more misplaced is a network's confidence
- On ResNet, the gap between prediction accuracy and its corresponding confidence is significantly high

Introspection in Neural Networks

Generalization and Calibration results

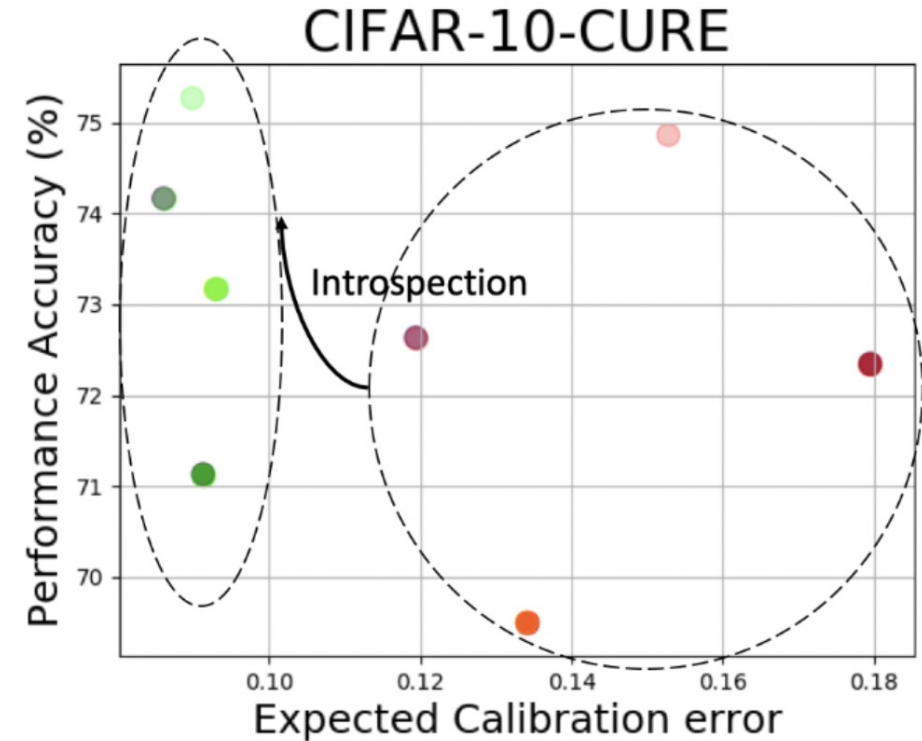
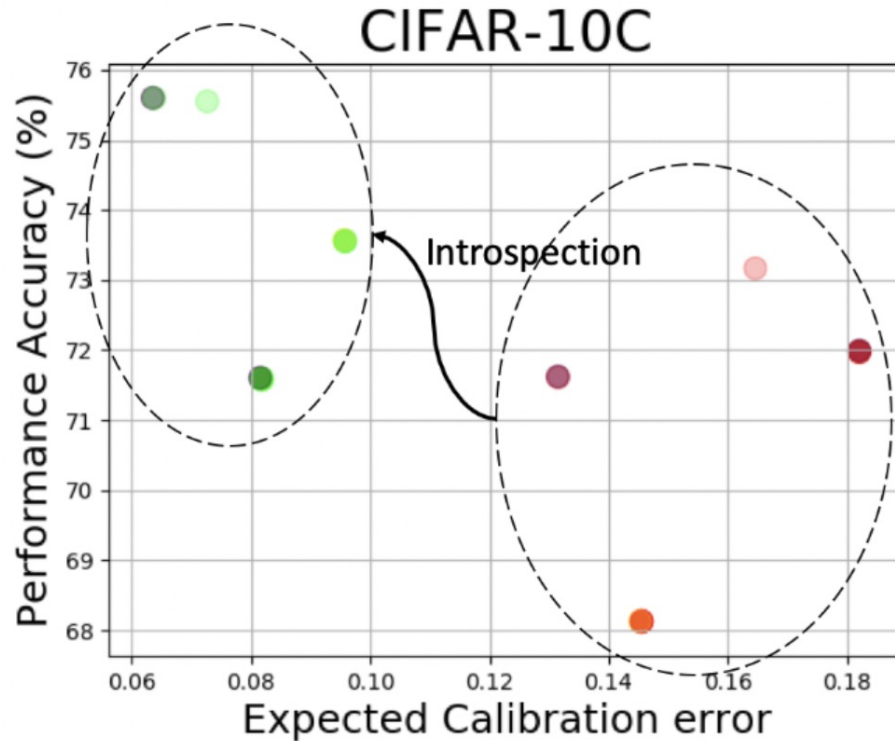


Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Ideal: Top-left corner

Y-Axis: Generalization

X-Axis: Calibration



Legend

Feed-Forward Networks	● ResNet-18	● ResNet-34	● ResNet-50	● ResNet-101
After Introspection	● ResNet-18	● ResNet-34	● ResNet-50	● ResNet-101

Introspection in Neural Networks

Plug-in nature of Introspection



Introspective Learning: A Two-stage Approach for Inference in Neural Networks

Introspection is a light-weight option to resolve robustness issues

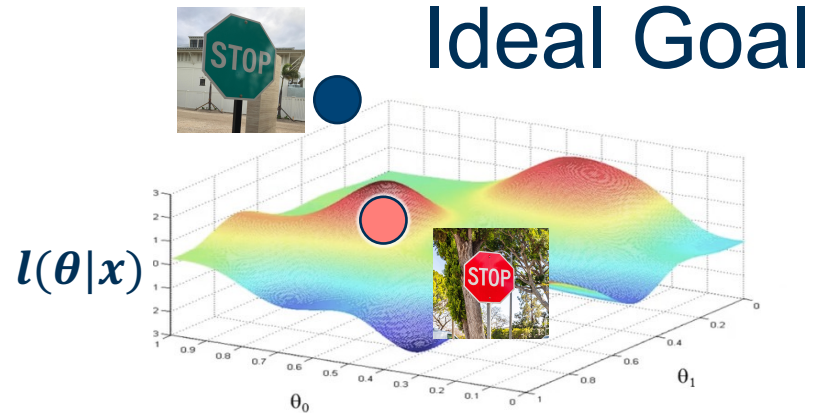
Table 1: Introspecting on top of existing robustness techniques.

METHODS		ACCURACY
RESNET-18	FEED-FORWARD	67.89%
	INTROSPECTIVE	71.4%
DENOISING	FEED-FORWARD	65.02%
	INTROSPECTIVE	68.86%
ADVERSARIAL TRAIN (27)	FEED-FORWARD	68.02%
	INTROSPECTIVE	70.86%
SIMCLR (19)	FEED-FORWARD	70.28%
	INTROSPECTIVE	73.32%
AUGMENT NOISE (23)	FEED-FORWARD	76.86%
	INTROSPECTIVE	77.98%
AUGMIX (24)	FEED-FORWARD	89.85%
	INTROSPECTIVE	89.89%

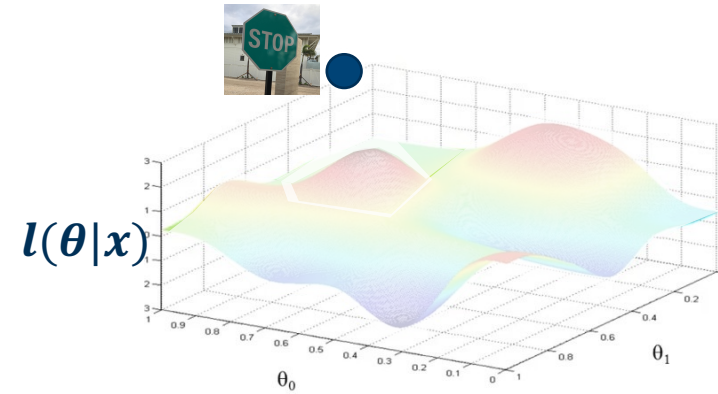
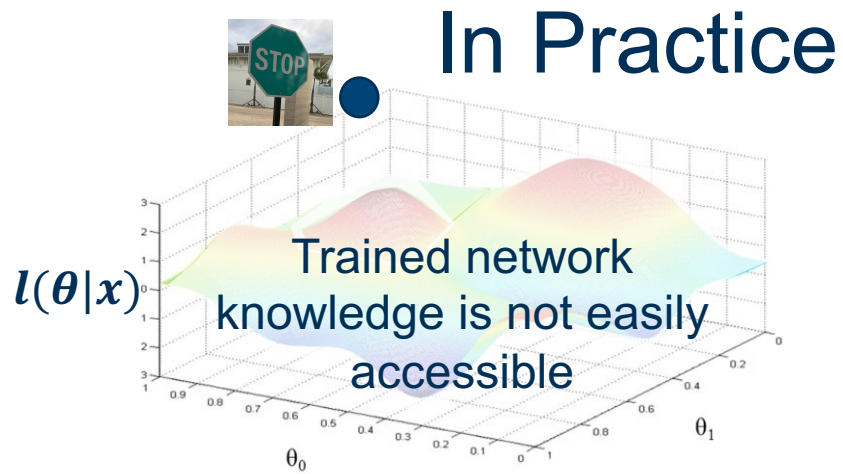
Introspection is a **plug-in approach** that works on all networks and on any downstream task!

Part I, II and III

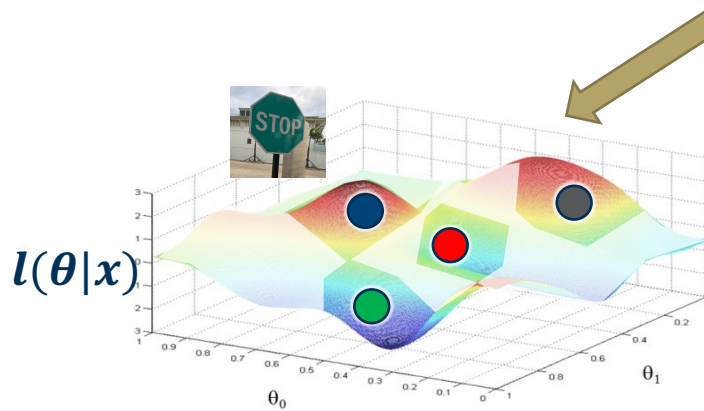
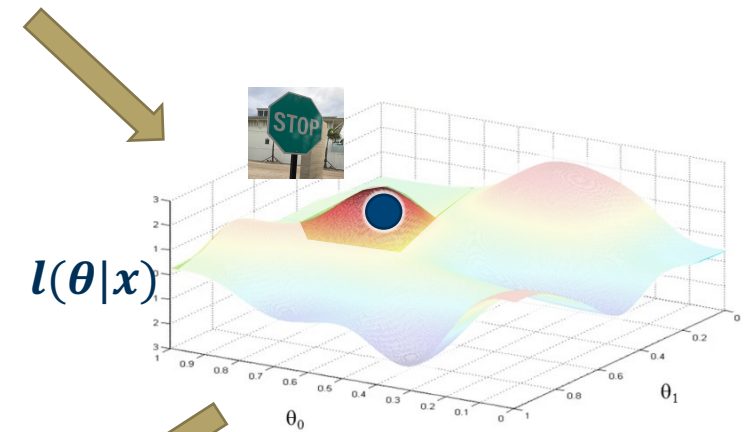
Tying it Back



From Part I



Novel data projects onto the likelihood function (however incorrectly), and extracts fisher information around the projection



By backpropagating contrast classes (and not updating the network), the network finds the steepest descent towards other regions of likelihood function

Robust Neural Networks

Part 4: Intervenability at Inference

Objective

Objective of the Tutorial

To discuss methodologies that promote robustness in neural networks at inference

- Part 1: Inference in Neural Networks
- Part 2: Explainability at Inference
- Part 3: Uncertainty at Inference
- **Part 4: Intervenability at Inference**
 - Definitions of Intervenability
 - Causality
 - Privacy
 - Interpretability
 - Prompting
 - Benchmarking
 - Case Study: Intervenability in Interpretability
- Part 5: Conclusions and Future Directions

Intervenability

Through the Causal Glass

Assess: The amenability of neural network decisions to human interventions



“Interventions in data are manipulations that are designed to test for causal factors”

Intervenability

Through the Privacy Glass

Assure: The amenability of neural network decisions to human interventions



*“Intervenability aims at the possibility for parties involved in any **privacy-relevant** data processing to **interfere** with the ongoing or planned data processing”*

Intervenability

Through the Interpretability Glass

Interpret: The amenability of neural network decisions to human interventions



*“The post-hoc field of explainability, that previously only justified decisions, becomes **active** by being involved in the decision making process and **providing limited, but relevant and contextual interventions**”*

Intervenability

Through the Benchmarking Glass

Verify: The amenability of neural network decisions to human interventions



*“... new **benchmarks** were proposed to specifically test generalization of classification and detection methods with respect to **simple** algorithmically generated interventions like spatial shifts, blur, changes in brightness or contrast...”*

Intervenability

Through the Human Glass

The amenability of neural network decisions to human interventions



- **Assess: Causality**
- **Assure: Privacy**
- **Interpret: Interpretability**
- **Verify: Benchmarking**

Case Study: Intervenability in Interpretability

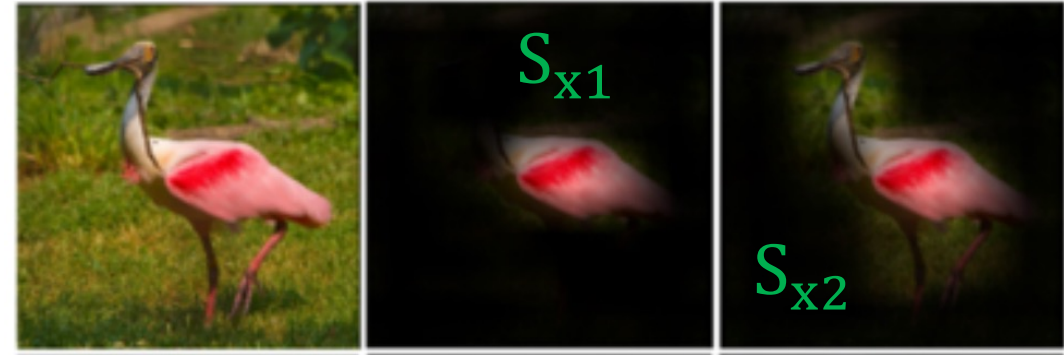
Explanation Evaluation via Masking

Common evaluation technique is masking the image and checking for prediction correctness

y = Prediction

S_x = Explanation masked data

$E(Y|S_x)$ = Expectation of class given S_x



If across N images,
 $E(Y|S_{x2}) > E(Y|S_{x1})$,
explanation technique 2
is better than explanation
technique 1



VOICE: Variance of Contrastive Explanations for Quantifying Uncertainty in Interpretability



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Case Study: Intervenability in Interpretability

Predictive Uncertainty in Explanations

Explanatory techniques have predictive uncertainty

Explanation of Prediction

Uncertainty of Explanation



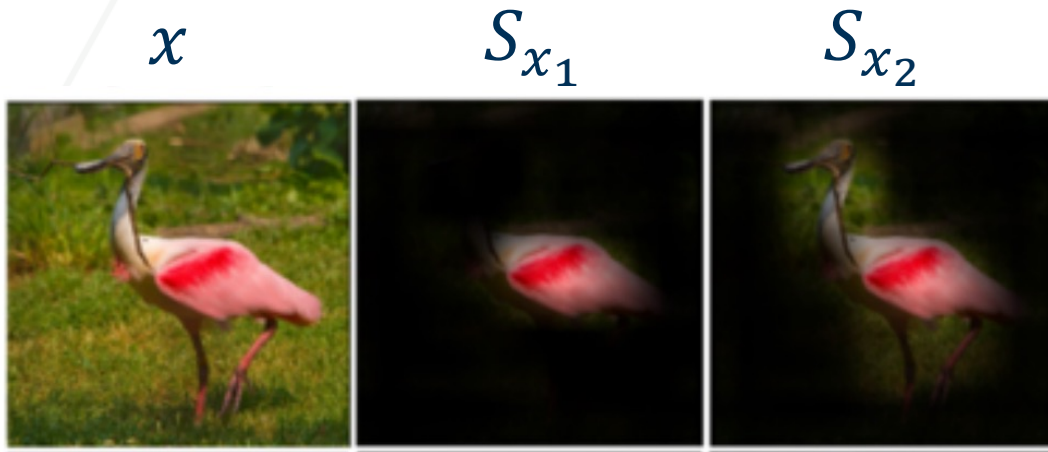
Why Bullmastiff?

Uncertainty in answering
Why Bullmastiff?

Case Study: Intervenability in Interpretability

Predictive Uncertainty

Uncertainty due to variance in prediction when model is kept constant



$$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$$

y = Prediction

$V[y]$ = Variance of prediction (Predictive Uncertainty)

S_x = Subset of data (Some intervention)

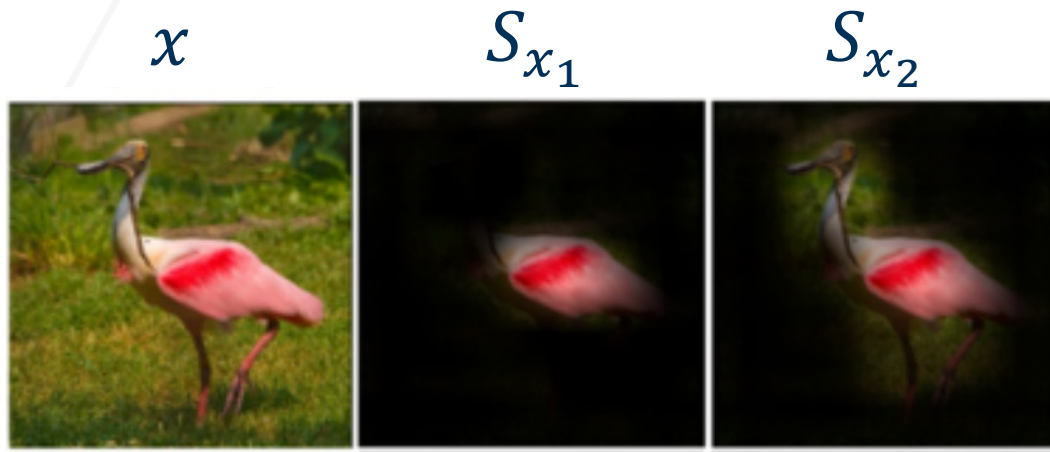
$E(Y|S_x)$ = Expectation of class given a subset

$V(Y|S_x)$ = Variance of class given all other residuals

Case Study: Intervenability in Interpretability

Visual Explanations (partially) reduce Predictive Uncertainty

A 'good' explanatory technique is evaluated to have zero $V[E(y|S_x)]$



zero ←

$$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$$

y = Prediction

$V[y]$ = Variance of prediction (Predictive Uncertainty)

S_x = Subset of data (Some intervention)

$E(Y|S_x)$ = Expectation of class given a subset

$V(Y|S_x)$ = Variance of class given all other residuals

Key Observation 1: Visual Explanations are evaluated to partially reduce the predictive uncertainty in a neural network

Network evaluations have nothing to do with human Explainability!

Case Study: Intervenability in Interpretability

Predictive Uncertainty in Explanations is the Residual

All other subsets 'not' chosen by the explanatory technique contributes to uncertainty



$$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$$

y = Prediction

$V[y]$ = Variance of prediction (Predictive Uncertainty)

S_x = Subset of data (Some intervention)

$E(Y|S_x)$ = Expectation of class given a subset

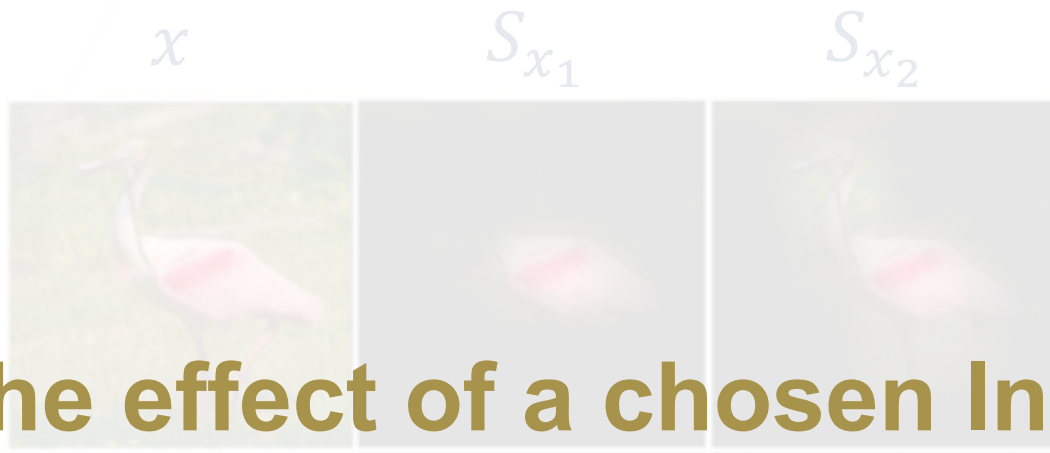
$V(Y|S_x)$ = Variance of class given all other residuals

Key Observation 2: Uncertainty in Explainability occurs due to all combinations of features that the explanation did not attribute to the network's decision

Case Study: Intervenability in Interpretability

Predictive Uncertainty in Explanations is the Residual

All other subsets 'not' chosen by the explanatory technique contributes to uncertainty



$$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$$

The effect of a chosen Interventions can be measured based on *all the Interventions that were not chosen*

Key Observation 2: Uncertainty in Explainability occurs due to all combinations of features that the explanation did not attribute to the network's decision

Case Study: Intervenability in Interpretability

Predictive Uncertainty in Explanations is the Residual

All other subsets 'not' chosen by the explanatory technique contributes to uncertainty

Explanation of Prediction Uncertainty of Explanation



Snout is not as highlighted as the jowls in explanation (not as important for decision)

However, snout is an important characteristic that is used to differentiate against other dogs. Hence, there is uncertainty on why this feature is not included in the attribution

Key Observation 2: Uncertainty in Explainability occurs due to all combinations of features that the explanation did not attribute to the network's decision

Case Study: Intervenability in Interpretability

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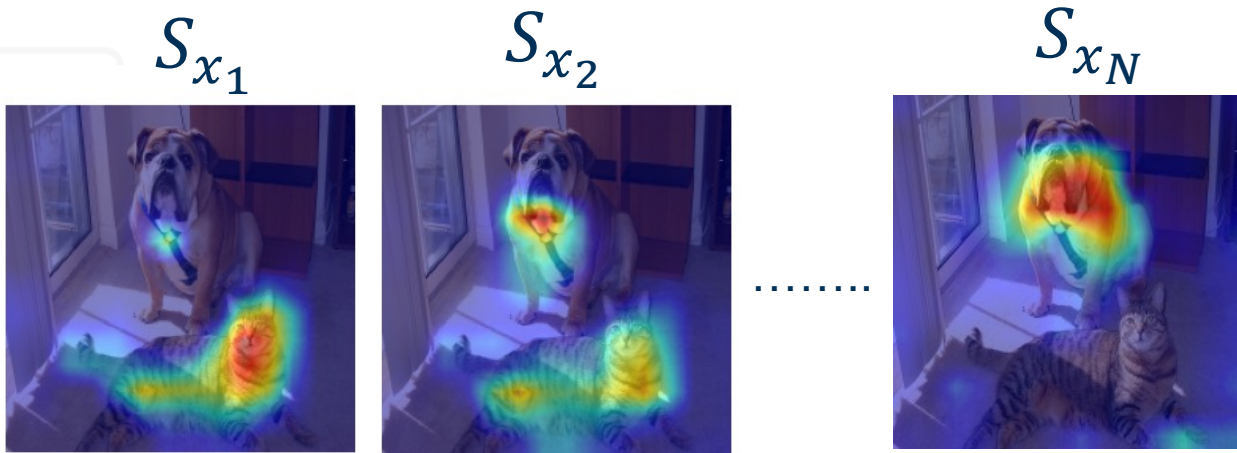
However, snout is an important characteristic that is used to differentiate against other dogs. Hence, there is uncertainty on why this feature is not included in the attribution

Not chosen features are intractable!

Case Study: Intervenability in Interpretability

Quantifying Interventions in Explainability

Contrastive explanations are an intelligent way of obtaining other subsets



$$V[y|S_x] = V[E(y|S_x)] + E(V[y|S_x])$$

Make it finite by only considering the subsets that change y

$$\left. \begin{array}{l} Y_1|S_{x1} \\ Y_2|S_{x2} \\ Y_3|S_{x3} \\ Y_4|S_{x4} \\ Y_5|S_{x5} \\ \cdot \\ \cdot \\ Y_N|S_{xN} \end{array} \right\} \text{Variance}$$

Case Study: Intervenability in Interpretability

Quantifying Interventions in Explainability

Uncertainty in Explainability can be used to analyze Explanatory methods and Networks

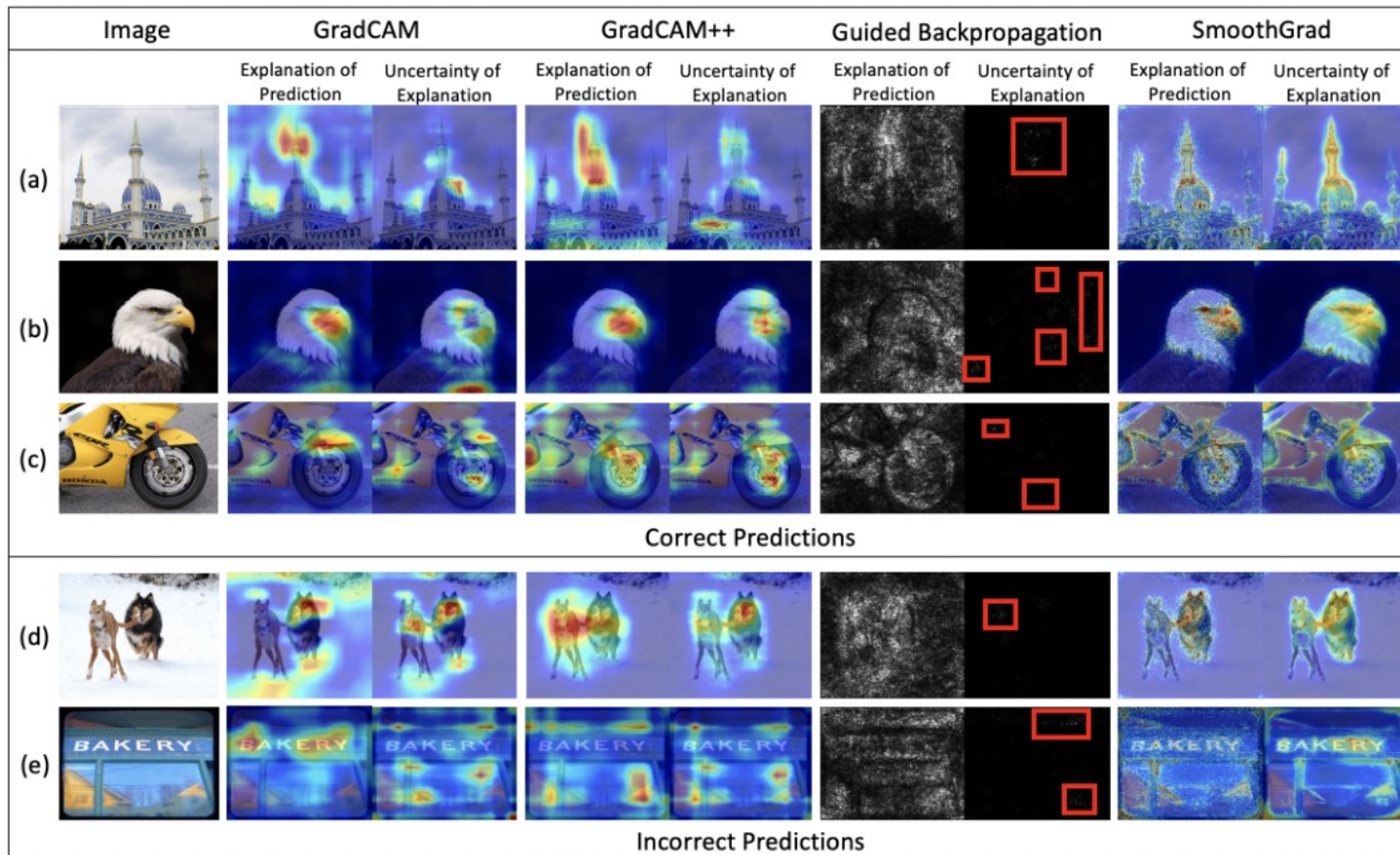
- Is GradCAM better than GradCAM++?
- Is a SWIN transformer more reliable than VGG-16?

Need objective quantification of Intervention Residuals

Case Study: Intervenability in Interpretability

Quantifying Interventions in Explainability: mIOU

On incorrect predictions, the overlap of explanations and uncertainty is higher



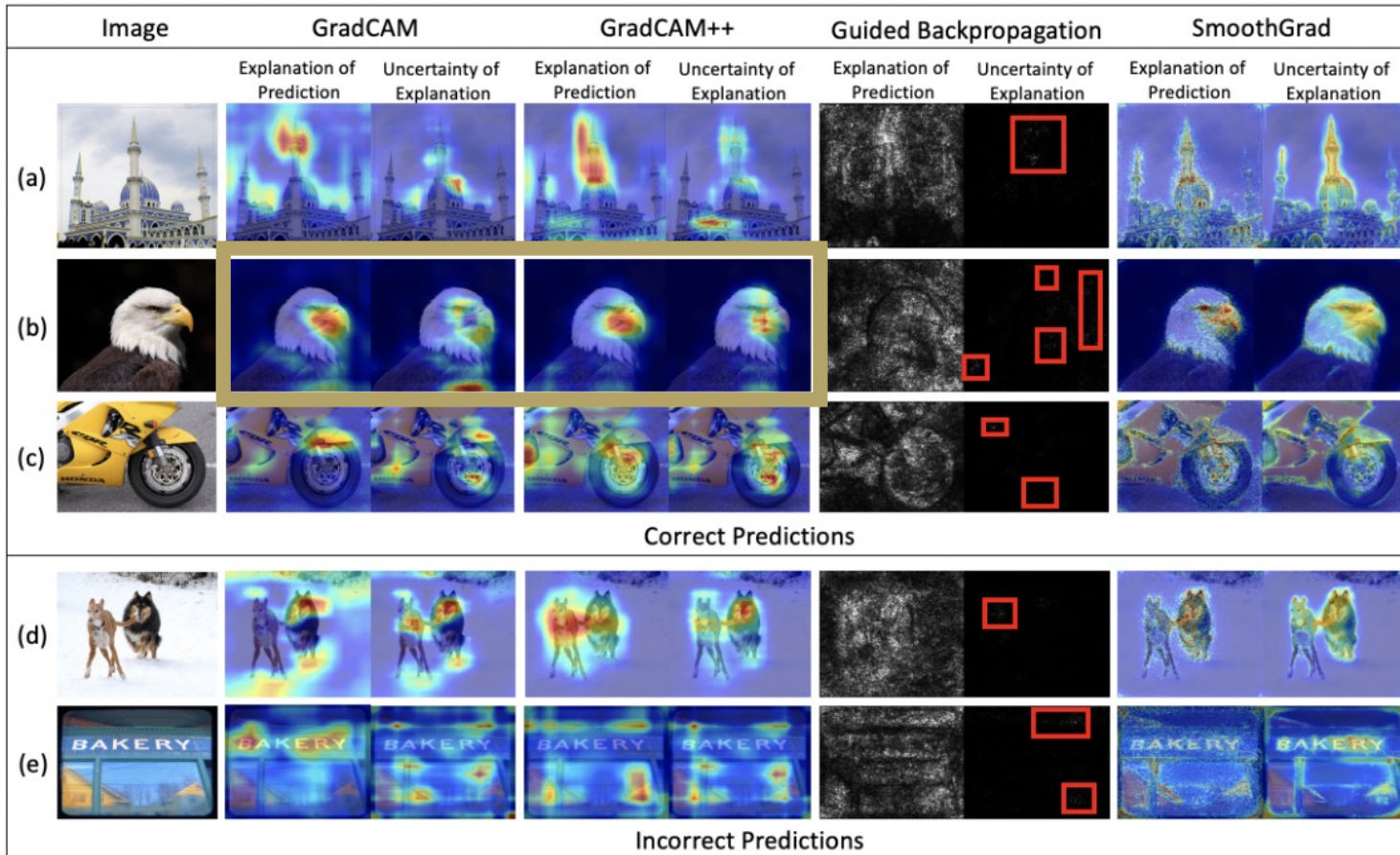
Objective Metric:
Intersection over Union (IoU)
between
explanation and
Uncertainty

Higher the IoU, higher the
uncertainty in explanation (or
less trustworthy is the
prediction)

Case Study: Intervenability in Interpretability

Quantifying Interventions in Explainability: mIOU

On incorrect predictions, the overlap of explanations and uncertainty is higher



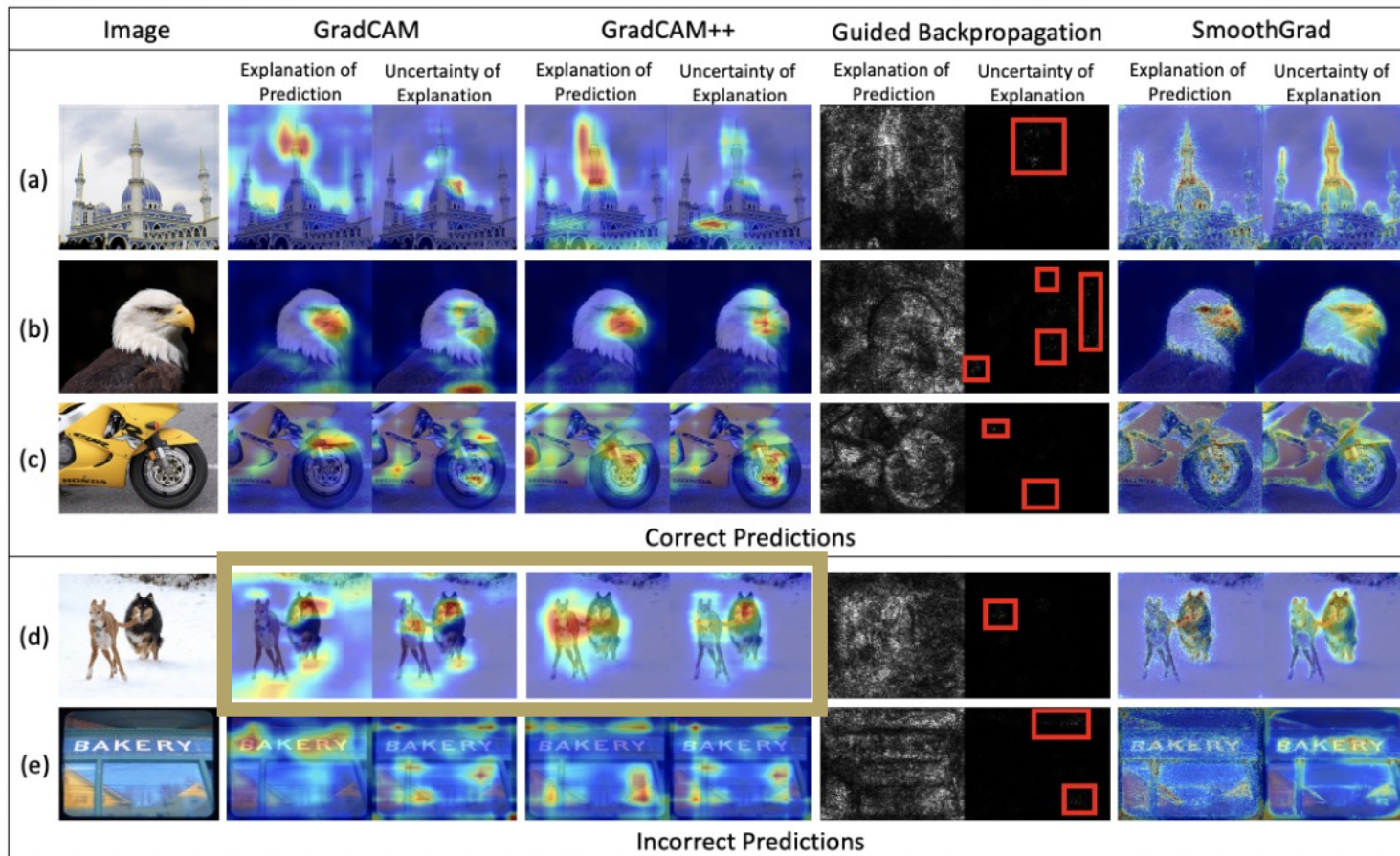
Objective Metric 1:
Intersection over Union (IoU)
between
explanation and
Uncertainty

Higher the IoU, higher the
uncertainty in explanation (or
less trustworthy is the
prediction)

Case Study: Intervenability in Interpretability

Quantifying Interventions in Explainability: mIOU

On incorrect predictions, the overlap of explanations and uncertainty is higher



Objective Metric 1:
Intersection over Union (IoU)
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Higher the IoU, higher the
uncertainty in explanation (or
less trustworthy is the
prediction)

Robust Neural Networks

Part 5: Conclusions and Future Directions

Key Takeaways

Role of Gradients

- **Robustness** under distributional shift in domains, environments, and adversaries are **challenges** for neural networks
 - **Gradients at Inference** provide a **holistic solution** to the above challenges
- **Gradients** can help **traverse** through a trained and unknown **manifold**
 - They approximate **Fisher Information** on the projection
 - They can be **manipulated** by providing **contrast** classes
 - They can be used to construct **localized contrastive** manifolds
 - They provide **implicit knowledge** about **all classes**, when only **one data** point is available at inference
- Gradients are useful in a number of **Image Understanding** applications
 - Highlighting features of the current prediction as well as **counterfactual** data and **contrastive** classes
 - Providing **directional information** in anomaly detection
 - **Quantifying uncertainty** for out-of-distribution, corruption, and adversarial detection
 - Providing **expectancy mismatch** for human vision related applications

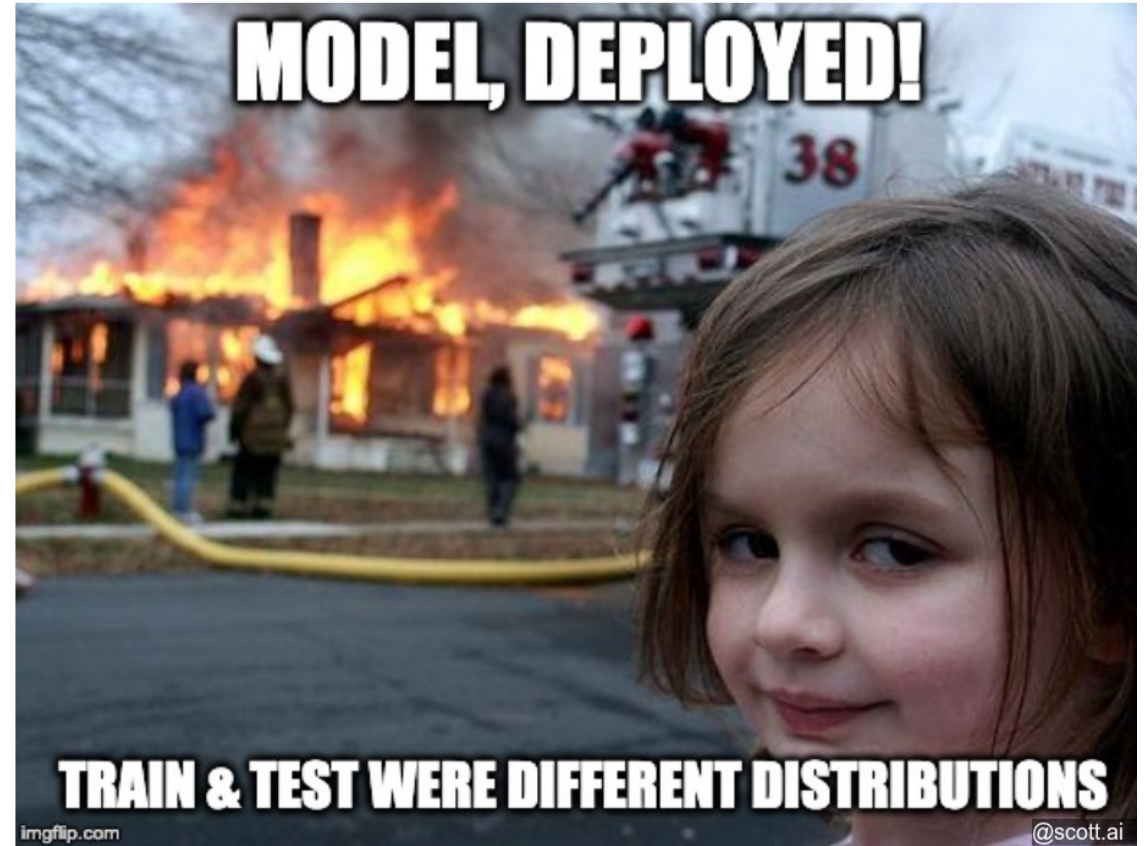
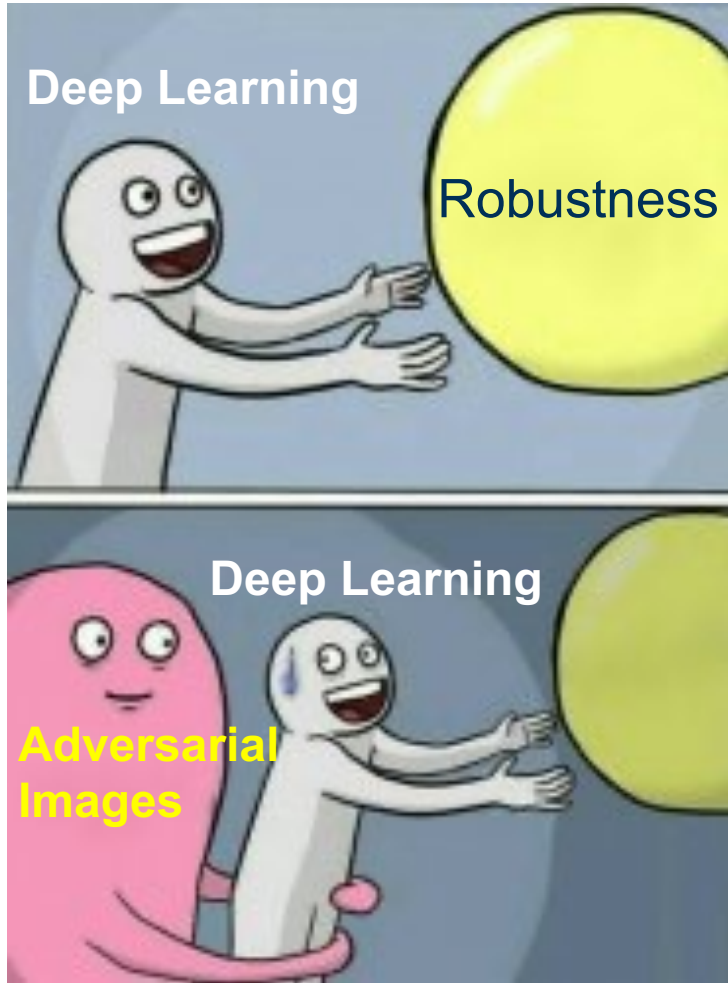
Future Directions

Research at Inference Stage

- **Test Time Augmentation (TTA) Research**
 - Multiple augmentations of data are passed through the network at inference
 - Research is in designing the best augmentations
- **Active Inference**
 - Utilize the knowledge in Neural Networks to *ask it to ask us*
 - Neural networks ask for the best augmentation of the data point given that one data point at inference
- **Uncertainty in Explainability, Label Interpretation, and Trust quantification**
 - Uncertainty research has to expand beyond model and data uncertainty
 - In some applications within medical and seismic communities, there is no agreed upon label for data. Uncertainty in label interpretation is its own research
- **Test-time Interventions for AI alignment**
 - Human interventions at test time to alter the decision-making process is essential trustworthy AI
 - Further research in intelligently involving experts in a non end-to-end framework is required

Mememes to Wrap it Up

Robustness at Inference



Cannot depend on training to construct robust models

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IEEE BigData 2023 Tutorial



<https://alregib.ece.gatech.edu/ieee-bigdata-2023-tutorial/>
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