Statistical Adjustments to Engineering Models

V. Roshan Joseph and Shreyes N. Melkote

JQT, October, 2009

Supported by NSF CMMI-0654369





Model-based Quality Improvement

- Models are used for
 - Process control
 - Process optimization

- Two types of models
 - Statistical models
 - Engineering models





Statistical Models

- Statistical models
 - Developed based on data
 - Linear/nonlinear regression models





Engineering Models

- Engineering models
 - Developed based on engineering/physical laws
 - Analytical and finite element models





Engineering Models Vs Statistical Models

- Statistical models
 - Predictions are good closer to the data, but can be poor when made away from data
- Engineering models
 - Physically meaningful predictions, but often are not accurate because of the assumptions
- Can we integrate them to produce better models?





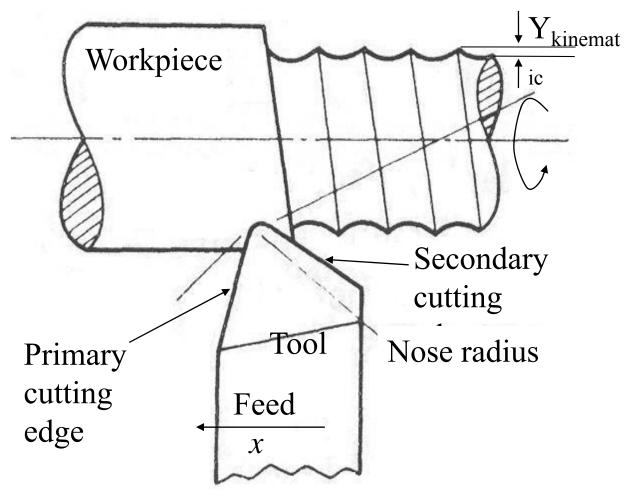
Engineering - Statistical Models

- Improve engineering models using data
 - More realistic predictions than engineering models
 - Less expensive than pure statistical models (fewer data)





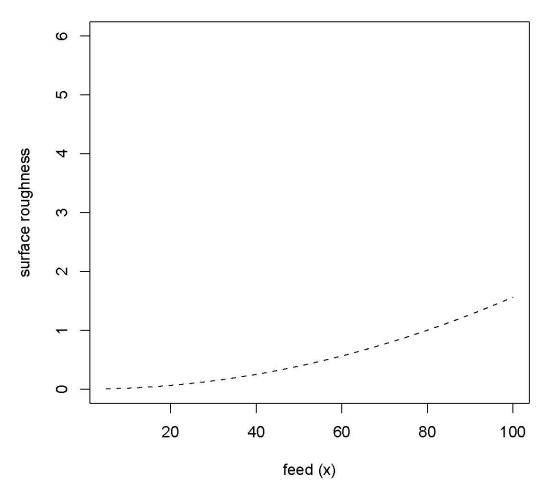
Surface Roughness Prediction in Micro-Turning





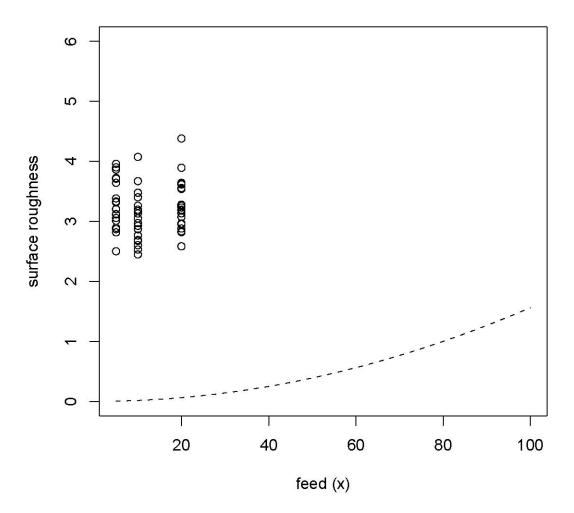


Engineering model: $Y_{kinematic} = \frac{x^2}{8r}$





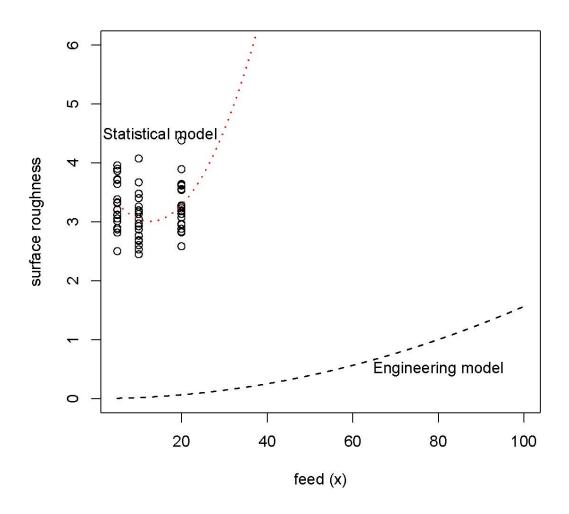






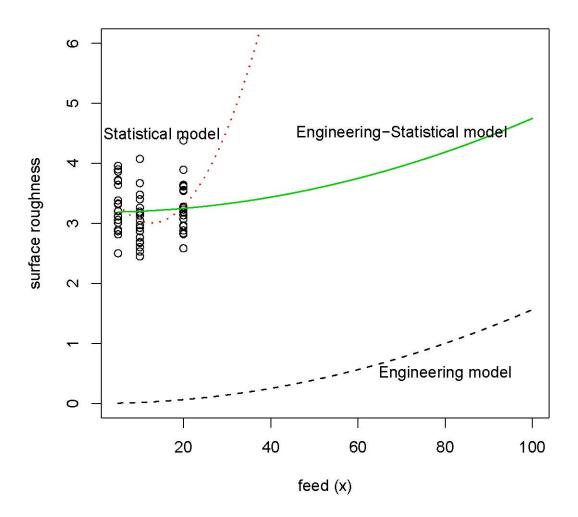


Statistical model: $Y = \beta_0 + \beta_1 x + \beta_2 x^2$



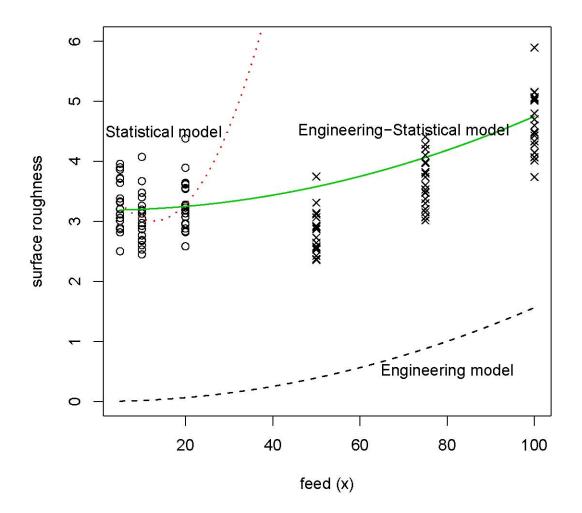
















Existing methods

- Mechanistic model calibration
 - Estimate unknown parameters (calibration parameters) from data
 - Box, Hunter, Hunter (1978), Kapoor et al. (1998)
 - Not a general method
- Bayesian calibration
 - Kennedy and O'Hagan (2001)
 - Reese et al. (2004), Higdon et al. (2004), Bayarri et al. (2007), Qian and Wu (2008).



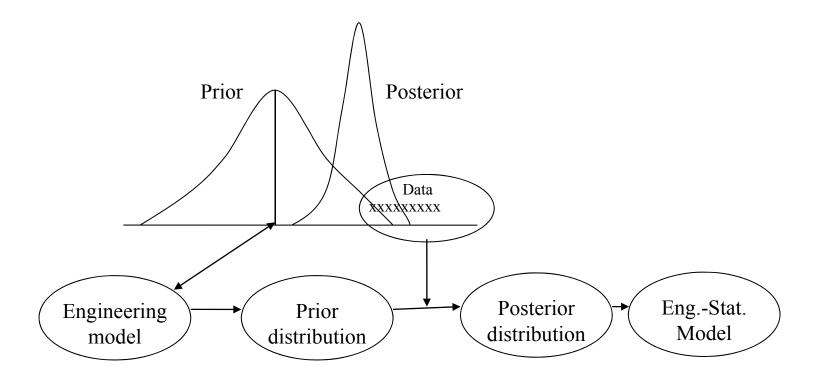


Bayesian Methodology

- Take engineering model as the prior mean
- Get data from the physical experiment
- Obtain posterior distribution
- Engineering-Statistical model is the posterior mean











Methodology-continued

- Output: $\mathbf{x} = (x_1, \dots, x_p)'$
- Random error: $\epsilon \sim \mathcal{N}(0, \sigma^2)$

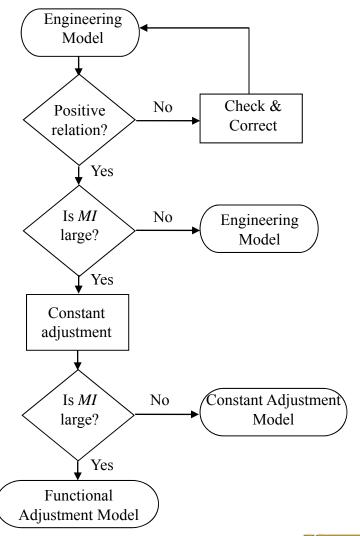
$$Y = \mu(\boldsymbol{x}) + \epsilon$$

- Objective: Find $\mu({m x})$
- Engineering model: $f({m x};{m \eta})$
- Calibration parameters: $oldsymbol{\eta} = (\eta_1, \cdots, \eta_a)'$
- Data: $(\boldsymbol{x}_1,y_1),\ \ldots,\ (\boldsymbol{x}_n,y_n)$





Sequential Model Building







Methodology-continued

- Check the usefulness of engineering model using graphical analysis
- If it is useful

$$MI = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{\mu}_i^E)^2$$

 If MI is small, then stop. Engineering model is good.





Constant adjustment model

$$\mu(\boldsymbol{x}) - f(\boldsymbol{x}) = \beta_0 + \beta_1 (f(\boldsymbol{x}) - \bar{f})$$

$$MI = \frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{\mu}_i^C)^2$$

• If MI is small, then stop. CAM is good.





Functional adjustment model

$$\mu(\boldsymbol{x}) - \mu^{C}(\boldsymbol{x}) = \delta(\boldsymbol{x}; \boldsymbol{\alpha})$$

$$\delta(\boldsymbol{x}; \boldsymbol{\alpha}) = \sum_{i=0}^{m} \alpha_i u_i(\boldsymbol{x})$$

Add terms until MI is small enough.





Constant adjustment model

$$Y - f(\boldsymbol{x}) = \beta_0 + \beta_1 (f(\boldsymbol{x}) - \bar{f}) + \epsilon$$

$$\epsilon \sim \mathcal{N}(0, \sigma^2), \, \beta_0 \sim \mathcal{N}(0, \tau_0^2), \, \beta_1 \sim \mathcal{N}(0, \tau_1^2)$$

$$m{y} - m{f} = m{F}m{eta} + m{\epsilon}, \;\; m{\epsilon} \sim \mathcal{N}(m{0}, \sigma^2 m{I})$$
 $m{eta} \sim \mathcal{N}(m{0}, m{\Sigma})$





Posterior distribution

• posterior distribution is

$$\boldsymbol{\beta}|\boldsymbol{y} \sim \mathcal{N}\left((\boldsymbol{F}'\boldsymbol{F} + \sigma^2\boldsymbol{\Sigma}^{-1})^{-1}\boldsymbol{F}'(\boldsymbol{y} - \boldsymbol{f}), \ \sigma^2(\boldsymbol{F}'\boldsymbol{F} + \sigma^2\boldsymbol{\Sigma}^{-1})^{-1}\right)$$

constant adjustment predictor is

$$\hat{\mu}^{C}(\boldsymbol{x}) = f(\boldsymbol{x}) + \hat{\beta}_{0} + \hat{\beta}_{1}(f(\boldsymbol{x}) - \bar{f})$$

Prediction interval

$$\hat{\mu}^{C}(\mathbf{x}) \pm z_{\alpha/2}\sigma \left\{ 1 + \frac{1}{n + \sigma^{2}/\tau_{0}^{2}} + \frac{(f(\mathbf{x}) - \bar{f})^{2}}{S + \sigma^{2}/\tau_{1}^{2}} \right\}^{1/2}$$





Simplification

least squares estimate

$$\tilde{\beta}_0 = \bar{y} - \bar{f}$$
 and $\tilde{\beta}_1 = \sum_{i=1}^n (y_i - f_i)(f_i - \bar{f})/S$

$$S = \sum_{i=1}^{n} (f_i - \bar{f})^2$$

$$\hat{\beta}_0 = \frac{\tau_0^2}{\tau_0^2 + \sigma^2/n} \tilde{\beta}_0 \text{ and } \hat{\beta}_1 = \frac{\tau_1^2}{\tau_1^2 + \sigma^2/S} \tilde{\beta}_1$$





Empirical Bayes estimation

Estimate hyperparameters by maximizing

$$l = -\frac{1}{2}\log\det(\mathbf{F}\boldsymbol{\Sigma}\mathbf{F}' + \sigma^2\mathbf{I}) - \frac{1}{2}(\mathbf{y} - \mathbf{f})'(\mathbf{F}\boldsymbol{\Sigma}\mathbf{F}' + \sigma^2\mathbf{I})^{-1}(\mathbf{y} - \mathbf{f})$$

$$\hat{\tau}_0^2 = (\tilde{\beta}_0^2 - \sigma^2/n)_+ \text{ and } \hat{\tau}_1^2 = (\tilde{\beta}_1^2 - \sigma^2/S)_+$$

$$\hat{\beta}_0 = \left(1 - \frac{1}{z_0^2}\right)_+ \tilde{\beta}_0 \text{ and } \hat{\beta}_1 = \left(1 - \frac{1}{z_1^2}\right)_+ \tilde{\beta}_1,$$

$$z_0 = \frac{|\tilde{\beta}_0|}{\sigma/\sqrt{n}}$$
 and $z_1 = \frac{|\tilde{\beta}_1|}{\sigma/\sqrt{S}}$.





Approximate frequentist procedure

• Fit the simple linear regression

$$y_i - f_i = \beta_0 + \beta_1 (f_i - \overline{f}) + \epsilon_i$$

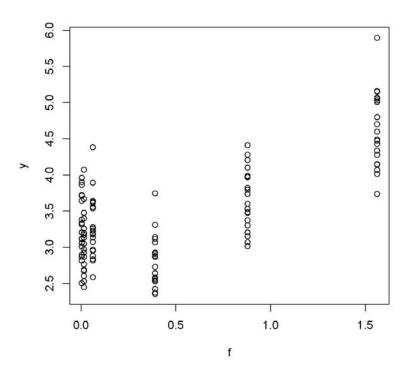
and force β_j to be 0 if $|z_j| < \sqrt{2}$.





Surface roughness example

• Engineering model: $f_i = x_i^2/6400$



There is a positive relation





Example-continued

• From replicates $\hat{\sigma}^2 = s^2 = .183$

$$MI = \frac{1}{120} \sum_{i=1}^{120} (y_i - f_i)^2 = 9.12.$$

 Engineering model is not good for prediction

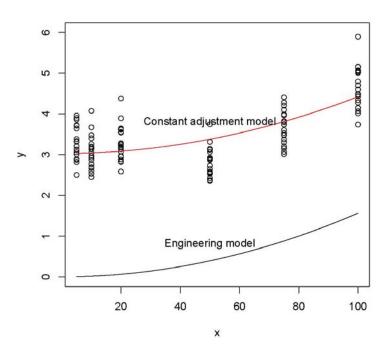
$$MI > \frac{r-1}{r}s^2 + \frac{\sigma^2}{n}\chi_{q,\alpha}^2.$$





Constant adjustment model

$$\hat{\mu}^C(x) - f(x) = 2.98 - .11(f(x) - .4857)$$



$$MI = \frac{1}{120} \sum_{i=1}^{120} (y_i - \hat{\mu}_i^C)^2 = .255$$





Functional adjustment model

$$Y - \mu^{C}(\boldsymbol{x}) = \delta(\boldsymbol{x}; \boldsymbol{\alpha}) + \epsilon$$
$$\delta(\boldsymbol{x}; \boldsymbol{\alpha}) = \alpha_{0} + \sum_{i=1}^{m} \alpha_{i} u_{i}(\boldsymbol{x})$$
$$\boldsymbol{\alpha} \sim \mathcal{N}(\boldsymbol{0}, \gamma^{2} \boldsymbol{R})$$





Two-stage estimation

• Use the estimate of $\mu^C(\boldsymbol{x})$ from the constant adjustment model

 $\hat{\mu}^{F}(\boldsymbol{x}) = \hat{\mu}^{C}(\boldsymbol{x}) + \sum_{i=0}^{m} \hat{\alpha}_{i} u_{i}(\boldsymbol{x})$ $\hat{\alpha} = (\boldsymbol{U}'\boldsymbol{U} + \frac{\sigma^{2}}{\gamma^{2}}\boldsymbol{R}^{-1})^{-1}\boldsymbol{U}'(\boldsymbol{y} - \hat{\boldsymbol{\mu}}^{C})$

$$l = -\frac{1}{2}\log\det(\gamma^2\boldsymbol{U}\boldsymbol{R}\boldsymbol{U}' + \sigma^2\boldsymbol{I}) - \frac{1}{2}(\boldsymbol{y} - \hat{\boldsymbol{\mu}}^C)'(\gamma^2\boldsymbol{U}\boldsymbol{R}\boldsymbol{U}' + \sigma^2\boldsymbol{I})(\boldsymbol{y} - \hat{\boldsymbol{\mu}}^C)$$





Approximate frequentist procedure

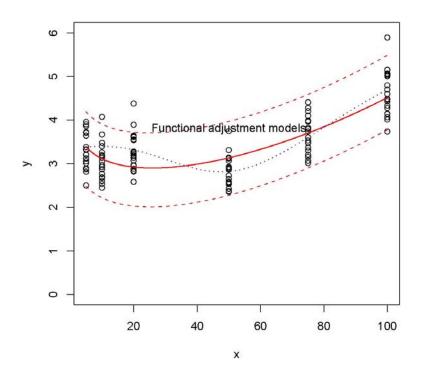
- Fit a multiple linear regression
- Do a variable selection





Surface roughness example

$$\hat{\mu}^F(x) - \hat{\mu}^C(x) = .015(x - 43.33) - .593(\log(1+x) - 3.35)$$



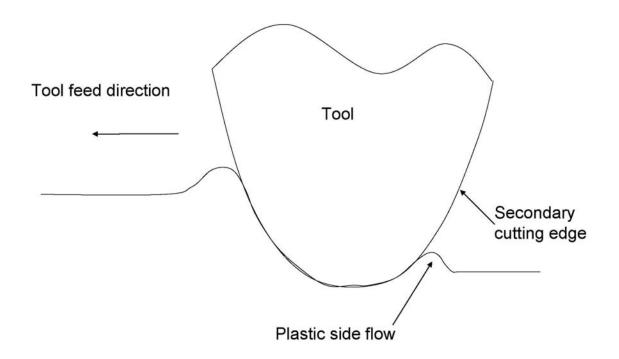
$$MI = \frac{1}{120} \sum_{i=1}^{120} (y_i - \hat{\mu}_i^F)^2 = .215.$$





Calibration parameters

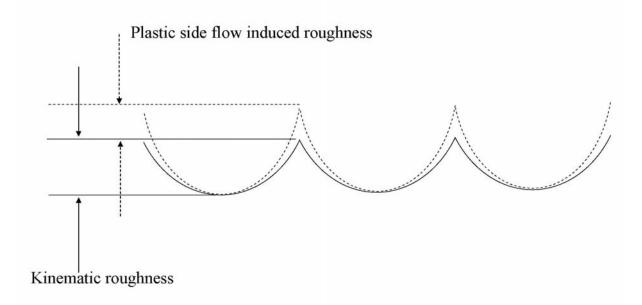
Liu and Melkote (2006)







New engineering model



$$f(x; \boldsymbol{\eta}) = Y_{kinematic} + Y_{plastic} = \frac{x^2}{8r} + \eta_0 + \eta_1 \log(R(x))$$

 R(x) is calculated using a combination of analytical formulas and finite element simulations





Statistical adjustments

First use least squares estimate

$$\tilde{\boldsymbol{\eta}} = \arg\min_{\boldsymbol{\eta} \in [\boldsymbol{\eta}_L, \boldsymbol{\eta}_U]} \sum_{i=1}^n [y_i - f_i(\boldsymbol{\eta})]^2$$

$$f(x; \widetilde{\eta}) = \frac{x^2}{8r} - 24.83 + 4.49 \log R(x)$$

MI=.209 (new engineering model is good)





Constant adjustment model

$$Y - f(\mathbf{x}; \boldsymbol{\eta}) = \beta_0 + \beta_1 (f(\mathbf{x}; \boldsymbol{\eta}) - f(\boldsymbol{\eta})) + \epsilon$$

$$A(\eta) = \frac{1}{\sigma^2} \sum_{i=1}^{n} [y_i - f_i(\eta)]^2 + \log(1 + (z_0^2(\eta) - 1)_+)$$

+ \log(1 + (z_1^2(\eta) - 1)_+) - (z_0^2(\eta) - 1)_+ - (z_1^2(\eta) - 1)_+

$$\hat{\beta}_0 = \left(1 - \frac{1}{z_0^2(\hat{\boldsymbol{\eta}})}\right)_+ \tilde{\beta}_0(\hat{\boldsymbol{\eta}}) \text{ and } \hat{\beta}_1 = \left(1 - \frac{1}{z_1^2(\hat{\boldsymbol{\eta}})}\right)_+ \tilde{\beta}_1(\hat{\boldsymbol{\eta}})$$





Approximate frequentist procedure

Fit a nonlinear regression

$$y_i = f_i(\boldsymbol{\eta}) - \beta_0 - \beta_1(f_i(\boldsymbol{\eta}) - \bar{f}(\boldsymbol{\eta})) + \epsilon_i$$

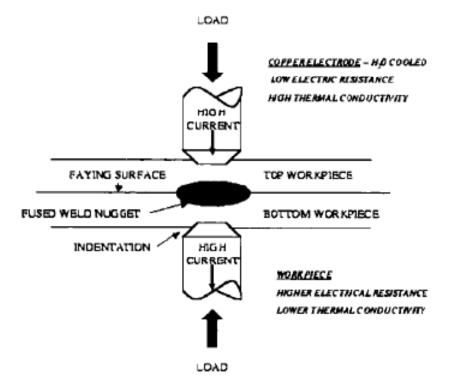
and force
$$\beta_j$$
 to be 0 if $|z_j| < \sqrt{2}$.





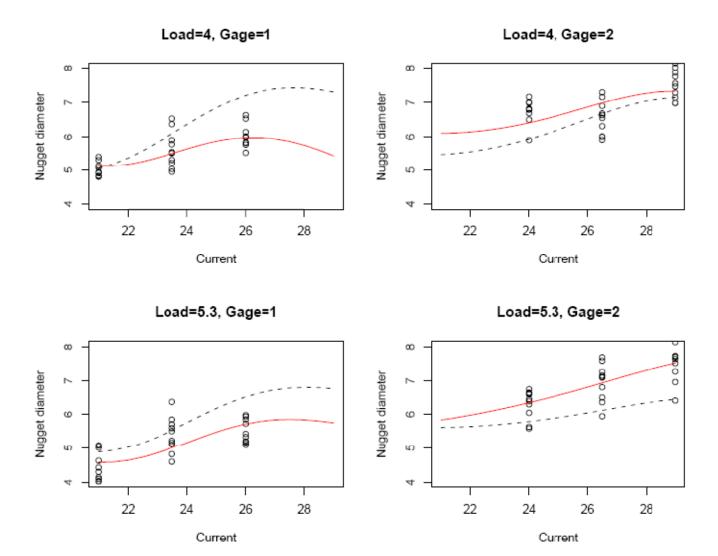
A Spot Welding Example

- Higdon et al. (2004) and Bayarri et al. (2007)
 - Three factors: Load, Current, and Gage
 - One calibration parameter





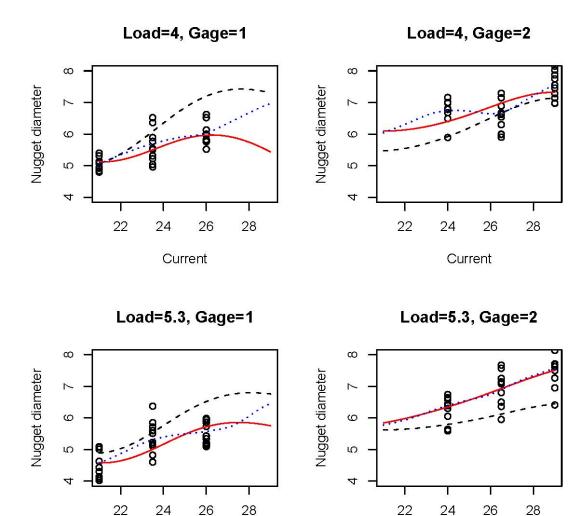




$$\hat{\mu}^F(\mathbf{x}) - \hat{\mu}^C(\mathbf{x}) = .12x_1 - .21(x_2 - .03) + .65x_3 + .44x_1x_2 + .40(x_2x_3 - .33)$$







Current

Eng. Model (Black-dashed): 0.69 Joseph&Melkote (Red-solid): 0.23 Bayarri et al. (Blue-dotted): 0.20

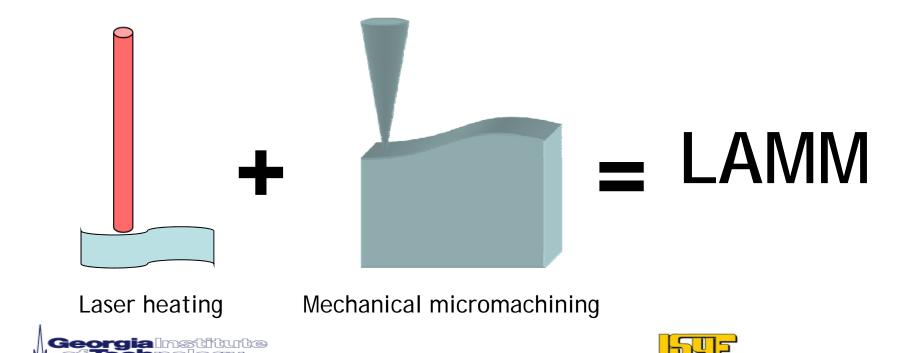
Current





Example: LAMM

Laser assisted mechanical micromachining (LAMM) integrates thermal softening with mechanical micro cutting



INDUSTRIAL & SYSTEMS ENGINEERING

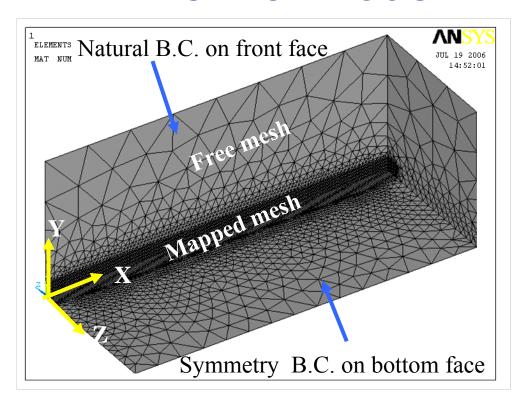
Objective

Find optimum processing conditions that minimize cutting/thrust forces and thermal damage.





Thermal Model

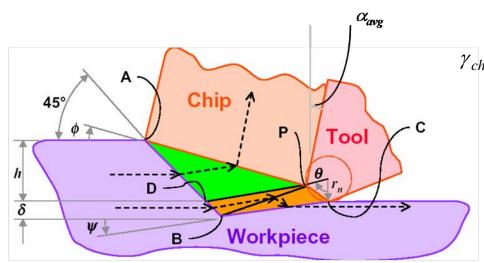


- Mapped dense mesh (25 μm x 12.5 μm x 20μm)
- An 8 noded 3-D thermal element (Solid70) is used
- Gaussian distribution of heat flux applied to a 5x5 element matrix which sweeps the mesh on the front face





Geometric Model



(Manjunathiah et. al, 2000)

$$\gamma_{chip} = 2V \frac{\gamma_{chip}}{\sqrt{2} \sin(\pi/4 + \theta_{PD}) \overline{PD}}$$

$$\gamma_{work} = 2V \frac{\gamma_{work}}{\sqrt{2} \sin(\pi/4 + \theta_{PD}) \overline{PD} + \frac{\sin(\psi + \theta/2)}{\sin\psi} \overline{PC}}$$



$$\gamma_{chip} = \frac{\sqrt{2} \sin \theta_{PD}}{\sin(\pi/4 + \theta_{PD})} + \frac{\cos(\alpha_{avg} + \theta_{PD})}{\cos(\alpha_{avg} - \phi) \sin(\phi + \theta_{PD})}$$

$$\gamma_{work} = \frac{\sqrt{2} \sin \theta_{PD}}{\sin(\pi/4 + \theta_{PD})} + \frac{\sin(\theta_{PD} + \theta/2)}{\sin(\theta_{PB} + \theta/2) \sin(\theta_{PB} + \theta_{PD})} + \frac{\sin(\theta/2)}{\sin(\psi + \theta/2)}$$

$$\gamma_{eff} = rac{v_{chip}\gamma_{chip} + v_{work}\gamma_{work}}{v_{chip} + v_{work}}$$

$$\gamma_{eff} = rac{v_{chip}\gamma_{chip} + v_{work}}{v_{chip} + v_{work}\gamma_{work}}$$

For plane strain conditions,

$$\varepsilon = \gamma_{eff} / \sqrt{3}$$

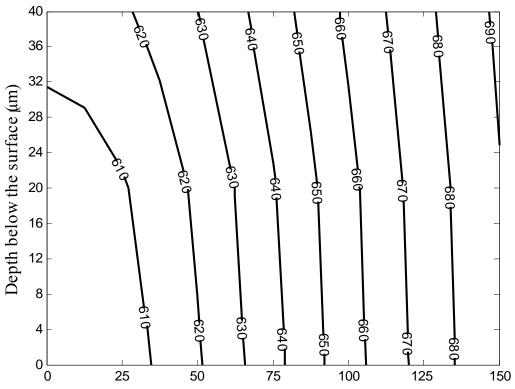
$$\varepsilon = \gamma_{eff} / \sqrt{3}$$



Shear Flow Strength

$$\sigma(\varepsilon, \dot{\varepsilon}, T, HRC) = \left(A + B\varepsilon^{n} + C \ln(\varepsilon + \varepsilon_{0}) + D \left(1 + E \ln\left(\frac{\dot{\varepsilon}}{\dot{\varepsilon}_{0}}\right)\right) \left(1 - \left(T^{*}\right)^{m}\right)$$
 Yan et al., 2007

 $S = \sigma / \sqrt{3}$



Distance from the center of the tool face along tool edge at 100 μ m from the center of the laser beam (μ m)

10W laser power, 10 mm/min speed 100 μm laser-tool distance and 110 μm spot size

Forces

Cutting and thrust forces,

$$F_{c} = \{(h-p)\cot\phi + h + r_{n}\sin\theta - (k-1)\delta\} \sum_{i=1}^{n} \overline{S}(i)w(i)$$

$$F_{t} = \{(h-p)\cot\phi - h + r_{n}\sin\theta + (k-1)\delta\cot\psi\} \sum_{i=1}^{n} \overline{S}(i)w(i)$$



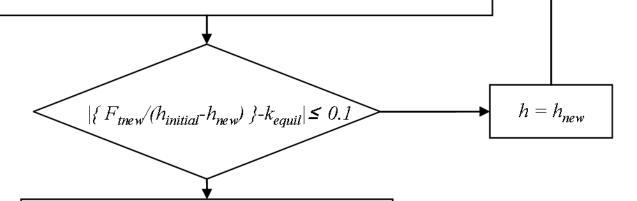


Equilibrium Forces/Deflection

- •Initialize $h=h_{initial}$
- •Calculate Force, $F_t(h)$ from force model
- •Determine k_{equil}

$$h_{new} = h - \varepsilon$$

•Calculate new thrust force $F_{\textit{tnew}}$ based on new depth of cut, $h_{\textit{new}}$

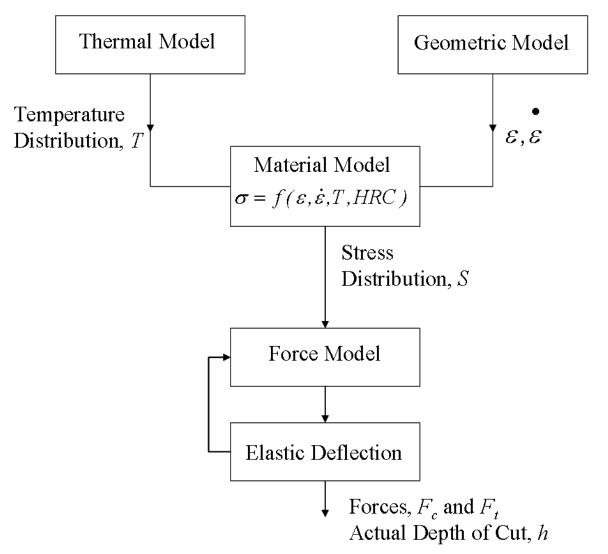


- •Calculate equilibrium depth of cut, h
- •Calculate the equilibrium force, F_c and F_t





Force model

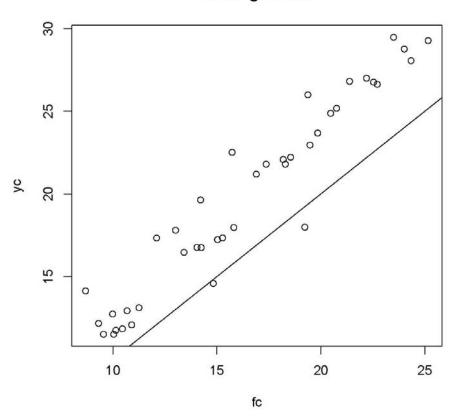






Force prediction



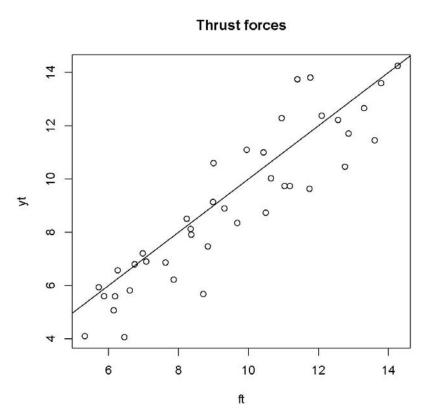


• Positive relation, but predictions are smaller than actual





Force prediction-continued

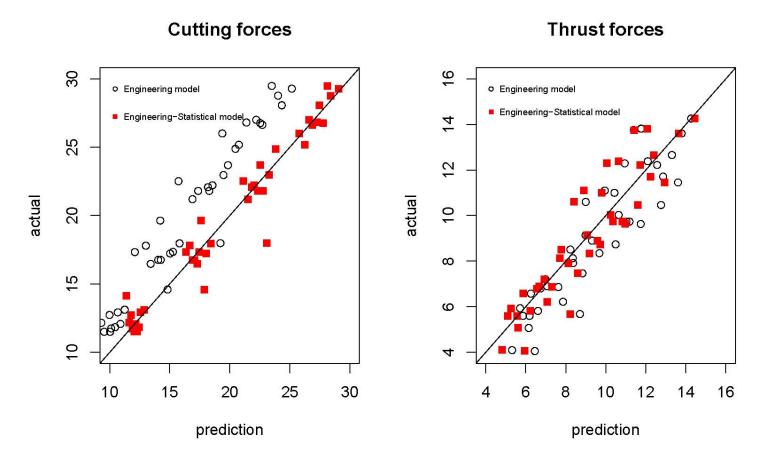


• Better than cutting force, but slightly smaller than actual





Engineering-Statistical Force Models



Plot of measured vs. predicted cutting and thrust forces





Optimization Problem

• For a given depth of cut (t), find the optimum levels of set depth of cut, laser power, laser speed, and distance from tool to minimize cutting/thrust forces while making sure there is no heat affected zone.

$$\min_{x_1, x_2, x_3, x_4} \hat{y}_c^2 + \hat{y}_t^2$$
subject to
$$doc = t$$

$$T_2 \le A_{c_1}$$





Nonlinear programming

$$\min \left\{ 1.54 x_1^{0.89} \exp(0.0014 x_2 - 0.009 x_3 e^{-0.0034 x_4}) \right\}^2 + \left\{ 1.03 x_1^{0.8} \exp(0.0014 x_2 - 0.043 x_3 e^{-0.0034 x_4}) \right\}^2$$

$$x_1 - 0.57x_1^{0.8} \exp(0.0014x_2 - 0.196x_3e^{-0.0034x_4}) = t$$

$$25 + 196.4x_3 \exp(-0.0021x_1x_3 - 0.00045x_2x_3) \le 800$$

$$10 \le x_1 \le 25$$
, $10 \le x_2 \le 50$, $0 \le x_3 \le 10$, $100 \le x_4 \le 200$





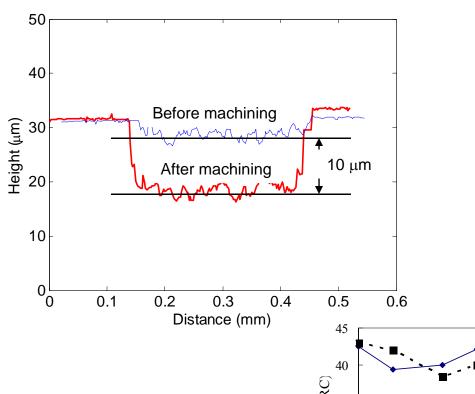
Optimization Results

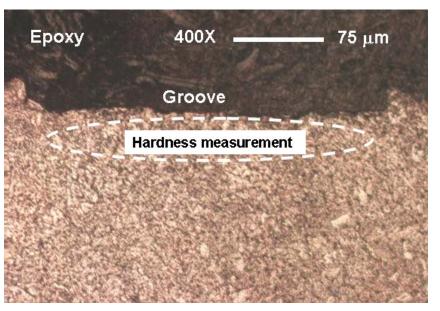
- For example, for depth of cut = 10 μ m
- Set depth of cut $(x_1) = 12.30 \mu m$
- Cutting speed $(x_2) = 10$ mm/min
- Laser power $(x_3) = 4.5 \text{ W}$
- Laser location from the tool edge $(x_4) = 100 \mu m$

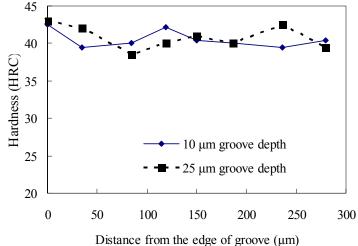




Validation









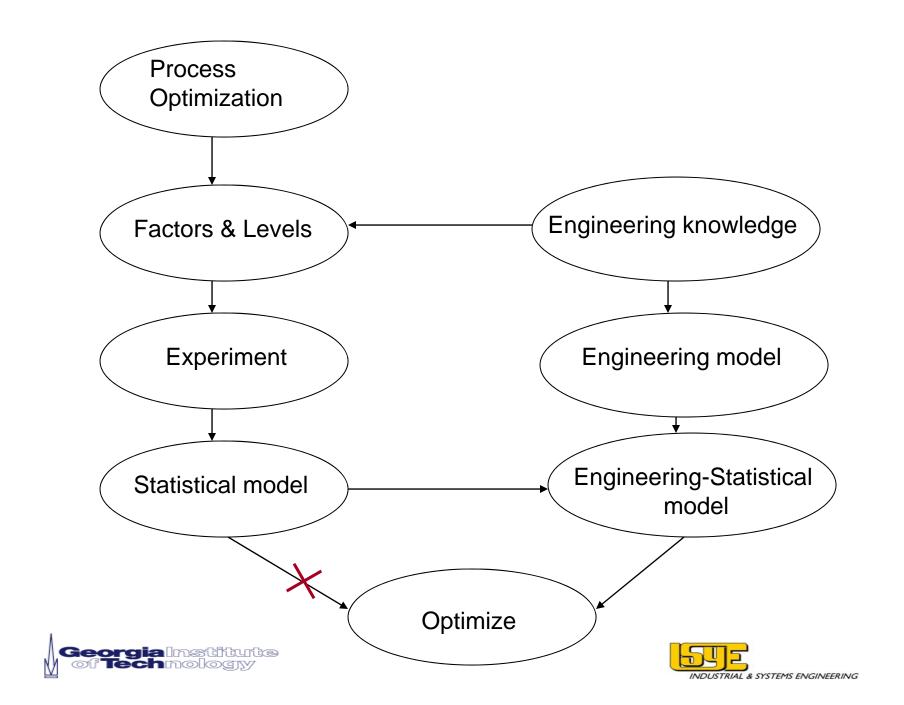


Conclusions

- Engineering models can be improved by using data
- Engineering-Statistical models perform better than engineering models and statistical models
- Need relatively less amount of data
- They use the physics of the process







Conclusions-continued

- Simple procedure
 - Fit two linear/nonlinear regressions
 - Do variable selection

- Easy-to-implement
 - No additional programming is required



